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### STATIC ELECTRICAL CHARACTERISTICS

**Table 3. Static Electrical Characteristics**

Characteristics noted under conditions of  $7.0\text{ V} \leq V_{\text{BAT}} \leq 16\text{ V}$ ,  $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ , SLEEP = 5.0 V unless otherwise noted. Typical values reflect the parameter's approximate midpoint average value with  $V_{\text{BAT}} = 13\text{ V}$ ,  $T_A = 25^\circ\text{C}$ . All positive currents are into the pin. All negative currents are out of the pin.

| Characteristic  | Symbol                   | Min | Typ  | Max  | Unit          |
|---|--------------------------|-----|------|------|---------------|
| <b>POWER CONSUMPTION</b>  |                          |     |      |      |               |
| Operational Battery Current (RMS with Tx = 7.812 kHz Square Wave) |                          |     |      |      | mA            |
| BUS Load = 1380 $\Omega$ to GND, 3.6 nF to GND                    | $I_{\text{BAT(OP1)}}$    | -   | 3.0  | 11.5 |               |
| BUS Load = 257 $\Omega$ to GND, 20.2 nF to GND                    | $I_{\text{BAT(OP2)}}$    | -   | 22.4 | 32   |               |
| Battery Bus Low Input Current                                     |                          |     |      |      | mA            |
| After SLEEP Toggle Low to High; Prior to Tx Toggling              | $I_{\text{BAT(BUS L1)}}$ | -   | 1.1  | 3.0  |               |
| After Tx Toggle High to Low                                       | $I_{\text{BAT(BUS L2)}}$ | -   | 6.4  | 8.5  |               |
| Sleep State Battery Current                                       | $I_{\text{BAT(SLEEP)}}$  |     |      |      | $\mu\text{A}$ |
| $V_{\text{SLEEP}} = 0\text{ V}$                                   |                          | -   | 38.2 | 65   |               |

#### BUS

|  |                                 |                        |      |                  |                  |
|--|---------------------------------|------------------------|------|------------------|------------------|
| BUS Input Receiver Threshold <sup>(6)</sup>  |                                 |                        |      |                  | V                |
| Threshold High (Bus Increasing until Rx $\geq 3.0\text{ V}$ )  | $V_{\text{BUS(IH)}}$            | 4.25                   | 3.9  | -                |                  |
| Threshold Low (Bus Decreasing until Rx $\leq 3.0\text{ V}$ )   | $V_{\text{BUS(IL)}}$            | -                      | 3.7  | 3.5              |                  |
| Threshold in Sleep State (SLEEP = 0 V)   | $\text{BUS}_{\text{TH(SLEEP)}}$ | 2.4                    | 3.0  | 3.4              |                  |
| Hysteresis ( $V_{\text{BUS(IH)}} - V_{\text{BUS(IL)}}$ , SLEEP = 0 V)  | $V_{\text{BUS(HYST)}}$          | 0.1                    | 0.2  | 0.6              |                  |
| BUS-Out Voltage (257 $\Omega \leq R_{\text{BUS(L)}} \leq 1380\ \Omega$ )                                       |                                 |                        |      |                  | V                |
| $8.2\text{ V} \leq V_{\text{BAT}} \leq 16\text{ V}$ , Tx = 5.0 V   | $V_{\text{BUS(OUT1)}}$          | 6.25                   | 6.9  | 8.0              |                  |
| $4.25\text{ V} \leq V_{\text{BAT}} \leq 8.2\text{ V}$ , Tx = 5.0 V   | $V_{\text{BUS(OUT2)}}$          | $V_{\text{BAT}} - 1.6$ | -    | $V_{\text{BAT}}$ |                  |
| Tx = 0 V   | $V_{\text{BUS(OUT3)}}$          | -                      | 0.27 | 0.7              |                  |
| BUS Short Circuit Output Current   | $I_{\text{BUS(SHORT)}}$         |                        |      |                  | mA               |
| Tx = 5.0 V, $-2.0\text{ V} \leq V_{\text{BUS}} \leq 4.8\text{ V}$  |                                 | 60                     | 129  | 170              |                  |
| BUS Leakage Current  |                                 |                        |      |                  | $\mu\text{A}$    |
| $-2.0\text{ V} \leq V_{\text{BUS}} \leq 0\text{ V}$  | $I_{\text{BUS(LEAK1)}}$         | -500                   | -55  | -                |                  |
| $0\text{ V} \leq V_{\text{BUS}} \leq V_{\text{BAT}}$   | $I_{\text{BUS(LEAK2)}}$         | -                      | 189  | 500              |                  |
| BUS Thermal Shutdown <sup>(7)</sup> (Tx = 5.0 V, $I_{\text{BUS}} = -0.1\text{ mA}$ )                           | $T_{\text{BUS(LIM)}}$           |                        |      |                  | $^\circ\text{C}$ |
| Increase Temperature until $V_{\text{BUS}} \leq 2.5\text{ V}$  |                                 | 150                    | 170  | 190              |                  |
| BUS Thermal Shutdown Hysteresis <sup>(8)</sup>   | $T_{\text{BUS(LIMHYS)}}$        |                        |      |                  | $^\circ\text{C}$ |
| $T_{\text{BUS(LIM)}} - T_{\text{BUS(REEN)}}$   |                                 | 10                     | 12   | 15               |                  |
| BUS and LOAD Current with Loss of $V_{\text{BAT}}$ or GND ( $I_{\text{BAT}} = 0\ \mu\text{A}$ ) (see Figure 4) |                                 |                        |      |                  | mA               |
| $-18\text{ V} \leq V_{\text{BUS}} \leq 9.0\text{ V}$   | $I_{\text{BUS(LOSS)}}$          | -                      | 0.00 | 0.1              |                  |
| $-18\text{ V} \leq V_{\text{LOAD}} \leq 9.0\text{ V}$  | $I_{\text{LOAD(LOSS)}}$         | -                      | 0.00 | 0.1              |                  |

#### Notes

- Typical threshold value is the approximate actual occurring switch point value with  $V_{\text{BAT}} = 13\text{ V}$ ,  $T_A = 25^\circ\text{C}$ .
- Device characterized but not production tested for thermal shutdown.
- Device characterized but not production tested for thermal shutdown hysteresis.

TRICAL CHARACTERISTICS  
 STATIC ELECTRICAL CHARACTERISTICS

**Table 3. Static Electrical Characteristics (continued)**

Characteristics noted under conditions of  $7.0\text{ V} \leq V_{\text{BAT}} \leq 16\text{ V}$ ,  $-40^{\circ}\text{C} \leq T_{\text{A}} \leq 125^{\circ}\text{C}$ , SLEEP = 5.0 V unless otherwise noted. Typical values reflect the parameter's approximate midpoint average value with  $V_{\text{BAT}} = 13\text{ V}$ ,  $T_{\text{A}} = 25^{\circ}\text{C}$ . All positive currents are into the pin. All negative currents are out of the pin.

| Characteristic  | Symbol   | Min          | Typ           | Max        | Unit          |
|---|--|--------------|---------------|------------|---------------|
| <b>BUS (CONTINUED)</b>  |  |              |               |            |               |
| LOAD Output<br>$I_{\text{L}} = 6.0\text{ mA}$   | $L_{\text{ON}}$                                      | –            | 0.07          | 0.2        | V             |
| Unpowered LOAD Output<br>$V_{\text{BAT}} = 0\text{ V}$ , $I_{\text{L}} = 6.0\text{ mA}$                                   | $L_{\text{DIO}}$                                     | 0.3          | 0.56          | 0.9        | V             |
| <b>TX</b>   |  |              |               |            |               |
| Tx Input Voltage<br>Tx Input Logic Low Level<br>Tx Input Logic High Level   | $V_{\text{TX(IL)}}$<br>$V_{\text{TX(IH)}}$           | –<br>3.5     | –<br>–        | 0.8<br>–   | V             |
| Tx Input Current<br>$V_{\text{TX}} = 5.0\text{ V}$<br>$V_{\text{TX}} = 0\text{ V}$  | $I_{\text{TX(IH)}}$<br>$I_{\text{TX(IL)}}$           | 50<br>-2.0   | 106<br>0.23   | 200<br>2.0 | $\mu\text{A}$ |
| <b>LOOP</b>   |  |              |               |            |               |
| 4X/LOOP Input Current<br>$V_{\text{4X/LOOP}} = 0\text{ V}$ (Normal Mode)<br>$V_{\text{4X/LOOP}} = 5.0\text{ V}$ (4X Mode) | $I_{\text{4X/LOOP(IL)}}$<br>$I_{\text{4X/LOOP(IH)}}$ | -200<br>-200 | -60<br>110    | 200<br>200 | $\mu\text{A}$ |
| 4X/LOOP Input Threshold (Tx = 4096 Hz Square Wave)<br>Normal Mode to Loopback Mode<br>Loopback Mode to 4X Mode            | $V_{\text{4X/LOOP(IL)}}$<br>$V_{\text{4X/LOOP(IH)}}$ | 1.1<br>3.2   | 1.31<br>3.43  | 1.5<br>3.6 | V             |
| <b>RX</b>   |  |              |               |            |               |
| Rx Output Voltage Low<br>$V_{\text{BUS}} = 0\text{ V}$ , $I_{\text{RX}} = 1.6\text{ mA}$                                  | $V_{\text{RX(LOW)}}$                                 | 0.01         | 0.18          | 0.4        | V             |
| Rx Output Voltage High<br>$V_{\text{BUS}} = 7.0\text{ V}$ , $I_{\text{RX}} = -200\text{ }\mu\text{A}$                     | $V_{\text{RX(HIGH)}}$                                | 4.25         | 4.58          | 4.75       | V             |
| Rx Output Current<br>$V_{\text{RX}} = \text{High}$ ; Short Circuit Protection Limits                                      | $I_{\text{RX}}$                                      | 2.0          | 3.67          | 8.0        | mA            |
| <b>SLEEP</b>  |  |              |               |            |               |
| SLEEP Input Current<br>$V_{\text{SLEEP}} = 0\text{ V}$<br>$V_{\text{SLEEP}} = 5.0\text{ V}$                               | $I_{\text{SLEEP(IL)}}$<br>$I_{\text{SLEEP(IH)}}$     | –<br>1.0     | -0.23<br>6.21 | -2.0<br>20 | $\mu\text{A}$ |

**DYNAMIC ELECTRICAL CHARACTERISTICS**
**Table 4. Dynamic Electrical Characteristics**

Characteristics noted under conditions of  $7.0\text{ V} \leq V_{\text{BAT}} \leq 16\text{ V}$ ,  $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ ,  $\overline{\text{SLEEP}} = 5.0\text{ V}$  unless otherwise noted. Typical values reflect the parameter's approximate midpoint average value with  $V_{\text{BAT}} = 13\text{ V}$ ,  $T_A = 25^\circ\text{C}$ . All positive currents are into the pin. All negative currents are out of the pin.

| Characteristic   | Symbol  | Min        | Typ            | Max        | Unit |
|--|---|------------|----------------|------------|------|
| <b>BUS</b>   |   |            |                |            |      |
| BUS Voltage Rise Time <sup>(9)</sup> ( $9.0\text{ V} \leq V_{\text{BAT}} \leq 16\text{ V}$ , Tx = 7.812 kHz Square Wave) (see Figure 5)<br>BUS Load = 3,300 pF and 1.38 kΩ to GND<br>BUS Load = 16,500 pF and 300 Ω to GND | t <sub>RISE(BUS)</sub>                                | 9.0<br>9.0 | 11.15<br>11.86 | 15<br>15   | μs   |
| BUS Voltage Fall Time <sup>(9)</sup> ( $9.0\text{ V} \leq V_{\text{BAT}} \leq 16\text{ V}$ , Tx = 7.812 kHz Square Wave) (see Figure 5)<br>BUS Load = 3,300 pF and 1.38 kΩ to GND<br>BUS Load = 16,500 pF and 300 Ω to GND | t <sub>FALL(BUS)</sub>                                | 9.0<br>9.0 | 10.50<br>11.17 | 15<br>15   | μs   |
| Pulse Width Distortion Time ( $9.0\text{ V} \leq V_{\text{BAT}} \leq 16\text{ V}$ , Tx = 7.812 kHz Square Wave) (see Figure 6)<br>BUS Load = 3,300 pF and 1.38 kΩ to GND   | t <sub>PWD(BUS)</sub>                                 | 35         | 62             | 93         | μs   |
| Propagation Delay<br>Tx Threshold to Rx Threshold  | t <sub>PD(BUS)</sub>                                  | –          | 17.7           | 25         | μs   |
| <b>TX</b>  |   |            |                |            |      |
| Tx to BUS Delay Time (Tx = 2.5 V to $V_{\text{BUS}} = 3.875\text{ V}$ ) (see Figure 7)<br>4X Mode<br>Normal Mode   | t <sub>TXDELAY</sub>                                  | –<br>13    | 2.6<br>17.3    | 4.0<br>24  | μs   |
| $\overline{\text{SLEEP}}$ to Tx Setup Time (see Figure 7)  | t <sub><math>\overline{\text{SLEEP}}</math>TXSU</sub> | 80         | 40             | –          | μs   |
| <b>RX</b>  |   |            |                |            |      |
| Rx Output Delay Time (Tx = 2.5 V to $V_{\text{BUS}} = 3.875\text{ V}$ ) (see Figure 8)<br>Low-to-Output High<br>High-to-Output Low   | T <sub>RXDELAY/L-H</sub><br>T <sub>RXDELAY/H-L</sub>  | –<br>–     | 0.11<br>0.38   | 2.0<br>2.0 | μs   |
| Rx Output Transition Time (C <sub>RX</sub> = 50 pF to GND, 10% and 90% Points) (see Figure 9)<br>Low-to-Output High<br>High-to-Output Low  | t <sub>RXTRANS/L-H</sub><br>t <sub>RXTRANS/H-L</sub>  | –<br>–     | 0.34<br>0.08   | 1.0<br>1.0 | μs   |
| Rx Output Transition Time <sup>(10)</sup> (C <sub>RX</sub> = 50 pF to GND, $\overline{\text{SLEEP}} = 0\text{ V}$ , 10% and 90% Points) (see Figure 9)<br>Low-to-Output High<br>High-to-Output Low                         | t <sub>RXTRANS/L-H</sub><br>t <sub>RXTRANS/H-L</sub>  | –<br>–     | 0.32<br>0.08   | 5.0<br>5.0 | μs   |

**Notes**

9. Typical is the parameter's approximate average value with  $V_{\text{BAT}} = 13\text{ V}$ ,  $T_A = 25^\circ\text{C}$ .
10. Rx Output Transition Time from a sleep state.







Table 5. Class B Bus Capacitance and Resistance Expressions

| Level   | Capacitance   | Resistance to Ground  |
|---------|---|---|
| Minimum | $(3.3 \times 0.9) + (0.47 \times 0.9) = 3.39 \text{ nF}$    | $(1.5 \times 0.95) \parallel (10.6 \times 0.95) / 25 = 314 \ \Omega$    |
| Maximum | $(3.3 \times 1.1) + 25(0.47 \times 1.1) = 16.55 \text{ nF}$ | $(1.5 \times 1.05) \parallel (10.6 \times 1.05) = 1.38 \text{ k}\Omega$ |

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## TYPICAL APPLICATIONS

### Class B Module Inputs

#### Transmitter Data from the MCU (Tx)

The Tx input is a push-pull (N-channel/P-channel FETs) buffer with hysteresis for noise immunity purposes. This pin is a 5.0 V CMOS logic level input from the MCU following a true logic protocol. A logic [0] input drives the BUS output to 0 V (via the external pull-down resistor to ground on each node), while a logic [1] input produces a high voltage at the BUS output. A logic [0] input level is guaranteed when the Tx input pin is open-circuited by virtue of an internal 40 k $\Omega$  pull-down resistor. No external resistor is required for its operation.

#### Waveshaping and 4X/Loop

This input is a tristateable input: 0 V = normal waveshaping, 5.0 V = waveshaping is disabled for 4X transmitting, and high impedance = loopback mode of operation. This is a logic level input used to select whether waveshaping for the Class B output is enabled or disabled. A logic [0] enables waveshaping, while a logic [1] disables waveshaping. In the 4X mode, the BUS output rise time is less than 2.0  $\mu$ s and the fall time is less than 5.0  $\mu$ s (owing to the external RC pull-down to ground). In the loopback condition, the Tx signal is fed back to the Rx output *after* waveshaping *without* being transmitted onto the BUS. This mode of operation is useful for system diagnostic purposes.

### Class B Module Outputs

#### Transceiver Output (BUS)

This is the output driver stage that sources current to the bus. Its output follows the waveshaped waveform input. Its output voltage is limited to 6.25 V to 8.0 V under normal battery level conditions. The limited level is controlled by an internal regulator/clamp circuit. Once the battery voltage drops below 9.0 V, the regulator/clamp circuit saturates, causing the bus voltage to track the battery voltage. A 1.5 k $\Omega$   $\pm$ 5% external resistor (as well as any 10.6 k $\Omega$  pull-down resistors of any secondary nodes) sinks the current to discharge the capacitors during high-to-low transitions. This sourcing output is short circuit-protected (60 mA to 170 mA) against a short to -2.0 V and sinks less than 1.0 mA when shorted to VBAT. If a short occurs, the overtemperature shutdown circuit protects the source driver of the device. In the event battery power is lost to the assembly, the bus transmitter's output stage will be disabled and the leakage current from the BUS output will not source or sink more than 100  $\mu$ A of current. The transceiver will operate with a remote ground offset of  $\pm$ 2.0 V, but the lower corners of transmission will *not* be rounded during this condition.

#### Receiver Output to the Microcontroller (Rx)

This is a 5.0 V CMOS compatible push-pull output used to send received data to the microcontroller. It does not require an external pull-up resistor to be used. The receiver is always enabled and draws less than 65  $\mu$ A of current from V<sub>BAT</sub>. The receive threshold is dependent on the state of the SLEEP pin. The receiver circuitry is able to operate with V<sub>BAT</sub> voltages as low as 4.25 V and still remains capable of "waking up" the 33390 when remote Class B activity is detected.

When the SLEEP pin is 0 V and message activity occurs on the bus, the receiver passes the bus message through to the microcontroller. The 33390 does not automatically "wake up" from a sleep state when bus activity occurs: the microcontroller must tell it to do so.

In the Static Electrical Characteristics table, the maximum voltage for Rx is specified as 4.75 V over an operating range of -40°C to 125°C temperature and 7.0 V to 16 V V<sub>BAT</sub>. This maximum Rx voltage is compatible with the minimum V<sub>DD</sub> voltage of microcontrollers to prevent the 33390 from sourcing current to the microcontroller's output.

#### Switched Ground Output (LOAD)

Normally this output is a saturated switch to ground, which pulls down the external resistor between the BUS and LOAD outputs. In the event ground is lost to the assembly, the LOAD output will bias itself "off" and will not leak more than 100  $\mu$ A of current out of this pin.

#### Overtemperature Shutdown

If the BUS output becomes shorted to ground for any duration, an overtemperature shutdown circuit "latches off" the output source transistor whenever the die temperature exceeds 150°C to 190°C. The output transistor remains latched off until the Tx input is toggled from a logic [0] to a logic [1]. The rising edge provides the clearing function, provided the locally sensed temperature is 10°C to 15°C below the latch-off temperature trip temperature.

#### Waveshaping

Waveshaping is incorporated into the 33390 to minimize radiated EMI emissions.

#### Receiver Protocol

The Class B communication scheme uses a variable pulse width (VPW) protocol. The microcontroller provides the VPW decoding function. Once the receiver detects a transition on Rx, it starts an internal counter. The initial "start of frame" bit is a logic [1] and lasts 200  $\mu$ s. For subsequent bits, if there is a bus transition before 96  $\mu$ s, one logic state is inferred. If there is a bus transition after 96  $\mu$ s, the other logic state is inferred. The "end of data" bit is a logic [0] and lasts 200  $\mu$ s. If there is no activity on the bus for 280  $\mu$ s to 320  $\mu$ s following a broadcast message, multiple unit nodes may arbitrate for control of the next message. During an arbitration, after the

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“start of frame” bit has been transmitted, the secondary node transmitting the most consecutive logic [0] bits will be granted sole transmission access to the bus for that message.

#### Loss of Assembly Ground Connection

The definition of a loss of assembly ground condition at the device level is that all pins of the 33390, with the exception of BUS and LOAD, see a very low impedance to VBAT.

The LOAD pin of the device has an internal transistor switch connected to it that is normally saturated to ground. This pulls the LOAD-side of the external resistor (tied from BUS to LOAD) to ground under normal conditions. The LOAD pin switch is essentially that of an “upside down” FET, which is normally biased “on” so long as module ground is present and biased “off” when loss-of-ground occurs. When a loss of assembly ground occurs, the load transistor switch is self-biased “off”, allowing no more than 100  $\mu$ A of leakage current

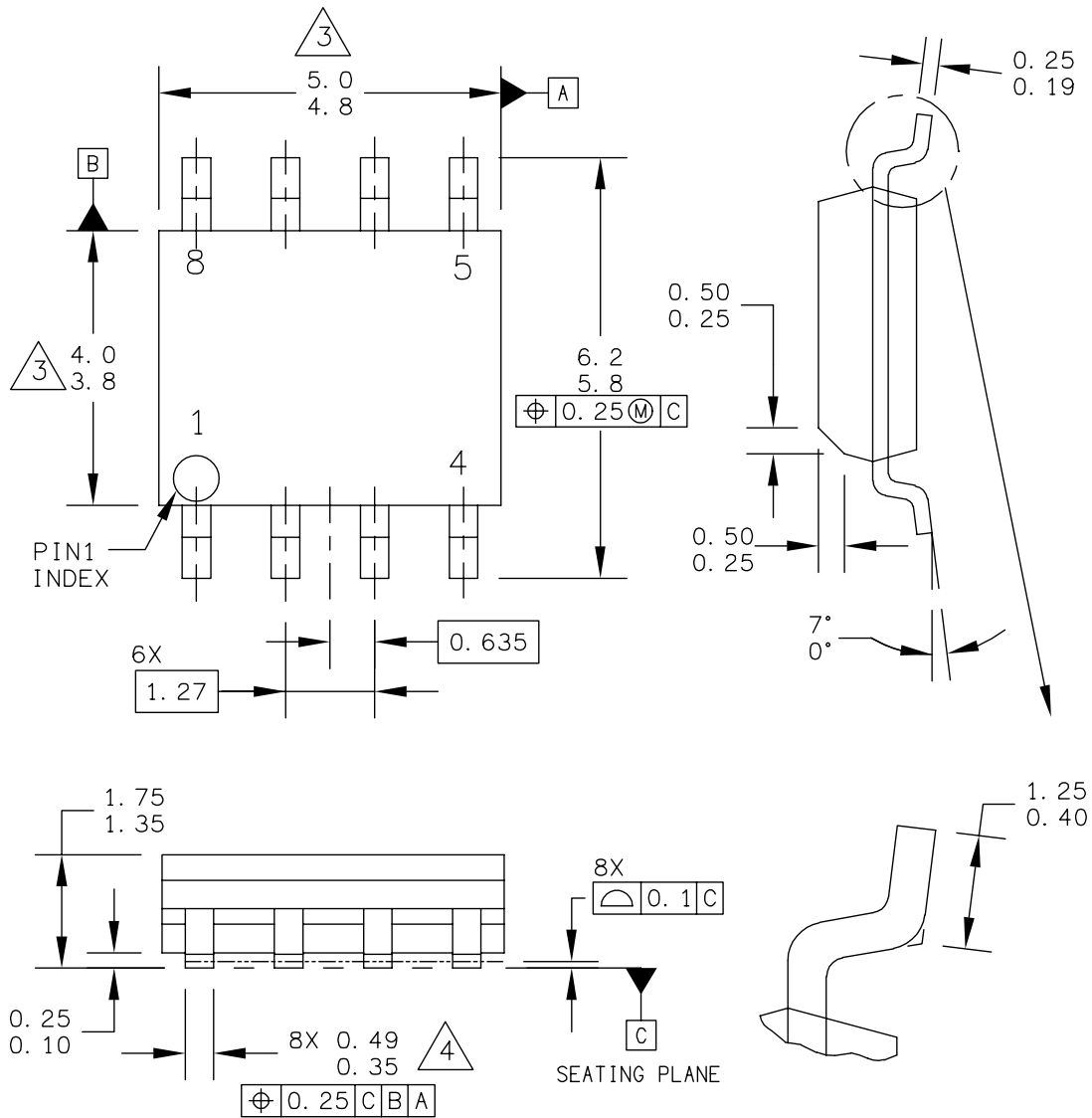
to flow in the LOAD pin. During such a loss of assembly ground condition, the BUS and LOAD pins exhibit a high impedance to VBAT; all other pins will exhibit a low impedance to V<sub>BAT</sub>. During this condition the BUS pin is prevented from sourcing any current or loading the bus, which would cause a corruption of any data being transmitted on the bus. While a particular assembly is experiencing a loss of ground, all other assembly nodes are permitted to function normally. It should be noted that with other nodes existing on the bus, the bus will always have some minimum/maximum impedance to ground as shown in [Table 5](#), page [10](#).

#### Loss of Assembly Battery Connection

The definition of a loss of assembly battery condition at the device level is that the VBAT pin of the 33390 sees an infinite impedance to VBAT, but there is some undefined impedance between these pins and ground.

### PACKAGE DIMENSIONS

For the most current package revision, visit [www.freescale.com](http://www.freescale.com) and perform a keyword search using the 98A listed below.



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