## 36V High Efficiency Boost Converter with I²C Controlled 6-CH LED Driver

## General Description

The RT8555 is a high efficiency driver for white LEDs. It is suitable for single/two cell battery input to drive LED light bars which contains six strings in parallel and up to 10 WLEDs per string. The internal current sinks support a maximum of $\pm 2 \%$ current mismatching for excellent brightness uniformity in each string of LEDs. To provide enough headroom for current sink operation, the Boost controller monitors the minimum voltage of the feedback pins and regulates an optimized output voltage for power efficiency.

The RT8555 has a wide input voltage operating range from 2.7 V to 24 V and contains $I^{2} \mathrm{C}$ interface for controlling the dimming mode, operating frequency and the LED current. The internal $100 \mathrm{~m} \Omega, 36 \mathrm{~V}$ power switch with current-mode control provides over-current protection. The switching frequency of the RT8555 is adjustable from 300 kHz to 2 MHz , which allows flexibility between efficiency and component size.

The RT8555 is available in the WL-CSP-20B $1.65 \times 2.05$ (BSC), with pitch 0.4 mm package.

## Ordering Information

RT8555
—Package Type WSC : WL-CSP-20B 1.65x2.05 (BSC)

Note :
Richtek products are :

- RoHS compliant and compatible with the current require-
ments of IPC/JEDEC J-STD-020.
- Suitable for use in SnPb or Pb -free soldering processes.


## Marking Information

$1 \mathrm{XW} \quad$| X: Product Code |
| :--- |
| $\mathrm{W}:$ Date Code |

## Features

- Wide Operating Input Voltage : 2.7V to 24 V
- High Output Voltage : Up to 36V
- Programmable Channel Current : 10mA to 35mA
- Channel Current Regulation with Accuracy $\pm 3 \%$ and Matching $\pm 2 \%$
- Dimming Controls
- Direct PWM Dimming up to 20kHz and Minimum On-Time to 400ns
- PWM to Analog Dimming up to 20kHz with 8-bit Resolution
- $I^{2} C$ Programs LED Current, Switching Frequency, Dimming Mode
- Switching Frequency : 300kHz to 2 MHz
- Protections
, LED Strings Open Detection
- Current Limit
- Programmable Over Voltage Protection
- Over-Temperature Protection
- 20-Ball WL-CSP, with pitch 0.4mm Package
- RoHS Compliant and Halogen Free


## Applications

- Tablet and Notebook Backlight


## Pin Configurations

| (TOP VIEW) |  |  |  |
| :---: | :---: | :---: | :---: |
| A1) | A2, | A3) | A4 |
| LX | PGND | SDA | SCL |
| (B1) | B2) | B3) | B4) |
| LX | PĞND | PẄM | ĖN |
| © ${ }^{\text {ci }}$ | CO | (C3) | (C4) |
| VİN | VOUT | GN̈D | FB3 |
| (Di) | (D2) | (D3) | (D4) |
| Vī̃ | VC̈P | GN̈D | $\stackrel{\text { FB2 }}{ }$ |
| (E1) | (E2) | (E3) | E4) |
| FB6 | FB̈5 | FB4 | $\stackrel{\mathrm{FB}}{ } 1$ |

WL-CSP-20B $1.65 \times 2.05$ (BSC)

Functional Pin Description

| Pin No. | Pin Name. |  |
| :---: | :--- | :--- |
| A1, B1 | LX | Switch Function |
| A2, B2 | PGND | Power Ground. |
| A3 | SDA | Data Signal Input of I ${ }^{2}$ C Interface. |
| A4 | SCL | Clock Signal Input of I ${ }^{2}$ C Interface. |
| B3 | PWM | PWM Dimming Control Input. |
| B4 | EN | Enable Control Input (Active High). |
| C1, D1 | VIN | Power Input. |
| C2 | VOUT | Output of Boost Converter. |
| C3, D3 | GND | Ground. |
| C4 | FB3 | Current Sink for LED3. |
| D2 | VCP | Output of Internal Regulator. |
| D4 | FB2 | Current Sink for LED2. |
| E1 | FB6 | Current Sink for LED6. |
| E2 | FB5 | Current Sink for LED5. |
| E3 | FB4 | Current Sink for LED4. |
| E4 | FB1 | Current Sink for LED1. |

## Function Block Diagram



## Operation

## Enable Control

When VIN is higher than the UVLO voltage and the EN pin input voltage is higher than rising threshold, the VDC will be regulated around 3.2 V if VIN is higher than 3.2 V .

## Switching Frequency

The LED driver switching frequency is adjusted by the $\mathrm{I}^{2} \mathrm{C}$. The switching frequency is from 300 kHz to 1.9 MHz .

## PWM Controller

This controller includes some logic circuit to control LX N -MOSFET on/off. This block controls the minimum ontime and max duty of LX.

## OCP \& OTP

When LX N-MOSFET peak current is higher than 2.5A(typically), the LX N-MOSFET is turned off immediately and resumed again at next clock pulse. When the junction temperature is higher than $150^{\circ} \mathrm{C}$ (typically), the LXN-MOSFET will be turned off until the temperature is lower than the $130^{\circ} \mathrm{C}$ (typically).

## OVP

The RT8555 integrates over voltage protection. The over voltage protection could be set by the $I^{2} \mathrm{C}$, When the OVP pin voltage is higher than 36 V , the LXN-MOSFET is turned off immediately to protect the LX N-MOSFET.

## Minimum LED Selection

This block detects all LEDx voltage and select a minimum voltage to EA (Error Amplifier). This function can guarantee the lowest of the LED pin voltage is around 500 mV and Vout can be Boost to the highest forward voltage of LED strings.

## LED Open Detection

If the voltage at LEDx pin is lower than 100 mV , this channel is defined as open channel and the Minimum LED Selection function will discard it to regulate other used channels in proper voltage.
Absolute Maximum Ratings (Note 1)

- Supply Voltage, VIN to GND ..... -0.3 V to 26.4 V
- LX, VOUT, FB1, FB2, FB3, FB4, FB5, FB6 to GND -0.3 V to 40 V
- EN, PWM, SDA, SCL, VCP to GND ..... -0.3 V to 6 V
- Power Dissipation, $\mathrm{P}_{\mathrm{D}}$ @ $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$WL-CSP-20B $1.65 \times 2.05$ (BSC)2.72W
- Package Thermal Resistance (Note 2) WL-CSP-20B $1.65 \times 2.05$ (BSC), $\theta_{\mathrm{JA}}$ ..... $36.7^{\circ} \mathrm{C} / \mathrm{W}$
- Junction Temperature ..... $150^{\circ} \mathrm{C}$
- Lead Temperature (Soldering, 10 sec .) ..... $260^{\circ} \mathrm{C}$
- Storage Temperature Range ..... $-65^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$
- ESD Susceptibility (Note 3)
HBM (Human Body Model) ..... 2kV
MM (Machine Model) ..... 200V
Recommended Operating Conditions (Note 4)
- Junction Temperature Range ..... $-40^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$
- Ambient Temperature Range $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$


## Electrical Characteristics

$\left(\mathrm{V}_{\mathrm{IN}}=3.8 \mathrm{~V}, \mathrm{C}_{\mathrm{IN}}=1 \mu \mathrm{~F}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right.$, unless otherwise specified)

| Parameter |  | Symbol | Test Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input Power Supply |  |  |  |  |  |  |  |
| Input Supply Voltage |  | VIN |  | 2.7 | 3.8 | 24 | V |
| Quiescent Current |  | $\mathrm{I}_{\mathrm{Q}}$ | LX no switching | -- | 2.7 | -- | mA |
| Shutdown Current |  | ISHDN | $\mathrm{V}_{\text {IN }}=3.8 \mathrm{~V}$, EN $=0 \mathrm{~V}$ | -- | -- | 1 | $\mu \mathrm{A}$ |
| Under-Voltage Lockout Threshold |  | Vuvio | VIn Rising | -- | 2.3 | -- | V |
| Under-Voltage Lockout Hysteresis |  | $\Delta \mathrm{V}$ UVLO |  | -- | 200 | -- | mV |
| Over-Temperature Protection Threshold |  | Totp |  | -- | 150 | -- | ${ }^{\circ} \mathrm{C}$ |
| Over-Temperature Protection Hysteresis |  | TOTP_HYS |  | -- | 20 | -- | ${ }^{\circ} \mathrm{C}$ |
| Interface Characteristic |  |  |  |  |  |  |  |
| EN, PWM, SCL, SDA Input Voltage | Logic-High | $\mathrm{V}_{\mathrm{IH}}$ |  | 1.4 | -- | -- | V |
|  | Logic-Low | VIL |  | -- | -- | 0.8 | V |
| Internal Pull-Low Current for EN, PWM |  | IIH_1 |  | -- | -- | 10 | $\mu \mathrm{A}$ |
| Internal Pull-Low Current for SCL, SDA |  | $\mathrm{IIH}_{\mathbf{H}}$ 2 |  | -- | 0.01 | 1 | $\mu \mathrm{A}$ |
| Output Low Level for SDA |  | VoL | External Pull High Current $=3 \mathrm{~mA}$ | -- | 0.3 | 0.5 | V |
| Output Leakage Current for SDA |  | ILK_DIO | SDA Pin Voltage $=3.3 \mathrm{~V}$ | -- | -- | 1 | $\mu \mathrm{A}$ |
| $1^{2} \mathrm{C}$ Interface Timing |  |  |  |  |  |  |  |
| Maximum ${ }^{2} \mathrm{C}$ Clock Frequency |  | fsc_max |  | -- | 400 | -- | kHz |


| Parameter | Symbol | Test Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Hold Time for START And Repeated START Condition | $\mathrm{t}_{\text {HD, STA }}$ |  | 0.6 | -- | -- | $\mu \mathrm{S}$ |
| SCL Clock Low Time | tLOW |  | 1.3 | -- | -- | $\mu \mathrm{S}$ |
| SCL Clock High Time | $\mathrm{t}_{\text {HIGH }}$ |  | 600 | -- | -- | ns |
| Setup Time for A Repeated START Condition | $t_{\text {SU, STA }}$ |  | 600 | -- | -- | ns |
| SDA Data Hold Time | $\mathrm{t}_{\text {HD, DAT }}$ |  | 50 | -- | -- | ns |
| SDA Data Setup Time | tsu,DAT |  | 100 | -- | -- | ns |
| Rising Time of SDA, SCL | $\mathrm{t}_{\mathrm{R}}$ |  | -- | -- | 300 | ns |
| Falling Time of SDA, SCL | $\mathrm{t}_{\mathrm{F}}$ |  | -- | -- | 300 | ns |
| Setup Time for STOP Condition | tsu,STO |  | 600 | -- | -- | ns |
| $I^{2} \mathrm{C}$ Bus Free Time Between a STOP and a START | $\mathrm{t}_{\text {BUF }}$ |  | 1.3 | -- | -- | $\mu \mathrm{S}$ |
| Capacitive Load for $\mathrm{I}^{2} \mathrm{C}$ Bus | $\mathrm{C}_{\mathrm{B}}$ |  | -- | -- | 400 | pF |
| Boost Converter |  |  |  |  |  |  |
| Switching Frequency Accuracy | fsw_ACC | Boost Operates at PWM Mode, $\mathrm{fsw}=600 \mathrm{kHz}$ | -10 | -- | 10 | \% |
| Switching Frequency Setting Range | fsw_RG | Boost Operates at PWM Mode | 0.3 | -- | 2 | MHz |
| Maximum Duty Cycle | Dmax | $\mathrm{f}_{\text {SW }}=600 \mathrm{kHz}$ | -- | 95 | -- | \% |
| Boost Switch RDs(ON) | RDS(ON) |  | -- | 0.1 | 0.3 | $\Omega$ |
| Switching Current Limitation | locp |  | 2 | 2.5 | 3 | A |
| LED Current |  |  |  |  |  |  |
| Leakage Current of FBx | lLK_FB | $\mathrm{V}_{\mathrm{FBx}}=36 \mathrm{~V}, \mathrm{I}_{\mathrm{FBx}}=0 \mathrm{~mA}$ | -- | -- | 1 | $\mu \mathrm{A}$ |
| Minimum FBx Regulation Voltage | $\mathrm{V}_{\mathrm{FB}}(\mathrm{MIN})$ | $\mathrm{I}_{\mathrm{FBx}}=20 \mathrm{~mA}$ | 0.3 | -- | -- | V |
| Maximum LED Current Setting | IfB(MAX) | LED 100\% Setting | 10 | -- | 35 | mA |
| Minimum LED Current Setting | IFB (MIN) | Setting By Dimming | 0.2 | -- | -- | mA |
| LED Current Accuracy | IFB_ACC | PWM Duty $=100 \%$, $\mathrm{I}_{\text {FBx }}=20 \mathrm{~mA}$ | -3 | -- | 3 | \% |
| LED Current Matching | IFB_MAT | PWM Duty $=100 \%, \mathrm{I}_{\text {FBx }}=20 \mathrm{~mA}$ | -2 | -- | 2 | \% |
| FBx Channel Unused Threshold | VFb_UNUSE |  | -- | 0.1 | -- | V |
| Light Bar Open Threshold | VFB_OPEN |  | -- | 0.1 | -- | V |
| PWM Minimum On Duty | DpWm_MIN | PWM Dimming Frequency $=20 \mathrm{kHz}$ | 0.8 | -- | -- | \% |

Note 1. Stresses beyond those listed "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
Note 2. $\theta_{\mathrm{JA}}$ is measured at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ on a high effective thermal conductivity four-layer test board per JEDEC 51-7.
Note 3. Devices are ESD sensitive. Handling precaution is recommended.
Note 4. The device is not guaranteed to function outside its operating conditions.

## Typical Application Circuit



Note : For unused channels (FBx), please connect FBx pin to GND.

## Timing Diagram

## $I^{2} \mathrm{C}$ Interface



RT8555 $I^{2} \mathrm{C}$ slave address $=7$ 'b0110_001. $\mathrm{I}^{2} \mathrm{C}$ interface support fast mode (bit rate up to $400 \mathrm{~kb} / \mathrm{s}$ ). The write or read bit stream ( $\mathrm{N} \geq 1$ ) is shown below

Read N bytes from RT8555


Write N bytes to RT8555

$\square$ Driven by Master, $\square$ Driven by Slave (RT8555),
P Stop, S Start, Sr Repeat Start

Typical Operating Characteristics



Quiescent Current vs. Input Voltage


Power On from EN



Line Transient Response


Power Off from EN


## Application Information

Table 1. Register Map

| Slave Address : b0110001 |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Register Address | bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 | Default Value |
| 0x00 | MIX-26K | Edge Rate Control |  | Spread Spectrum | Mixed Mode Change Duty |  | ILED Brightness Selection | Dimming Mode Selection | 0x4c |
| $0 \times 01$ | 10 bit mode selection | Over Voltage Protection Selection |  | Switching Current Limitation Selection | Boost Switching Frequency |  |  |  | 0x76 |
| 0x02 | ILED Current Setting |  |  |  |  |  |  |  | 0x92 |
| $0 \times 03$ |  | LDO Regulation Voltage Setting |  | ILED Brightness Compensation Ratio |  |  |  |  | 0x00 |
| 0x04 | ILED Brightness LSB Register 1 |  |  |  |  |  |  |  | 0x00 |
| 0x05 |  |  |  |  |  |  | ILED Brightness MSB Register 1 |  | 0x00 |
| $0 \times 06$ | ILED Brightness LSB Register 2 |  |  |  |  |  |  |  | 0x00 |
| $0 \times 07$ |  |  |  |  |  |  | ILED Brightness MSB Register 2 |  | 0x00 |
| 0x08 |  | Smart Dither Slope Time Control |  |  | LED driver headroom |  | Advanced Brightness Control |  | 0x00 |
| $0 \times 09$ |  | Fade In / Out Time Control |  | Smart <br> Dither <br> Enable |  | PWM <br> Dither <br> Enable | Dither Resolution |  | 0x1C |
| 0x0A | 26KHz Mode Division Frequency |  |  |  |  |  | Soft Start Time Control |  | 0x04 |
| 0x0B | Stop Compensation Duty |  |  |  |  |  |  |  | 0x00 |
| 0x0D | Control CLK PFM Function Enable |  |  |  |  |  |  |  | $0 \times 00$ |
| 0x0E |  |  | LED Unused Check |  | LED O | P Level |  |  | 0x00 |
| 0x50 |  |  |  |  |  |  |  |  | $0 \times 06$ |
| 0x51 |  |  |  |  |  |  |  |  | 0x00 |

Note : Blank part in table is restricted register.

The RT8555 is a general purpose 6-CH LED driver and is capable of delivering a maximum 35 mA LED current. The IC is a current mode Boost converter integrated with a 2.5A power switch and can cover a wide VIN range from 2.7 V to 24 V and contains $\mathrm{I}^{2} \mathrm{C}$ interface for controlling the dimming mode, operating frequency and the LED current. The internal $100 \mathrm{~m} \Omega, 36 \mathrm{~V}$ power switch with current-mode control provides over current protection. The switching frequency of the RT8555 is adjustable from 300 kHz to 2 MHz , which allows flexibility between efficiency and component size.

Programmable functions include :

## - PWMO frequencies

## Brightness Control by PWM Pin

The RT8555 provide three dimming modes for controlling the LED brightness. The three dimming modes include PWM mode, DC mode and Mixed mode, and the dimming mode could be set by register 00h.

Table 2. Dimming Control Mode Selection

| Address | Bit | Name | Default Value | Description | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 00h | [0] | Dimming Mode Selection | PWM Mode (B0) | B0 : PWM mode <br> B1 : Mixed mode | R/W |
|  | [3:2] | Mixed Mode Change Duty | 25\% (B11) | $\begin{aligned} & \text { B00 : 0\% } \\ & \text { B01 : 6.25\% } \\ & \text { B10 : 12.5\% } \\ & \text { B11 : } 25 \% \end{aligned}$ | R/W |
|  | [7] | MIX-26K | PWM pin (B0) | B0 : follow PWM pin frequency <br> B1: fixed 26kHz | R/W |

Note : DC mode = Dimming Mode Selection $(00 \mathrm{~h}[0]=\mathrm{B} 1)+$ Mixed Mode Change Duty $=0 \%(00 \mathrm{~h}[3: 2]=\mathrm{BO})$

## PWM Mode

The ON/OFF of the current source is synchronized to the PWM signal. The frequency of LED current is equal to the PWM input signal.


Figure 1. PWM Dimming

## DC Mode

The LED current will have two cycle delay in this mode, while the delay cycles are for average current calculation.


Figure 2. DC Dimming

## Mixed Mode

In $25 \%$ Mixed mode, $25 \%$ the PWM input signal and LED current are both delayed by two cycles with additional variations.

- When $25 \% \leq$ PWM duty $\leq 100 \%$, the PWM duty modulated the amplitude of the current. (Same as DC mode)
- PWM duty $<25 \%$, the DC dimming will translate to PWM dimming, controlling the PWM duty instead by amplitude. The LED current is fixed on quarter of LED current setting.


Figure 3. Mixed Mode Dimming

## Brightness Control Signal Selection

The RT8555 integrates a dimming control signal selection. The dimming control signal source could be set by the second bit of register 00h. If the bit equals to 0 , it means the dimming control signal source just depends on the input signal of the PWM pin. Otherwise, if the bit equals to 1 , the dimming control signal is controlled by the command of register 04/05h. The option is shown in Table 3 below.

Table 3. Dimming Control Signal Selection

| Address | Bit | Name | Default Value | Description | R/W |
| :---: | :---: | :--- | :---: | :--- | :---: |
| 00 h | $[1]$ | ILED Brightness <br> Selection | PWM Pin <br> $(B 0)$ | B0 : depend on the status of PWM pin <br> B1 : depend on address:04/05h data | R/W |

## Switching Frequency

The LED driver switching frequency is adjusted by the $I^{2} C$, the switching frequency setting range, Spread Spectrum, LX Slew Rate and resolutions are shown in the Table 4 below.

Table 4. Switching Frequency Setting

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00h | [4] | Spread Spectrum | w/o <br> (B0) | B0: w/o <br> B1: w/i |  | R/W |
| 00h | [6:5] | Edge Rate Control | Fast (B10) | B00: Slow <br> B01 : Normal <br> B10: Fast |  | R/W |
| 01h | [3:0] | Boost Switching Frequency | $\begin{aligned} & 900 \mathrm{kHz} \\ & \text { (0x06h) } \end{aligned}$ | $\begin{aligned} & \text { 0x00h : } 300 \mathrm{kHz} \\ & 0 \times 07 \mathrm{~h}: 1 \mathrm{MHz} \\ & 0 \times 0 \mathrm{Ch}: 2 \mathrm{MHz} \end{aligned}$ | 100kHz (0x00h to 0x07h) 200 kHz ( $0 \times 07 \mathrm{~h}$ to $0 \times 0 \mathrm{Ch}$ ) | R/W |

If the switching frequency command is below to register $0 \times 01$. The switching frequency is from 300 kHz to 1 MHz and resolution is 100 kHz . The switching frequency is from 1 MHZ to 2 MHz and resolution is 200 kHz .

## Current Limit Protection

The RT8555 integrates current limit protection, and the current of current limit protection could be set by $\mathrm{I}^{2} \mathrm{C}$, which is shown in the Table 5 below.

Table 5. Current Limit Protection Setting

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01 h | $[4]$ | Switching Current <br> Limitation Selection | 2.5 A <br> (B1) | B0 $: 1.5 \mathrm{~A}$ <br> $\mathrm{~B} 1: 2.5 \mathrm{~A}$ | -- | R/W |

The RT8555 can limit the peak current to achieve over current protection. The RT8555 senses the inductor current during the "ON" period that flows through the LX pin. The duty cycle depends on the current signal and internal slope compensation in comparison with the error signal. The internal switch of Boost converter will be turned off when the peak current value of inductor current is larger than the over current protection setting. In the "OFF" period, the inductor current will be decreased until the internal switch is turned on by the oscillator.

## Over Voltage Protection

The RT8555 integrates over voltage protection. The over voltage protection could be set by the $\mathrm{I}^{2} \mathrm{C}$, the voltage of over voltage protection ( $\mathrm{V}_{\mathrm{OV}}$ ) could be selected as the Table 6 below.

Table 6. OVP Voltage Setting

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01h | [6:5] | Over Voltage Protection Selection | $\begin{gathered} 36 \mathrm{~V} \\ (\mathrm{~B} 11) \end{gathered}$ | Boost output over voltage protection. <br> B00 : 25V <br> B01 : 28V <br> B10 : 32V <br> B11 : 36V | -- | R/W |

When the Boost output voltage rises above the $\mathrm{V}_{\text {ovp }}$, the internal switch will be turned off. Once the Boost output voltage drop below the $\mathrm{V}_{\mathrm{OV}}$, the internal switch will be turned on again. The Boost output voltage can be clamped at the $\mathrm{V}_{\text {ovp }}$.

## LED Current Setting

The LED current of each channel could be set by ${ }^{2} \mathrm{C}$ command; it is shown in the Table 7 .
Table 7. LED Current Setting

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 02h | [7:0] | ILED Current Setting | $\begin{gathered} 20.04 \mathrm{~mA} \\ (0 \times 92 \mathrm{~h}) \end{gathered}$ | Control the max current <br> 0x00h: 0mA <br> $0 \times 01 \mathrm{~h}$ to $0 \times 49 \mathrm{~h}: 10.02 \mathrm{~mA}$ <br> 0x49h : 10.02 mA <br> 0x92h : 20.04mA <br> 0xFFh: 35mA | $\begin{gathered} \sim 0.137 \mathrm{~mA} \\ (0 \times 49 \mathrm{~h} \text { to } 0 \times \mathrm{FFh}) \end{gathered}$ | R/W |

When the LED current setting command is below $0 x 92 \mathrm{~h}$, the LED current will be kept at 20.04 mA . When the command is $0 \times 00 \mathrm{~h}$, the LED current will be set to 0 mA . the maximum LED current setting is 35 mA . The one step of LED current is approximately 0.137 mA .

## LDO Regulation Voltage Setting

The LDO regulation voltage could be set by the I2C, it is shown in the Table 8.
Table 8. LDO Regulation Voltage Setting

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :--- | :---: | :--- | :--- | :--- | :---: | :---: |
| 03 h | $[6: 5]$ | LDO |  | LDO regulation voltage setting |  |  |
|  |  | Regulation | 3.2 V | B00: 3.2 V |  |  |
|  | Voltage | (B00) | B01: 3.4V | B10: 3.6 V |  | R/W |
|  | Setting |  | B11:4.6V |  |  |  |

When the LDO regulation voltage setting command is below B00, the LDO regulation voltage will be kept at 3.2V. The maximum LDO setting is 4.6 V . The setting condition is smaller than the input voltage.

## Brightness Control by $\mathrm{I}^{2} \mathrm{C}$ Register

With brightness register control the output current is controlled with 8-bit resolution or 10-bit resolution register bits. It is shown in the Table 9.

Table 9. Brightness Register

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 01h | [7] | 10 bit mode selection | 8bit <br> (B0) | B0 : 8 bit mode <br> B1 : 10 bit mode |  | R/W |
| 04h | [7:0] | ILED Brightness LSB Register 1 | $\begin{gathered} 0 \% \\ (0 \times 00 h) \end{gathered}$ | $\begin{aligned} & \text { 0x00h : 0\% } \\ & \text { 0xFFh : 100\% } \end{aligned}$ | ~ 0.4\% | R/W |
| 05h | [1:0] | ILED Brightness MSB Register 1 | $\begin{gathered} 0 \% \\ (0 \times 00 \mathrm{~h}) \end{gathered}$ | If $01 \mathrm{~h}[7]$ is 1 , need 04 h \& 05 h series write and then ILED brightness change |  | R/W |
| 06h | [7:0] | ILED Brightness LSB Register 2 | $\begin{gathered} 0 \% \\ (0 \times 00 \mathrm{~h}) \end{gathered}$ | $\begin{aligned} & \text { 0x00h : 0\% } \\ & \text { 0xFFh : 100\% } \end{aligned}$ | ~ 0.4\% | R/W |
| 07h | [1:0] | ILED Brightness MSB Register 2 | $\begin{gathered} 0 \% \\ (0 \times 00 h) \end{gathered}$ | If $01 \mathrm{~h}[7]$ is 1 , need 06 h \& 07h series write and then ILED brightness change |  | R/W |

## ILED Brightness Compensation

ILED Brightness compensation which is shown in the Table 10 below.
Table 10. ILED Brightness Compensation

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 03h | [4:0] | ILED Brightness compensation ratio | No compensation $(0 \times 00 \mathrm{~h})$ | Compensation ratio. <br> Formula : ILED / $1023 \times\{D A C-[D A C$ <br> $x(1023-D A C) \times k] / 1023 / 31\}$ |  | RM |
| OBh | [7:0] | Stop compensation duty | 0x00h | PWM duty compensation stop ratio |  | RM |

Note : ILED = ILED Current Setting (02h[7:0])
DAC = PWM pin Duty or ILED Brightness (04h[7:0], 05h[1:0] or 06h[7:0], 07h[1:0])


Figure 4. LED Current (Different Compensation Ratio) vs. Register Code


Figure 5. LED Current vs. Register Code

## Advanced Brightness Control

Dimming control is received either from PWM input pin or from $I^{2} \mathrm{C}$ register bits which is shown in the Table 11 below.
Table 11. Advanced Brightness Control

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 08h | [1:0] | Advanced Brightness Control | B00 | B00 : PWMO = PWMI or I ${ }^{2} \mathrm{C}(04 \mathrm{~h}, 05 \mathrm{~h})$ <br> B01: PWMO = PWMI multiply I ${ }^{2} \mathrm{C}(04 \mathrm{~h}, 05 \mathrm{~h})$ or $I^{2} C(04 h, 05 h)$ <br> B10 : PWMO = PWMI multiply $\mathrm{I}^{2} \mathrm{C}(06,07 \mathrm{~h})$ or $I^{2} \mathrm{C}(04 \mathrm{~h}, 05 \mathrm{~h})$ multiply $\mathrm{I}^{2} \mathrm{C}(06,07 \mathrm{~h})$ <br> B11 : same as B10 |  | R/W |

Table 12. Brightness Control Table

|  | B <br> Control2 | B <br> Control1 | pwm/26K | Mix Mode <br> Duty | PWM/I ${ }^{2}$ C | PWM/MIX | ILED Max | PWMO <br> Duty |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Register | $08 \mathrm{~h}[1]$ | $08 \mathrm{~h}[0]$ | $00[7]$ | $00 \mathrm{~h}[3: 2]$ | $00 \mathrm{~h}[1]$ | $00 \mathrm{~h}[0]$ |  |  |
| PWM | 0 | 0 | 0 | Don't care | 0 | 0 | PWMI | PWMI |
| $\mathrm{PWM}^{\star}{ }^{2} \mathrm{C}$ | 0 | 1 | 0 | Don't care | 0 | 0 | $\mathrm{PWMI}{ }^{\star}$ <br> $04 \mathrm{~h}, 05 \mathrm{~h}$ | PWMI |
| $\mathrm{I}^{2} \mathrm{C}-\mathrm{PWM}-26 \mathrm{~K}$ | 0 | 0 | 1 | Don't care | 1 | 0 | $04 \mathrm{~h}, 05 \mathrm{~h}$ | 04 h, <br> $05 h$ |
| $\mathrm{I}^{2} \mathrm{C}-\mathrm{DC}-26 \mathrm{~K}$ | 0 | 0 | 1 | 00 | 1 | 1 | $04 \mathrm{~h}, 05 \mathrm{~h}$ |  |

## LED Driver Headroom

The LED driver headroom could be set by the $\mathrm{I}^{2} \mathrm{C}$, it is shown in the Table 13.
Table 13. LED Driver Headroom

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 08h | [3:2] | LED driver headroom | B00 | LED driver headroom <br> B00 : 500mV <br> B01 : 570mV <br> B10 : 600mV <br> B11: 700mV | -- | R/W |

The RT8555 detects all FBx voltage and selects a minimum voltage to EA (Error Amplifier). When the LED driver headroom command is below $B 00$, the LED driver headroom will be kept at 500 mV and $\mathrm{V}_{\text {out }}$ can be boost to the highest forward voltage of LED strings. This function can guarantee the highest of FB pin voltage is 700 mV .

## Fade IN I OUT Time Control

The fade in / out time control could be set by the $\mathrm{I}^{2} \mathrm{C}$, it is shown in the Table 14.
Table 14. Fade In I Out Time Control

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 09h | [6:5] | Fade IN / OUT Time Control | B00 | DC mode fade time control <br> B00 : $0.5 \mu \mathrm{~s}$ <br> B01 : $1 \mu \mathrm{~s}$ <br> B10 : $2 \mu \mathrm{~s}$ <br> B11 : $4 \mu \mathrm{~s}$ | -- | R/W |

Fade in / out time can be control by address 09h[6:5], there are four brightness times that adjust range from $0.5 \mu \mathrm{~s}$ to $4 \mu \mathrm{~s}$. When the fade in/out command is below B00, the brightness time of per step will be kept at $0.5 \mu \mathrm{~s}$. This function can guarantee the highest of fade in/out time is $4 \mu \mathrm{~s}$. The Figure 6 shows the fade in time at 10 bit resolution. The Figure 7 shows the fade out time at 10 bit resolution.


Figure 6. LED Current (Dimming Up) vs. Fade IN Time


Figure 7. LED Current (Dimming Down) vs. Fade Out Time

## Soft-Start Time Control

The soft-start time control could be set by the $\mathrm{I}^{2} \mathrm{C}$, it is shown in the Table 15.
Table 15. Soft Start Time Control

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0Ah | [1:0] | Soft-Start Time Control | B00 | Soft start time control $\begin{aligned} & \text { B00 : x1 } \\ & \text { B01 : x2 } \\ & \text { B10 : x4 } \\ & \text { B11 : x8 } \end{aligned}$ | -- | R/W |

Soft-start time can be control by address 0Ah[1:0], there are four soft start times that adjust range from 1 time to 8 time. When the command is below B00, the soft start time will be kept at 1 time. This function can guarantee the highest of soft start time is 8 time. The Figure 8 shows the soft start time at power on. The Figure 9 shows the soft start time at power off.

Soft-Start Time (Dimming Up)


Figure 8. LED Current (Dimming Up) vs. Soft Start Time

## Soft Start Time (Dimming Down)



Figure 9. LED Current (Dimming Down) vs. Soft Start Time

## Smart Dither Slope Time Control

The smart dither slope time control could be set by the $\mathrm{I}^{2} \mathrm{C}$, it is shown in the Table 16.
Table 16. Smart Dither Slop Time Control

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 08h | [6:4] | Smart Dither Slope Time Control | B000 | Slope time control <br> B000 : 7.8ms <br> B001 : 7.8ms <br> B010 : 15.625ms <br> B011 : 31.25ms <br> B100 : 62.5ms <br> B101 : 125ms <br> B110: 250ms <br> B111:500ms | -- | R/W |
| 09h | [4:4] | Smart Dither Enable | B1 | Smart dither enable <br> B0 : Disable <br> B1 : Enable | -- | R/W |

Smart dither slope time can be control by address 08h[6:4], there are many difference brightness times that adjust range from 7.8 ms to 500 ms . When the smart dither slope command is below B000, the slope time that is the dimming duty from $0 \%$ to $100 \%$ will be kept at 7.8 ms . This function can guarantee the highest of slope time is 500 ms . The resolution is shown in Table 17.

Table 17. Smart Dither Resolution

| Time (period T) <br> $\mathbf{1 0}$ bit mode | $\mathbf{0 T \sim 1 T}$ | $\mathbf{1 T \sim 2 T}$ | 2T~3T | $\mathbf{3 T \sim 4 T}$ | 4T~5T | 5T~6T | 6T~7T |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Dimming Duty (\%) | 0~ <br> $1.5625 \%$ | $1.5625 \%$ <br> $\sim 3.125 \%$ | $3.125 \%$ <br> $\sim 6.25 \%$ | $6.25 \%$ <br> $\sim 12.5 \%$ | $12.5 \%$ <br> $\sim 25 \%$ | 25\% <br> $\sim 50 \%$ | $50 \%$ <br> $\sim 100 \%$ |
| Resolution (step) | 1024 | 512 | 512 | 512 | 512 | 512 | 511 |
| Slope Time Setting <br> 7.8 ms | 1.114 ms | 1.114 ms | 1.114 ms | 1.114 ms | 1.114 ms | 1.114 ms | 1.114 ms |



Figure 10. LED Current (Dimming Up) vs. Time


Figure 11. LED Current (Dimming Down) vs. Time

## Dither Resolution Control

The dither resolution control could be set by the $\mathrm{I}^{2} \mathrm{C}$, it is shown in the Table 18.
Table 18. Dither Slop Time Control

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :--- | :---: | :--- | :---: | :---: |
| 09h | $[1: 0]$ | Dither <br> Resolution | B00 | Dither resolution <br> B00 0 bit <br> B01: 1 bit <br> B10 $: 2$ bit <br> B11: 3 bit | -- | R/W |
| 09 h | $[2: 2]$ | PWM Dither <br> Enable | B1 | PWM dither enable <br> B0 : Disable <br> B1 : Enable | -- | R/W |
| 09h | $[3: 3]$ | DC Dither <br> Enable | B1 | DC dither enable <br> B0 : Disable <br> B1 : Enable | -- | R/W |

Dither resolution can be control by address 09h[1:0], there are four kind of dither resolution that are from 0 bit to 3 bit. When the command is below B00, the dither resolution that is the dimming duty from $0 \%$ to $100 \%$ will be kept at 0 bit. This function can guarantee the highest of dither resolution is 3 bit. The dither resolution is shown in Table 19.

Table 19. Dither Resolution

| Dimming Duty (\%) <br> Resolution <br> (step) $\times$ Step Time $(\mu \mathrm{s})$ <br> 百 | $\begin{aligned} & 0 \sim \\ & 1.5625 \% \end{aligned}$ | $\begin{aligned} & 1.5625 \% ~ \\ & 3.125 \% \end{aligned}$ | $\begin{aligned} & 3.125 \% \\ & \sim 6.25 \% \end{aligned}$ | $\begin{aligned} & \text { 6.25\% } \\ & \sim 12.5 \% \end{aligned}$ | $\begin{aligned} & \text { 12.5\% } \\ & \sim 25 \% \end{aligned}$ | $\left\lvert\, \begin{aligned} & 25 \% \\ & \sim 50 \% \end{aligned}\right.$ | $\left\lvert\, \begin{aligned} & \text { 50\% } \\ & \sim 100 \% \end{aligned}\right.$ | Total Time ( $\mu \mathrm{s}$ ) (0\%~100\%) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| No DC dither 09h[3:3] = 0 | $16 \times 1 \mu \mathrm{~s}$ | $16 \times 1 \mu \mathrm{~s}$ | $32 \times 1 \mu \mathrm{~s}$ | $64 \times 1 \mu \mathrm{~s}$ | $128 \times 1 \mu \mathrm{~S}$ | $\begin{gathered} 256 \mathrm{x} \\ 1 \mu \mathrm{~S} \end{gathered}$ | $\begin{gathered} 511 \mathrm{x} \\ 1 \mu \mathrm{~s} \end{gathered}$ | 1023 $\mu \mathrm{s}$ |
| Obit dither | $32 \times 16 \mu s$ | $32 \times 16 \mu s$ | $64 \times 8 \mu \mathrm{~s}$ | $\begin{gathered} 128 \mathrm{x} \\ 4 \mu \mathrm{~S} \end{gathered}$ | $256 \times 2 \mu \mathrm{~s}$ | $\begin{gathered} 512 \mathrm{x} \\ 1 \mu \mathrm{~S} \end{gathered}$ | $\begin{gathered} 511 \mathrm{x} \\ 1 \mu \mathrm{~s} \end{gathered}$ | 3583 ${ }^{\text {s }}$ |
| 1bit dither | $64 \times 16 \mu s$ | $64 \times 16 \mu \mathrm{~s}$ | $128 \times 8 \mu \mathrm{~S}$ | $\begin{gathered} 256 x \\ 4 \mu \mathrm{~s} \end{gathered}$ | $512 \times 1 \mu \mathrm{~S}$ | $\begin{gathered} 512 x \\ 2 \mu \mathrm{~s} \end{gathered}$ | $\begin{gathered} 511 \mathrm{x} \\ 2 \mu \mathrm{~s} \end{gathered}$ | 7166 ${ }^{\text {s }}$ |
| 2bit dither | $128 \times 16 \mu \mathrm{~s}$ | $128 \times 16 \mu \mathrm{~s}$ | $256 \times 8 \mu \mathrm{~S}$ | $\begin{gathered} 512 \times \\ 4 \mu \mathrm{~S} \\ \hline \end{gathered}$ | $512 \times 4 \mu \mathrm{~S}$ | $\begin{gathered} 512 x \\ 4 \mu \mathrm{~S} \\ \hline \end{gathered}$ | $\begin{gathered} 511 \mathrm{x} \\ 4 \mu \mathrm{~s} \end{gathered}$ | $14332 \mu s$ |
| 3bit dither | $256 \times 16 \mu \mathrm{~S}$ | $256 \times 16 \mu \mathrm{~s}$ | $512 \times 8 \mu \mathrm{~S}$ | $\begin{gathered} 512 x \\ 8 \mu \mathrm{~s} \end{gathered}$ | $512 \times 8 \mu \mathrm{~s}$ | $\begin{gathered} 512 x \\ 8 \mu \mathrm{~S} \\ \hline \end{gathered}$ | $\begin{gathered} 511 \mathrm{x} \\ 8 \mu \mathrm{~s} \\ \hline \end{gathered}$ | 28664 $\mu \mathrm{s}$ |

Note : Fade Time is $1 \mu \mathrm{~s}(09 \mathrm{~h}[6: 5]=\mathrm{B01})$


Figuer 12. LED Current (Dimming Up) vs. Time


Figuer 13. LED Current (Dimming Down) vs. Time

26KHz Mode Division Frequency
The 26 KHz mode division frequency could be set by the $\mathrm{I}^{2} \mathrm{C}$, it is shown in the Table 20.
Table 20. 26KHz Mode Division Frequency

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| OAh | [7:5] | 26 KHz mode division frequency | B000 | PWMO frequency <br> B000: 26KHz <br> B001: $26 \mathrm{KHz} / 2$ <br> B010 : 26KHz/4 <br> B011 : $26 \mathrm{KHz/8}$ <br> B1xx : $26 \mathrm{KHz} / 16$ | -- | R/W |

The 26 kHz mode division frequency can be control by address $0 \mathrm{Ah}[7: 5]$, there are five kind of division frequency that contain $26 \mathrm{KHz}, 26 \mathrm{KHz} / 2,26 \mathrm{KHz} / 4,26 \mathrm{KHz} / 8$ and $26 \mathrm{KHz} / 16$. When the command is below B000, the PWMO frequency that is the 26 kHz mode will be kept at 26 KHz . This function can guarantee the most of division frequency is division 16 time.

## Control CLK PFM Function Enable

The CLK PFM function enable could be set by the $\mathrm{I}^{2} \mathrm{C}$, it is shown in the Table 21.
Table 21. Control CLK PFM Function Enable

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :--- | :---: | :--- | :---: | :---: |
| ODh | [7:7] | Control CLK <br> PFM function <br> enable | B0 | Control CLK PFM function <br> enable <br> B0: off <br> B1: on | -- | RMW |

The CLK PFM function enable can be control by address $0 \mathrm{Dh}[7: 7]$. If the bit equals to 0 , it means the boost switching frequency just depends on the switching frequency setting. Otherwise, if the bit equals to 1 , the boost switching frequency will be decreased, when the boost on time is lower than the minimum on time.

## LED Protection

RT8555 has LED protection for LED OVP level, LED unused. The LED protection could be set by the $I^{2} C$, it is shown in the Table 22.

Table 22. LED Protection

| Address | Bit | Name | Default Value | Description | Resolution | R/W |
| :---: | :---: | :--- | :---: | :--- | :---: | :---: |
| 0Eh | $[3: 2]$ | LED OVP <br> level | B00 | LED OVP level <br> B00 $: 2.1 \mathrm{~V}$ <br> B01:2.52V <br> B10 $: 2.8 \mathrm{~V}$ <br> B11:3.5V | -- | R/W |
| 0Eh | $[5: 5]$ | LED unused <br> check | B0 | LED unused check <br> B0 $:$ Disable <br> B1: Enable | -- | R/W |

## LED OVP level

The LED OVP level can be control by address 0Eh[3:2], there are four kind of LED OVP level that is from 2.1 V to 3.5 V . When the command is below B00, the LED OVP level that is the minimum FBx voltage up to the target level will be kept at 2.1 V . This function can guarantee the highest of LED OVP level is 3.5 V . When the minimum FBx voltage rises above the LED OVP level setting, the internal switch will be turned off. Once the minimum FBx voltage drops below the LED OVP level setting, the internal switch will be turned on again. The minimum FBx voltage can be clamped at the LED OVP level setting

## LED unused check

The LED unused check can be control by address $0 E h[5: 5]$. If the bit equals to 0 , it means the function disable. Otherwise, if the bit equals to 1 , the function enable, and the internal pulled current of the FBx pin will be turned off. The FBx pin should be connected to GND. This channel is detected as unused channel and latch. If the un-used channel is not connected to GND, and the FBx level is low to 100 mV . It means open LED protection.

## LED Connection

The RT8555 equips 6-CH LED drivers and each channel supports up to 10 LEDs. The LED strings are connected from the output of the boost converter to pin FBx ( $x=1$ to 6) respectively. If one of the current sink channels is not used, the FBx pin should be connected to GND. If the unused channel is not connected to GND, it will be considered that the LED string is opened; the channel will turn light when the LED string is recovering connected.

## Open LED Protection

If the FBx pin voltage is low to 0.1 V , the LED driver will judge the channel to be open. The FBx pin voltage will not be regulated and not latch, until the FBx pin is recovery connected, the FBx pin will normal work again. If all FBx pin are open (floating), the output voltage will be clamped to the setting voltage of OVP ( $\left.\mathrm{V}_{\text {OUT(OVP) }}\right)$.

## Over Temperature Protection

The RT8555 has over temperature protection function to prevent the IC from overheating due to excessive power dissipation. The OTP function will shutdown the IC when junction temperature exceeds $150^{\circ} \mathrm{C}$ (typ.). When junction temperature is cool down to $130^{\circ} \mathrm{C}$ (Totp_hys $=20^{\circ} \mathrm{C}$ ), the LED driver will return to normal work.

## Inductor Selection

The value of the inductance, L , can be approximated by the following equation, where the transition is from Discontinuous Conduction Mode (DCM) to Continuous Conduction Mode (CCM) :
$\mathrm{L}=\frac{\mathrm{D} \times(1-\mathrm{D})^{2} \times \mathrm{V}_{\mathrm{OUT}}}{2 \times \mathrm{f}_{\mathrm{OSC}} \times \mathrm{I}_{\mathrm{OUT}}}$
The duty cycle, D , can be calculated as the following equation :
$\mathrm{D}=\frac{\mathrm{V}_{\mathrm{OUT}}-\mathrm{V}_{\mathrm{IN}}}{\mathrm{V}_{\text {OUT }}}$
Where $\mathrm{V}_{\text {OUt }}$ is the maximum output voltage, $\mathrm{V}_{\text {IN }}$ is the minimum input voltage, fosc is the operating frequency, and lout is the sum of current from all LED strings. The boost converter operates in DCM over the entire input voltage range when the inductor value is less than this value, L. With an inductance greater than L, the converter operates in CCM at the minimum input voltage and may be discontinuous at higher voltages.

The inductor must be selected with a saturated current rating that is greater than the peak current as provided by the following equation :
$\mathrm{I}_{\text {PEAK }}=\frac{\mathrm{V}_{\text {OUT }} \times \mathrm{I}_{\text {OUT }}}{\eta \times \mathrm{V}_{\text {IN }}}+\frac{\mathrm{V}_{\text {IN }} \times \mathrm{D} \times \mathrm{T}_{\mathrm{OSC}}}{2 \times \mathrm{L}}$
where $\eta$ is the efficiency of the power converter.

## Diode Selection

Schottky diodes are recommended for most applications because of their fast recovery time and low forward voltage. Power dissipation, reverse voltage rating, and pulsating peak current are important parameters for consideration when making a Schottky diode selection. Make sure that the diode's peak current rating exceeds I IPEAK and reverse voltage rating exceeds the maximum output voltage.

## Input Capacitor Selection

The ceramic capacitors are recommended for input capacitor applications. Low ESR will effectively reduce the input voltage ripple caused by switching operation. Two $10 \mu \mathrm{~F} / 25 \mathrm{~V}$ capacitors are sufficient for most applications. Nevertheless, this value can be decreased for lower output current requirement. Another consideration is the voltage rating of the input capacitor must be greater than the maximum input voltage.

## Output Capacitor Selection

Output ripple voltage is an important index for estimating the performance. This portion consists of two parts, one is the ESR voltage of output capacitor, another part is formed by charging and discharging process of output capacitor. Refer to Figure 14 , evaluate $\Delta \mathrm{V}_{\text {OUT1 }}$ by ideal energy equalization. According to the definition of Q , the $Q$ value can be calculated as following equation :

$$
\begin{aligned}
\mathrm{Q}= & \frac{1}{2} \times\left[\left(\mathrm{l}_{\mathrm{IN}}-\frac{1}{2} \Delta \mathrm{I}_{\mathrm{L}}-\mathrm{l}_{\mathrm{OUT}}\right)+\left(\mathrm{l}_{\mathrm{IN}}-\frac{1}{2} \Delta \mathrm{I}_{\mathrm{L}}-\mathrm{l}_{\mathrm{OUT}}\right)\right] \\
& \times \frac{\mathrm{V}_{\text {IN }}}{\mathrm{V}_{\mathrm{OUT}}} \times \frac{1}{\mathrm{f}_{\mathrm{OSC}}}=\mathrm{C}_{\text {OUT }} \times \Delta \mathrm{V}_{\text {OUT1 }}
\end{aligned}
$$

where $f_{\text {Osc }}$ is the switching frequency, and $\Delta \mathrm{I}_{\mathrm{L}}$ is the inductor ripple current. Move Cout to the left side to estimate the value of $\Delta \mathrm{V}_{\text {OUT1 }}$ as the following equation :

$$
\Delta \mathrm{V}_{\mathrm{OUT} 1}=\frac{\mathrm{D} \times \mathrm{I}_{\mathrm{OUT}}}{\eta \times \mathrm{C}_{\mathrm{OUT}} \times \mathrm{f}_{\mathrm{OSC}}}
$$

Then, take the ESR into consideration, the ESR voltage can be determined as the following equation :
$\Delta \mathrm{V}_{\mathrm{ESR}}=\left(\frac{\mathrm{l}_{\mathrm{OUT}}}{1-\mathrm{D}}+\frac{\mathrm{V}_{\mathrm{IN}} \times \mathrm{D} \times \mathrm{T}_{\mathrm{OSC}}}{2 \mathrm{~L}}\right) \times \mathrm{R}_{\mathrm{ESR}}$
Finally, the total output ripple $\Delta \mathrm{V}_{\text {OUT }}$ is combined from the $\Delta \mathrm{V}_{\text {OUT1 }}$ and $\Delta \mathrm{V}_{\text {ESR }}$. In the general application, the output capacitor is recommended to use a $4.7 \mu \mathrm{~F} / 50 \mathrm{~V}$ electrolytic capacitor.


Figure 14. The Output Ripple Voltage without the Contribution of ESR

## Thermal Considerations

For continuous operation, do not exceed absolute maximum junction temperature. The maximum power dissipation depends on the thermal resistance of the IC package, PCB layout, rate of surrounding airflow, and difference between junction and ambient temperature. The maximum power dissipation can be calculated by the following formula :
$P_{D(\text { MAX })}=\left(T_{J(M A X)}-T_{A}\right) / \theta_{J A}$
where $T_{J(M A X)}$ is the maximum junction temperature, $T_{A}$ is the ambient temperature, and $\theta_{\mathrm{JA}}$ is the junction to ambient thermal resistance.

For recommended operating condition specifications, the maximum junction temperature is $125^{\circ} \mathrm{C}$. The junction to ambient thermal resistance, $\theta_{\mathrm{JA}}$, is layout dependent. For WL-CSP-20B $1.65 \times 2.05$ (BSC) package, the thermal resistance, $\theta_{\mathrm{JA}}$, is $36.7^{\circ} \mathrm{C} / \mathrm{W}$ on a standard JEDEC 51-7 four-layer thermal test board. The maximum power dissipation at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ can be calculated by the following formula :
$P_{D(\operatorname{MAX})}=\left(125^{\circ} \mathrm{C}-25^{\circ} \mathrm{C}\right) /\left(36.7^{\circ} \mathrm{C} / \mathrm{W}\right)=2.72 \mathrm{~W}$ for WL-CSP-20B 1.65x2.05 (BSC) package

The maximum power dissipation depends on the operating ambient temperature for fixed $\mathrm{T}_{\mathrm{J}(\mathrm{MAX})}$ and thermal resistance, $\theta_{\mathrm{JA}}$. The derating curve in Figure 15 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.


Figure 15. Derating Curve of Maximum Power Dissipation

## Layout Consideration

- For good regulation, place the power components as close to the IC as possible. The traces should be wide and short, especially for the high current output loop.
- The input and output bypass capacitor should be placed as close to the IC as possible and connected to the ground plane of the PCB.
- Minimize the size of the L nodes and keep traces wide and short. Care should be taken to avoid running traces that carry any noise-sensitive signals near LX or highcurrent traces.
- Separate power ground (PGND) and ground (GND).Connect the GND and the PGND islands at a single end. Make sure that there are no other connections between these separate ground planes.
- Connect the exposed pad to a strong ground plane for maximum thermal dissipation.


Figure 16. PCB Layout Guide

## Outline Dimension



| Symbol | Dimensions In Millimeters |  | Dimensions In Inches |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Min. | Max. | Min. | Max. |
| A | 0.500 | 0.600 | 0.020 | 0.024 |
| A1 | 0.170 | 0.230 | 0.007 | 0.009 |
| b | 0.220 | 0.280 | 0.009 | 0.011 |
| D | 2.000 | 2.100 | 0.079 | 0.083 |
| D1 | 1.600 |  | 0.063 |  |
| E | 1.600 | 1.700 | 0.063 | 0.067 |
| E1 | 1.200 |  | 0.047 |  |
| e 0.400 | 0.016 |  |  |  |

20B WL-CSP 1.65x2.05 Package (BSC)

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