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Texas Instruments TFP401AMPZPEP

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TFP401A-EP

SLDS160A-MARCH 2009-REVISED JULY 2011

TI PanelBus™ DIGITAL RECEIVER

Check for Samples: TFP401A-EP

FEATURES

- Supports Pixel Rates Up to 165 MHz (including 1080p and WUXGA at 60Hz)
- **Digital Visual Interface (DVI) Specification** Compliant (1)
- True-Color, 24 Bit/Pixel, 16.7M Colors at One or Two Pixels Per Clock
- Laser Trimmed Internal Termination Resistors for Optimum Fixed Impedance Matching
- Skew Tolerant Up to One Pixel Clock Cycle
- 4x Over-Sampling
- **Reduced Power Consumption 1.8 V Core** Operation With 3.3 V I/Os and Supplies (2)
- **Reduced Ground Bounce Using Time-Staggered Pixel Outputs**
- Low Noise and Power Dissipation Using TI **PowerPAD[™] Packaging**
- Advanced Technology Using TI 0.18-mm **EPIC-5™ CMOS Process**
- **TFP401A Incorporates HSYNC Jitter** Immunity (3)
- (1) The Digital Visual Interface Specification, DVI, is an industry standard developed by the Digital Display Working Group (DDWG) for high-speed digital connection to digital displays. The TFP401A is compliant to the DVI Specification Rev. 1.0.
- (2) The TFP401A has an internal voltage regulator that provides the 1.8-V core power supply from the externally supplied 3.3-V supplies.
- The TFP401A incorporates additional circuitry to create a (3) stable HSYNC from DVI transmitters that introduce undesirable jitter on the transmitted HSYNC signal.

SUPPORTS DEFENSE, AEROSPACE, AND MEDICAL APPLICATIONS

- **Controlled Baseline**
- **One Assembly/Test Site**
- **One Fabrication Site**
- Available in Military (-55°C/125°C) Temperature Range (Custom temperature ranges available)
- **Extended Product Life Cycle**
- **Extended Product-Change Notification**
- **Product Traceability**

DESCRIPTION

The Texas Instruments TFP401A is a TI PanelBus ™ flat panel display product, part of a comprehensive family of end-to-end DVI 1.0 compliant solutions. Targeted primarily at desktop LCD monitors and digital projectors, the TFP401A finds applications in any design requiring high-speed digital interface. The TFP401A supports display resolutions up to 1080p and WUXGA in 24-bit true color pixel format. The TFP401A offers design flexibility to drive one or two pixels per clock, supports TFT or DSTN panels, and provides an option for time staggered pixel outputs for reduced ground bounce. PowerPAD[™] advanced packaging technology results in best of class power ground dissipation, footprint, and ultra-low inductance. The TFP401A combines PanelBus ™ circuit innovation with TI's advanced 0.18-mm EPIC-5™ CMOS process technology, along with TI PowerPAD™ package technology to achieve a reliable, low-powered, low-noise, high-speed digital interface solution.



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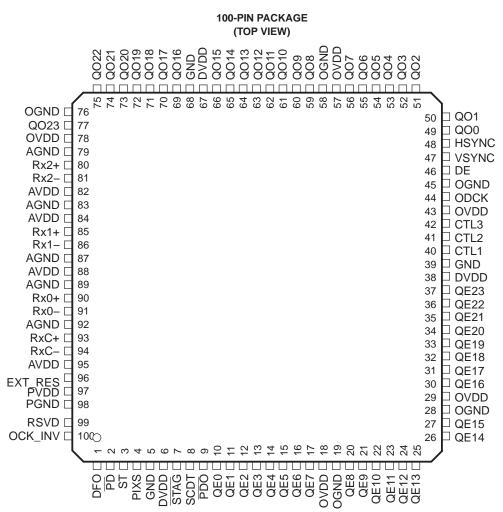
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SLDS160A - MARCH 2009 - REVISED JULY 2011

ORDERING INFORMATION ⁽¹⁾				
	PACKAGED DEVICE ⁽²⁾			
T _A	100-TQFP (PZP)			
–55°C to 125°C	TFP401AMPZPEP			

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI Web site at www.ti.com.

(2) Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.

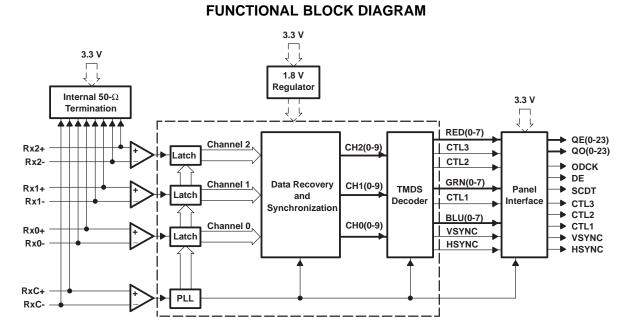




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SLDS160A-MARCH 2009-REVISED JULY 2011



TERMINAL FUNCTIONS

TERMINAL //O		1/0	DESCRIPTION
NAME	NO.	1/0	DESCRIPTION
AGND	79, 83, 87, 89, 92	GND	Analog Ground - Ground reference and current return for analog circuitry.
AV _{DD}	82, 84, 88, 95	V_{DD}	Analog VDD - Power supply for analog circuitry. Nominally 3.3 V
CTL[3:1]	42, 41, 40	DO	General-purpose control signals - Used for user defined control. CTL1 is not powered-down via PDO.
DE	46	DO	Output data enable - Used to indicate time of active video display versus non-active display or blank time. During blank, only HSYNC, VSYNC, and CTL1-3 are transmitted. During times of active display, or non-blank, only pixel data, QE[23:0] and QO[23:0], is transmitted. High : Active display time Low: Blank time
DFO	1	DI	Output clock data format - Controls the output clock (ODCK) format for either TFT or DSTN panel support. For TFT support ODCK clock runs continuously. For DSTN support ODCK only clocks when DE is high, otherwise ODCK is held low when DE is low. High : DSTN support/ODCK held low when DE = low Low: TFT support/ODCK runs continuously.
DGND	5, 39, 68	GND	Digital ground - Ground reference and current return for digital core
DV _{DD}	6, 38, 67	V_{DD}	Digital V _{DD} - Power supply for digital core. Nominally 3.3 V
EXT_RES	96	AI	Internal impedance matching - The TFP401A is internally optimized for impedance matching at 50 W. An external resistor tied to this pin has no effect on device performance.
HSYNC	48	DO	Horizontal sync output
RSVD	99	DI	Reserved. Must be tied high for normal operation.
OV _{DD}	18, 29, 43, 57, 78	V_{DD}	Output driver VDD - Power supply for output drivers. Nominally 3.3 V
ODCK	44	DO	Output data clock - Pixel clock. All pixel outputs QE[23:0] and QO[23:0] (if in 2-pixel/clock mode) along with DE, HSYNC, VSYNC and CTL[3:1] are synchronized to this clock.
OGND	19, 28 ,45, 58, 76	GND	Output driver ground - Ground reference and current return for digital output drivers
OCK_INV	100	DI	ODCK Polarity - Selects ODCK edge on which pixel data (QE[23:0] and QO[23:0]) and control signals (HSYNC, VSYNC, DE, CTL1-3) are latched. Normal Mode: High : Latches output data on rising ODCK edge Low : Latches output data on falling ODCK edge



SLDS160A - MARCH 2009 - REVISED JULY 2011

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TERMINA	FUNCTIONS	(continued)

TERMINAL		1/0					
NAME	NO.	- I/O	DESCRIPTION				
PD	2	DI	Power down - An active low signal that controls the TFP401A power-down state. During power down all output buffers are switched to a high impedance state. All analog circuits are powered down and all inputs are disabled, except for PD. If PD is left unconnected an internal pullup defaults the TFP401A to normal operation. High : Normal operation Low: Power down				
PDO	9	DI	Output drive power down - An active low signal that controls the power-down state of the output drivers. During output drive power down, the output drivers (except SCDT and CTL1) are driven to a high impedance state. When PDO is left unconnected, an internal pullup defaults the TFP401A to normal operation. High : Normal operation/output drivers on Low: Output drive power down.				
PGND	98	GND	PLL GND - Ground reference and current return for internal PLL				
PIXS	4	DI	Pixel select - Selects between one or two pixels per clock output modes. During the 2-pixel/clock mode, both even pixels, QE[23:0], and odd pixels, QO[23:0], are output in tandem on a given clock cycle. During 1-pixel/clock, even and odd pixels are output sequentially, one at a time, with the even pixel first, on the even pixel bus, QE[23:0]. (The first pixel per line is pixel-0, the even pixel. The second pixel per line is pixel-1, the odd pixel). High : 2-pixel/clock Low: 1-pixel/clock				
PV _{DD}	97	V _{DD}	PLL V _{DD} - Power supply for internal PLL				
QE[8:15]	20-27	DO	Even green pixel output - Output for even and odd green pixels when in 1-pixel/clock mode. Output for even only green pixel when in 2-pixel/clock mode. Output data is synchronized to the output data clock, ODCK. LSB: QE8/pin 20 MSB: QE15/pin 27				
QE[16:23]	30-37	DO	Even red pixel output - Output for even and odd red pixels when in 1-pixel/clock mode. Output for even only red pixel when in 2-pixel/clock mode. Output data is synchronized to the output data clock, ODCK. LSB: QE16/pin 30 MSB: QE23/pin 37				
QO[0:7]	49-56	DO	Odd blue pixel output - Output for odd only blue pixel when in 2-pixel/clock mode. Not used, and held low, when in 1-pixel/clock mode. Output data is synchronized to the output data clock, ODCK. LSB: QO0/pin 49 MSB: QO7/pin 56				
QO[8:15]	59-66	DO	Odd green pixel output - Output for odd only green pixel when in 2-pixel/clock mode. Not used, and held low, when in 1-pixel/clock mode. Output data is synchronized to the output data clock, ODCK. LSB: QO8/pin 59 MSB: QO15/pin 66				
QO[16:23]	69-75, 77	DO	Odd red pixel output - Output for odd only red pixel when in 2-pixel/clock mode. Not used, and held low, when in 1-pixel/clock mode. Output data is synchronized to the output data clock, ODCK. LSB: QO16/pin 69 MSB: QO23/pin 77				
QE[0:7]	10-17	DO	Even blue pixel output - Output for even and odd blue pixels when in 1-pixel/clock mode. Output for even only blue pixel when in 2-pixel per clock mode. Output data is synchronized to the output data clock, ODCK. LSB: QE0/pin 10 MSB: QE7/pin 17				
RxC+	93	AI	Clock positive receiver input - Positive side of reference clock. TMDS low voltage signal differential input pair.				
RxC-	94	AI	Clock negative receiver input - Negative side of reference clock. TMDS low voltage signal differential input pair.				
Rx0+	90	AI	Channel-0 positive receiver input - Positive side of channel-0. TMDS low voltage signal differential input pair. Channel-0 receives blue pixel data in active display and HSYNC, VSYNC control signals in blank.				



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TFP401A-EP

SLDS160A - MARCH 2009 - REVISED JULY 2011

TERMINAL		1/0			
NAME	NO.	I/O	DESCRIPTION		
Rx0-	91	AI	Channel-0 negative receiver input - Negative side of channel-0. TMDS low voltage signal differential input pair.		
Rx1+	85	AI	Channel-1 positive receiver input - Positive side of channel-1 TMDS low voltage signal differential input pair. Channel-1 receives green pixel data in active display and CTL1 control signals in blank.		
Rx1-	86	AI	Channel-1 negative receiver input - Negative side of channel-1 TMDS low voltage signal differential input pair.		
Rx2+	80	AI	Channel-2 positive receiver input - Positive side of channel-2 TMDS low voltage signal differential input pair. Channel-2 receives red pixel data in active display and CTL2, CTL3 control signals in blank.		
Rx2-	81	AI	Channel-2 negative receiver input - Negative side of channel-2 TMDS low voltage signal differential input pair.		
SCDT	8	DO	Sync detect - Output to signal when the link is active or inactive. The link is considered to be active when DE is actively switching. The TFP401A monitors the state DE to determine link activity. SCDT can be tied externally to PDO to power down the output drivers when the link is inactive. High: Active link Low: Inactive link		
ST	3	DI	Output drive strength select - Selects output drive strength for high or low current drive. (See dc specifications for IOH and IOL vs ST state). High : High drive strength Low : Low drive strength		
STAG	7	DI	Staggered pixel select - An active low signal used in the 2-pixel/clock pixel mode (PIXS = high). Time staggers the even and odd pixel outputs to reduce ground bounce. Normal operation outputs the odd and even pixels simultaneously. High : Normal simultaneous even/odd pixel output Low: Time staggered even/odd pixel output		
VSYNC	47	DO	Vertical sync output		

ABSOLUTE MAXIMUM RATINGS⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
DV_DD,AV_DD,OV_DD,PV_DD	Supply voltage range		-0.3	4	V
VI	Input voltage range, logic/analog signals		-0.3	4	V
	Operating ambient temperature range		-55	125	°C
T _{stg}	Storage temperature range ⁽²⁾		-65	150	°C
T _c	Case temperature for 10 seconds			260	°C
	Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds			260	°C
		Soldered ⁽³⁾		4.3	14/
	Package power dissipation/ PowerPAD™	Not soldered ⁽⁴⁾		2.7	W
	ESD protection, all pins			25	KV Human Body Model
	JEDEC latchup (EIA/JESD78)			100	mA

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) Long-term high-temperature storage and/or extended use at maximum recommended operating conditions may result in a reduction of overall device life. See http://www.ti.com/ep_quality for additional information on enhanced plastic packaging

(3) Specified with PowerPAD[™] bond pad on the backside of the package soldered to a 2 oz. Cu plate PCB thermal plane. Specified at maximum allowed operating temperature, 70°C.

(4) PowerPAD[™] bond pad on the backside of the package is not soldered to a thermal plane. Specified at maximum allowed operating temperature, 70°C.



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SLDS160A - MARCH 2009-REVISED JULY 2011

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RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V_{DD} (DV _{DD} , AV _{DD} , PV _{DD} , OV _{DD})	Supply voltage	3	3.3	3.6	V
t _{pix} ⁽¹⁾	Pixel time	6.06		40	ns
R _t	Single ended analog input termination resistance	45	50	57	Ω
T _A	Operating free-air temperature	-55		125	°C

(1) tpix is the pixel time defined as the period of the RxC clock input. The period of the output clock, ODCK is equal to tpix when in 1-pixel/clock mode and 2tpix when in 2-pixel/clock mode.

DC DIGITAL I/O ELECTRICAL CHARACTERISTICS

over operating free-air temperature range (unless otherwise noted)

	PARAMETER TEST CONDITIONS		NDITIONS	MIN	TYP	MAX	UNIT
V _{IH}	High level digital input voltage ⁽¹⁾			2		DV_DD	V
V _{IL}	Low level digital input voltage ⁽¹⁾			0		0.8	V
I _{OH}	High level output drive current ⁽²⁾	ST = High,	V _{OH} =2.4 V	5	10	16.3	~ ^
		ST = Low,	V _{OH} = 2.4 V	3	6	10.3	mA
I _{OL}	Low level output drive current ⁽²⁾	ST = High,	V _{OL} = 0.8 V	8	13	19	
		ST = Low,	V _{OL} = 0.8 V	4	7	11	mA
I _{OZ}	Hi-Z output leakage current	$\overline{PD} = Low \text{ or } \overline{PD}$	D = Low	-1		1	μA

(1) Digital inputs are labeled DI in I/O column of Terminal Functions Table.

(2) Digital outputs are labeled DO in I/O column of Terminal Functions Table.

DC ELECTRICAL CHARACTERISTICS

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP MAX	UNIT
V _{ID}	Analog input differential voltage ⁽¹⁾		75	1200	mV
V _{IC}	Analog input common mode voltage ⁽¹⁾		AV _{DD} -300	AV _{DD} -37	mV
V _{I(OC)}	Open circuit analog input voltage		AV _{DD} -10	AV _{DD} +10	mV
I _{DD(2PIX)}	Normal 2-pix/clock power supply current ⁽²⁾	ODCK = 82.5 MHz 2-pix/clock		370	mA
I _{PD}	Power down current ⁽³⁾	PD = Low		10	mA
I _{PDO}	Output drive power down current ⁽³⁾	PDO = Low		35	mA

(1) Specified as dc characteristic with no overshoot or undershoot.

(2) Alternating 2-pixel black/2-pixel white pattern. ST = high, STAG = high, QE[23:0] and QO[23:0] CL = 10 pF.

(3) Analog inputs are open circuit (transmitter is disconnected from TFP401A).



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SLDS160A - MARCH 2009 - REVISED JULY 2011

AC ELECTRICAL CHARACTERISTICS

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST C	ONDITIONS	MIN	TYP	MAX	UNIT	
V _{ID} (2)	Differential input sensitivity ⁽¹⁾			150		1560	mV _{p-p}	
t _{ps}	Analog input intra-pair (+ to -) differential skew ⁽²⁾					0.4	t _{bit} ⁽³⁾	
t _{ccs}	Analog Input inter-pair or channel-to-channel skew ⁽²⁾					1	$t_{pix}^{}$ ⁽⁴⁾	
t _{ijit}	Worse case differential input clock jitter tolerance ⁽⁵⁾ , ⁽²⁾			50			ps	
t _{f1}	Fall time of data and control signals ⁽⁷⁾ , ⁽⁸⁾	ST = Low, ST = High,	CL=5 pF CL=10 pF			2.4 1.9	ns	
t _{r1}	Rise time of data and control signals ⁽⁷⁾ , ⁽⁸⁾ ⁽⁶⁾	ST = Low, ST = High,	CL=5 pF CL=10 pF			2.4 1.9	ns	
t _{r2}	Rise time of ODCK clock ⁽⁷⁾ ⁽⁶⁾	ST = Low, ST = High,	CL=5 pF CL=10 pF			2.4 1.9	ns	
t _{f2}	Fall time of ODCK clock ⁽⁷⁾ ⁽⁶⁾	ST = Low, ST = High,	CL=5 pF CL=10 pF			2.4 1.9	ns	
t _{su1}	Setup time, data and control signal to falling edge of ODCK ⁽⁶⁾	1 pixel/clock, Pl OCK_INV = low	XS = low,	1.8				
		<u>2 pixe</u> l/clock, Pl STAG = high, O		3.8			ns	
		2 pixel and STA STAG = low, OC		0.6				
t _{h1}	Hold time, data and control signal to falling edge of ODCK ⁽⁶⁾	1 pixel/clock, Pl OCK_INV = low		0.6				
		<u>2 pixel</u> and STAG, PIXS = high, STAG = low, OCK_INV = low		2.5			ns	
		<u>2 pixe</u> l/clock, Pl STAG = high, O		2.9				
t _{su2}	Setup time, data and control signal to rising edge of ODCK ⁽⁶⁾	1 pixel/clock, PI OCK_INV = high		2.1				
		<u>2 pixe</u> l/clock, PI STAG = high, O	CK_INV = high	4			ns	
		2 pixel and STA STAG = low, OC		1.5				
t _{h2}	Hold time, data and control signal to rising edge of ODCK ⁽⁶⁾	1 pixel/clock, Pl OCK_INV = high	n	0.3				
		<u>2 pixel</u> and STA STAG = low, OC		2.4			ns	
		<u>2 pixe</u> l/clock, Pl STAG = high, O	XS = high, CK_INV = high	2.1				
f _{ODCK}	ODCK frequency	PIX = Low (1-PI	,	25		165	MHz	
		PIX = High (2-P	IX/CLK)	12.5		82.5		
t _{pd(PDL)}	ODCK duty-cycle Propagation delay time from PD low to Hi-Z outputs ⁽⁶⁾			45%	60%	75% 9	ns	

Specified as ac parameter to include sensitivity to overshoot, undershoot and reflection. (1)

- By characterization (2)
- (3)
- t_{bit} is 1/10 the pixel time, t_{pix} t_{pix} is the pixel time defined as the period of the RxC input clock. The period of ODCK is equal to t_{pix} in 1-pixel/clock mode or 2t_{pix} when in 2-pixel/clock mode. (4)
- Measured differentially at 50% crossing using ODCK output clock as trigger. (5)
- (6) Not Production Test
- (7) Rise and fall times measured as time between 20% and 80% of signal amplitude.
- Data and control signals are : QE[23:0], QO[23:0], DE, HSYNC, VSYNC and CTL[3:1] (8)

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SLDS160A - MARCH 2009-REVISED JULY 2011

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AC ELECTRICAL CHARACTERISTICS (continued)

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t _{pd(PDOL)}	Propagation delay time from PDO low to Hi-Z outputs ⁽⁶⁾				9	ns
$t_{t(HSC)}$	Transition time between DE transition to SCDT $\log^{(9)}$			~17-26		ms
$t_{t(FSC)}$	Transition time between DE transition to SCDT high ⁽⁹⁾			8		DE transitions
t _{d(st)}	Delay time, ODCK latching edge to QE[23:0] data output	STAG = Low PIXS = High		0.25		t _{pix} ⁽⁴⁾

(9) Link active or inactive is determined by amount of time detected between DE transitions. SCDT indicates link activity.

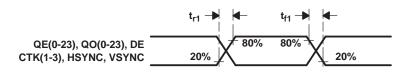


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SLDS160A-MARCH 2009-REVISED JULY 2011

PARAMETER MEASUREMENT INFORMATION





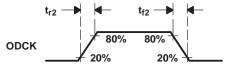


Figure 2. Rise and Fall Time of ODCK

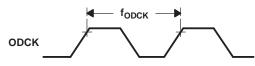
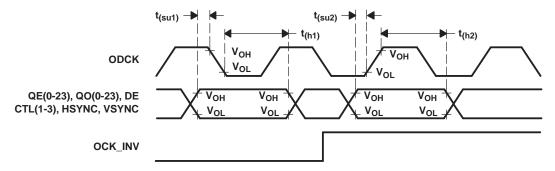
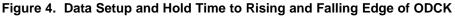
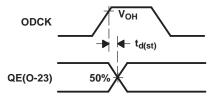


Figure 3. ODCK Frequency







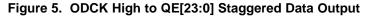
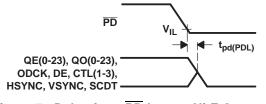


Figure 6. Analog Input Intra-Pair Differential Skew







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SLDS160A - MARCH 2009-REVISED JULY 2011

PARAMETER MEASUREMENT INFORMATION (continued)

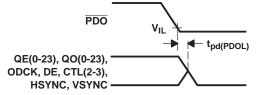
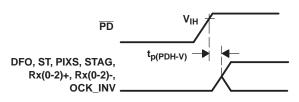
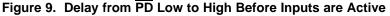


Figure 8. Delay from PDO Low to Hi-Z Outputs





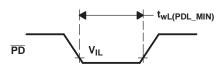


Figure 10. Minimum Time PD Low

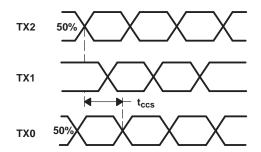
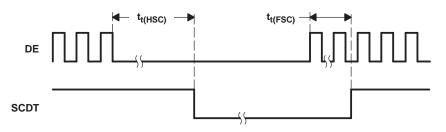
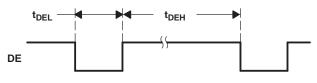


Figure 11. Analog Input Channel-to-Channel Skew











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TFP401A-EP

SLDS160A - MARCH 2009 - REVISED JULY 2011

FUNDAMENTAL OPERATION

The TFP401A is a digital visual interface (DVI) compliant TMDS digital receiver that is used in digital flat panel display systems to receive and decode TMDS encoded RGB pixel data streams. In a digital display system a host, usually a PC or workstation, contains a TMDS compatible transmitter that receives 24 bit pixel data along with appropriate control signals and encodes them into a high-speed low-voltage differential serial bit stream fit for transmission over a twisted-pair cable to a display device. The display device, usually a flat-panel monitor, will require a TMDS compatible receiver like the TI TFP401A to decode the serial bit stream back to the same 24 bit pixel data and control signals that originated at the host. This decoded data can then be applied directly to the flat panel drive circuitry to produce an image on the display. Since the host and display can be separated by distances up to 5 meters or more, serial transmission of the pixel data is preferred. To support modern display resolutions up to UXGA a high bandwidth receiver with good jitter and skew tolerance is required.

TMDS PIXEL DATA AND CONTROL SIGNAL ENCODING

TMDS stands for transition minimized differential signaling. Only one of two possible TMDS characters for a given pixel will be transmitted at a given time. The transmitter keeps a running count of the number of ones and zeros previously sent and transmits the character that will minimize the number of transitions and approximate a dc balance of the transmission line. Three TMDS channels are used to receive RGB pixel data during active display time, DE = high. The same three channels also receive control signals, HSYNC, VSYNC, and user defined control signals CTL[3:1]. These control signals are received during inactive display or blanking-time. Blanking-time is when DE = low. The following table maps the received input data to appropriate TMDS input channel in a DVI compliant system.

RECEIVED PIXEL DATA ACTIVE DISPLAY DE = HIGH	INPUT CHANNEL	OUTPUT PINS (VALID FOR DE = HIGH)
Red[7:0]	Channel - 2 (Rx2 +)	QE[23:16] QO[23:16]
Green[7:0]	Channel - 1 (Rx1 +)	QE[15:8] QO[15:8]
Blue[7:0]	Channel - 0 (Rx0 +)	QE[7:0] QO[7:0]
RECEIVED CONTROL DATA BLANKING DE = LOW	INPUT CHANNEL	UTPUT PINS (VALID FOR DE = LOW)
CTL[3:2]	Channel - 2 (Rx2 +)	CTL[3:2]
CTL[1: 0] ⁽¹⁾	Channel - 1 (Rx1 +)	CTL1
HSYNC, VSYNC	Channel - 0 (Rx0 +)	HSYNC, VSYNC

(1) Some TMDS transmitters transmit a CTL0 signal. The TFP401A decodes and transfers CTL[3:1] and ignores CTL0 characters. CTL0 is not available as a TFP401A output.

The TFP401A discriminates between valid pixel TMDS characters and control TMDS characters to determine the state of active display versus blanking, i.e., state of DE.



TFP401A-EP



SLDS160A - MARCH 2009 - REVISED JULY 2011

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TFP401A CLOCKING AND DATA SYNCHRONIZATION

The TFP401A receives a clock reference from the DVI transmitter that has a period equal to the pixel time, Tpix. The frequency of this clock is also referred to as the pixel rate. Since the TMDS encoded data on Rx[2:0] contains 10 bits per 8-bit pixel, it follows that the Rx[2:0] serial bit rate is 10 times the pixel rate. For example, the required pixel rate to support an UXGA resolution with 60-Hz refresh rate is 165 MHz. The TMDS serial bit rate is 10x the pixel rate or 1.65 Gb/s. Due to the transmission of this high-speed digital bit stream, on three separate channels (or twisted-pair wires) of long distances (3-5 meters), phase synchronization between the data steams and the input reference clock is not specified. In addition, skew between the three data channels is common. The TFP401A uses a 4x oversampling scheme of the input data streams to achieve reliable synchronization with up to 1-Tpix channel-to-channel skew tolerance. Accumulated jitter on the clock and data lines due to reflections and external noise sources is also typical of high speed serial data transmission, hence the TFP401A's design for high jitter tolerance.

The input clock to the TFP401A is conditioned by a phase-locked-loop (PLL) to remove high-frequency jitter from the clock. The PLL provides four 10x clock outputs of different phase to locate and sync the TMDS data streams (4x oversampling). During active display the pixel data is encoded to be transition minimized, whereas in blank, the control data is encoded to be transition maximized. A DVI compliant transmitter is required to transmit in blank for a minimum period of time, 128-Tpix, to specify sufficient time for data synchronization when the receiver sees a transition maximized code. Synchronization during blank, when the data is transition maximized, specifies reliable data bit boundary detection. Phase synchronization to the data streams is unique for each of the three input channels and is maintained as long as the link remains active.

TFP401A TMDS INPUT LEVELS AND INPUT IMPEDANCE MATCHING

The TMDS inputs to the TFP401A receiver have a fixed single-ended termination to AVDD The TFP401A is internally optimized using a laser trim process to precisely fix the impedance at 50 W. The device functions normally with or without a resistor on the EXT_RES pin, so it remains drop-in compatible with current sockets. The fixed impedance eliminates the need for an external resistor while providing optimum impedance matching to standard 50-W DVI cables.

Figure 14 shows a conceptual schematic of a DVI transmitter and TFP401A receiver connection. A transmitter drives the twisted pair cable via a current source, usually achieved with an open-drain type output driver. The internal resistor, which is matched to the cable impedance, at the TFP401A input provides a pullup to AVDD. Naturally, when the transmitter is disconnected and the TFP401A DVI inputs are left unconnected, the TFP401A receiver inputs pullup to AVDD. The single ended differential signal and full differential signal is shown in Figure 15. The TFP401A is designed to respond to differential signal swings ranging from 150 mV to 1.56 V with common mode voltages ranging from (AVDD-300 mV) to (AVDD-37 mV).



Instruments

TFP401A-EP

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SLDS160A-MARCH 2009-REVISED JULY 2011

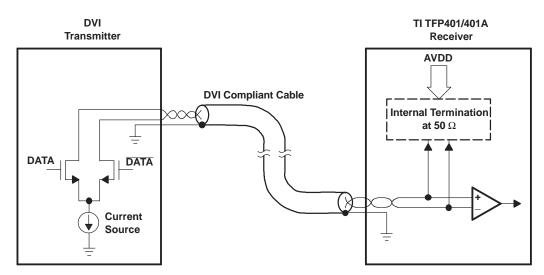


Figure 14. TMDS Differential Input and Transmitter Connection

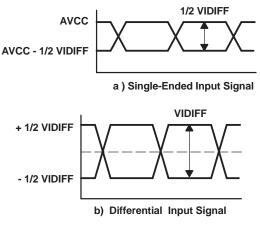


Figure 15. TMDS Inputs

TFP401A INCORPORATES HSYNC JITTER IMMUNITY

Several DVI transmitters available in the market introduce jitter on the transmitted HSYNC and VSYNC signals during the TMDS encryption process. The HSYNC signal can shift by one pixel position (one clock) from nominal in either direction, resulting in up to two cycles of HSYNC shift. This jitter carries through to the DVI receiver, and if the position of HSYNC shifts continuously, the receiver can lose track of the input timing and pixel noise will occur on the display. For this reason, a DVI compliant receiver with HSYNC jitter immunity should be used in all displays that could be connected to host PCs with transmitters that have this HSYNC jitter problem.

The TFP401A integrates HSYNC regeneration circuitry that provides a seamless interface to these noncompliant transmitters. The position of the data enable (DE) signal is always fixed in relation to data, irrespective of the location of HSYNC. The TFP401A receiver uses the DE and clock signals recreate stable vertical and horizontal sync signals. The circuit filters the HSYNC output of the receiver, and HSYNC is shifted to the nearest eighth bit boundary, producing a stable output with respect to data, as shown in Figure 16. This will ensure accurate data synchronization at the input of the display timing controller.



TFP401A-EP



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SLDS160A - MARCH 2009-REVISED JULY 2011

This HSYNC regeneration circuit is transparent to the monitor and need not be removed even if the transmitted HSYNC is stable. For example, the *PanelBus* [™] line of DVI 1.0 compliant transmitters, such as the TFP6422 and TFP420, do not have the HSYNC jitter problem. The TFP401A will operate correctly with either compliant or noncompliant transmitters. In contrast, the TFP401 is ideal for customers who have control over the transmit portion of the design such as bundled system manufacturers and for internal monitor use (the DVI connection between monitor and panel modules).

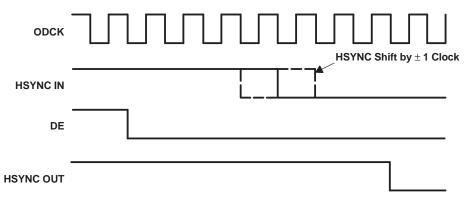


Figure 16. HSYNC Regeneration Timing Diagram

TFP401A MODES OF OPERATION

The TFP401A provides systems design flexibility and value by providing the system designer with configurable options or modes of operation to support varying system architectures. The following table outlines the various panel modes that can be supported along with appropriate external control pin settings.

PANEL	PANEL PIXEL RATE		ODCK	DFO	PIXS	OCK_INV	
TFT or 16-bit DSTN	1 pix/clock	Falling	Free run	0	0	0	
TFT or 16-bit DSTN	1 pix/clock	Rising	Free run	0	0	1	
TFT	2 pix/clock	Falling	Free run	0	1	0	
TFT	2 pix/clock	Rising	Free run	0	1	1	
24-bit DSTN	1 pix/clock	Falling	Gated low	1	0	0	
NONE	1 pix/clock	Rising	Gated low	1	0	1	
24-bit DSTN	2 pix/clock	Falling	Gated low	1	1	0	
24-bit DSTN	2 pix/clock	Rising	Gated low	1	1	1	

TFP401A OUTPUT DRIVER CONFIGURATIONS

The TFP401A provides flexibility by offering various output driver features that can be used to optimize power consumption, ground-bounce and power-supply noise. The following sections outline the output driver features and their effects.

Output driver power down ($\overline{\text{PDO}}$ = low), Pulling $\overline{\text{PDO}}$ low will place all the output drivers, except CTL1 and SCDT, into a high-impedance state. The SCDT output which indicates link-disabled or link-inactive can be tied directly to the PDO input to disable the output drivers when the link is inactive or when the cable is disconnected. An internal pullup on the PDO pin will default the TFP401A to the normal nonpower down output drive mode if left unconnected.

Drive Strength (ST = high for high drive strength, ST=low for low drive strength.) The TFP401A allows for selectable output drive strength on the data, control and ODCK outputs. See the dc specifications table for the values of IOH and IOL current drives for a given ST state. The high output strength offers approximately two times the drive as the low output drive strength.



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TFP401A-EP

SLDS160A - MARCH 2009 - REVISED JULY 2011

Time Staggered Pixel Output. This option works only in conjunction with the 2-pixel/clock mode (PIXS = high). Setting STAG = low will time stagger the even and odd pixel output so as to reduce the amount of instantaneous current surge from the power supply. Depending on the PCB layout and design this can help reduce the amount of system ground bounce and power supply noise. The time stagger is such that in 2-pixel/clock mode the even pixel is delayed from the latching edge of ODCK by 0.25 Tcip. (Tcip is the period of ODCK. The ODCK period is 2Tpix when in 2-pixel/clock mode.)

Depending on system constraints of output load, pixel rate, panel input architecture and board cost the TFP401A drive strength and staggered pixel options allow flexibility to reduce system power-supply noise, ground bounce and EMI.

Power Management. The TFP401A offers several system power management features.

The output driver power down (\overline{PDO} = low) is an intermediate mode which offers several uses. During this mode, all output drivers except SCDT and CTL1 are driven to a high-impedance state while the rest of the device circuitry remains active

The TFP401A power down (PD = low) is a complete power down in that it powers down the digital core, the analog <u>circuitry</u>, and output drivers. All output drivers are placed into a Hi-Z state. <u>All</u> inputs are disabled except for the PD input. The TFP401A will not respond to any digital or analog inputs until PD is pulled high.

Both PDO and PD have internal pullups, so if left unconnected they default the TFP401A to normal operating modes.

Sync Detect. The TFP401A offers an output, SCDT, to indicate link activity. The TFP401A monitors activity on DE to determine if the link is active. When 2^18 clocks produced by an on-chip free running oscillator whose frequency is around 10-15 MHz pass without a transition on DE, the TFP401A considers the link inactive and SCDT is driven low. Hence SCDT goes low after the terminal count of the counter is reached that is 17~26 ms. When SCDT is low, if 8 DE edges are detected within the terminal count of 2^18 clocks, the link is considered active and SCDT goes high.

SCDT can be used to signal a system power management circuit to initiate <u>a system</u> power down when the link is considered inactive. The SCDT can also be tied directly to the TFP401A PDO input to power down the output drivers when the link is inactive. It is not recommended to use the SCDT to drive the PD input since, once in complete power-down, the analog inputs are ignored and the SCDT state does not change. An external system power management circuit to drive PD is preferred.

SYNC DETECT OPERATION

Some graphics card when in sleep/standby mode send characters that can make the DE toggle and make SCDT high, hence in such applications, to robustly determine if the link is in active or inactive mode, it is recommended that a sync signal like HSYNC can be used in addition to the SCDT. Timing format on the recovered HSYNC signal can be used in addition to SCDT to determine if the link is receiving a valid video format.

In applications where PD is being pulsed (to save power while in sleep/standby mode) when the link is inactive, and SCDT is used solely to determine the link activity, then in such cases SCDT should not be used until 25 ms of signal and power application.

There is a rare possibility that SCDT can get stuck high on power up or removal of the DVI signal. For example: If the power on a DVI distribution box sourcing the signal to the receiver is cycled rapidly (2-3 times/second), then there is a small possibility, (1 in ~40-50 times) of cycling power that SCDT may be stuck high when the box is powered off.

TI POWERPAD™ 100-TQFP PACKAGE

The TFP401A is packaged in TI's thermally enhanced PowerPAD[™] 100TQFP packaging. The PowerPAD[™] package is a 14 mm y 14 mm y 1 mm TQFP outline with 0.5-mm lead-pitch. The PowerPAD[™] package has a specially designed die mount pad that offers improved thermal capability over typical TQFP packages of the same outline. The TI 100-TQFP PowerPAD[™] package offers a back-side solder plane that connects directly to the die mount pad for enhanced thermal conduction. Soldering the back side of the TFP401A to the application board is not required thermally as the device power dissipation is well within the package capability when not soldered. If traces or vias are located under the back side pad, they should be protected by suitable solder mask or other assembly technique to prevent inadvertent shorting to the exposed back side pad.



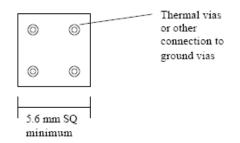


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SLDS160A - MARCH 2009-REVISED JULY 2011

Soldering the back side pad of the device to a thermal land connected to the PCB ground plane is recommended for electrical and EMI considerations. The thermal land may be soldered to the exposed PowerPAD[™] using standard reflow soldering techniques.

The recommended pad size for the grounded thermal land is 5.6mm sq. minimum, centered in the device land pattern. When vias are required to ground the land, multiple vias are recommended for a low impedance connection to the ground plane. Vias in the exposed pad should be small enough or filled to prevent wicking the solder away from the interface between the package body and the thermal land on the surface of the board during solder reflow.



More information on this package and other requirements for using thermal lands and thermal vias are detailed in the TI application report PowerPAD[™] *Thermally Enhanced Package Application Report*, TI literature number SLMA002, available via the TI Web pages beginning at www.ti.com.

Table 1 outlines the thermal properties of the TI 100-TQFP PowerPAD[™] package. The 100-TQFP non-PowerPAD[™] package is included only for reference.

PARAMETER ^{(1) (2)}	WITHOUT PowerPAD™	PowerPAD™ NOT CONNECTED TO PCB THERMAL PLANE	PowerPAD™ CONNECTED TO PCB THERMAL PLANE ⁽¹⁾
Theta-JA	45°C/W	27.3°C/W	17.3°C/W
Theta-JC	3.11°C/W	0.12°C/W	0.12°C/W
Maximum power dissipation ⁽³⁾	1.6 W	2.7 W	4.3 W

(1) Specified with 2-oz. Cu PCB plating.

(2) Airflow is at 0 LFM (no airflow)

(3) Measured at ambient temperature, $T_A = 70^{\circ}C$.



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TFP401A-EP

SLDS160A - MARCH 2009 - REVISED JULY 2011

REVISTION HISTORY

Changes	from	Original	(March	2009)	to	Revision	Δ
onunges		Original	(mai ci i	2005		1101131011	

•	Changed 1st bullet in FEATURES: FROM: Supports UXGA Resolution (Output Pixel Rate Up to 165MHz) TO: Supports Pixel Rates Up to 165 MHz (including 1080p and WUXGA at 60Hz)	1
		1
•	Changed sentence in first paragraph of description FROM: supports display resolutions up to UXGA in 24-bit true	
	color pixelTO: supports display resolutions up to 1080p and WUXGA in 24-bit true color pixel	1

Changed SXGA to UXGA in paragraph, last sentence under FUNDAMENTAL OPERATION section 11



31-May-2014

PACKAGING INFORMATION

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Orderable Device	Status	Package Type	•	Pins	•	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
TFP401AMPZPEP	ACTIVE	HTQFP	PZP	100	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-55 to 125	TFP401AMPZPEP	Samples
V62/09627-01XE	ACTIVE	HTQFP	PZP	100	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-55 to 125	TFP401AMPZPEP	Samples

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs. LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design. PREVIEW: Device has been announced but is not in production. Samples may or may not be available. OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined. Pb-Free/Green conversion plan has not been defined. Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above. Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight

in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width

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Addendum-Page 1



31-May-2014

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF TFP401A-EP :

Catalog: TFP401A

Automotive: TFP401A-Q1

NOTE: Qualified Version Definitions:

- Catalog TI's standard catalog product
- Automotive Q100 devices qualified for high-reliability automotive applications targeting zero defects

Addendum-Page 2



PZP (S-PQFP-G100)

MECHANICAL DATA

PowerPAD[™] PLASTIC QUAD FLATPACK

0,27 0,17 ⊕ 0,08 ∭ 0,50 51 75 AAAA AAAA 76 **—** 50 THERMAL PAD SIZE AND SHAPE SHOWN ON SEPARATE SHEET Н 100 26 \bigcirc 0.13 NOM ΗH НH 2512,00 TYP Gage Plane ↓ 14,20 SQ 13,80 0,25 16,20 SQ 0,15 15,80 0°-7° 0,05 1,05 0,75 0,95 0.45 Seating Plane -1,20 MAX □ 0,08 4146929/C 09/11

NOTES:

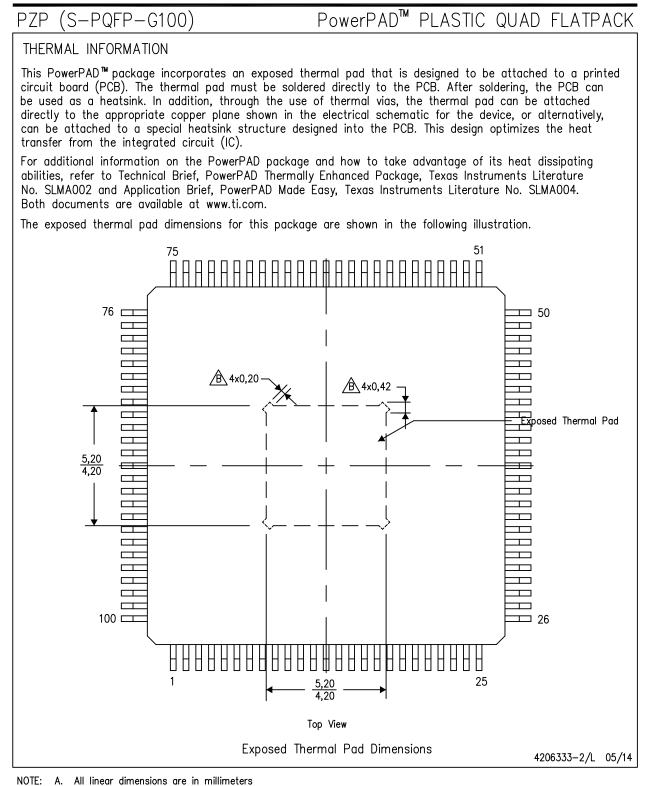
- A. All linear dimensions are in millimeters.B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <http://www.ti.com>.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
- F. Falls within JEDEC MS-026

PowerPAD is a trademark of Texas Instruments.





THERMAL PAD MECHANICAL DATA



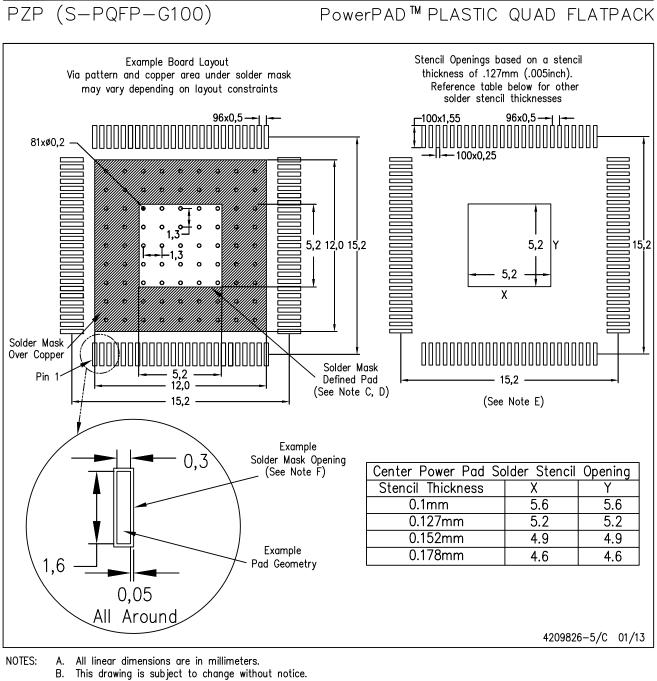
NOTE: A. All linear dimensions are in minimetric Δ .

Tie strap features may not be present. PowerPAD is a trademark of Texas Instruments





LAND PATTERN DATA



- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com http://www.ti.com. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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Logic	logic.ti.com	Security	www.ti.com/security
Power Mgmt	power.ti.com	Space, Avionics and Defense	www.ti.com/space-avionics-defense
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