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[VWO85-08IO1](#)

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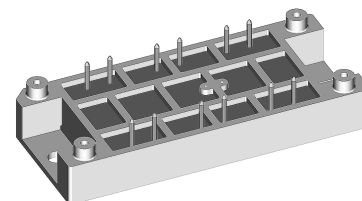
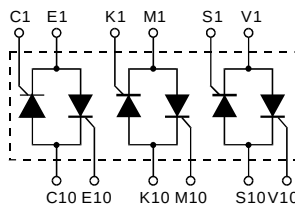
Three Phase AC Controller Modules

$$I_{RMS} = 3 \times 83 \text{ A}$$

$$V_{RRM} = 800\text{-}1600 \text{ V}$$

Preliminary data

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
800	800	VWO 85-08io1
1200	1200	VWO 85-12io1
1400	1400	VWO 85-14io1
1600	1600	VWO 85-16io1



Symbol	Test Conditions	Max. Ratings per phase	
I_{RMS}	$T_C = 85^\circ\text{C}$, 50 - 400 Hz (per phase)	59	A
I_{RMS}	$T_C = 85^\circ\text{C}$, 50 - 400 Hz (per phase) for 10 sec.	83	A
I_{TAVM}	$T_C = 85^\circ\text{C}$; (180° sine)	27	A
I_{TSM}	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine	520 A
		$t = 8.3 \text{ ms}$ (60 Hz), sine	560 A
	$T_{VJ} = 125^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine	470 A
		$t = 8.3 \text{ ms}$ (60 Hz), sine	510 A
I^2t	$T_{VJ} = 45^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine	1350 A ² s
		$t = 8.3 \text{ ms}$ (60 Hz), sine	1320 A ² s
	$T_{VJ} = 125^\circ\text{C}$; $V_R = 0$	$t = 10 \text{ ms}$ (50 Hz), sine	1100 A ² s
		$t = 8.3 \text{ ms}$ (60 Hz), sine	1090 A ² s
$(di/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$; $f = 50 \text{ Hz}$, $t_p = 200 \mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.45 \text{ A}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$	repetitive, $I_T = 45 \text{ A}$	150 A/ μs
		non repetitive, $I_T = I_{TAVM}$	500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$; $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = 2/3 V_{DRM}$	1000 V/ μs
P_{GM}	$T_{VJ} = 125^\circ\text{C}$	$t_p = 30 \mu\text{s}$	10 W
	$I_T = I_{TAVM}$	$t_p = 300 \mu\text{s}$	5 W
P_{GAVM}			0.5 W
V_{RGM}			10 V
T_{VJ}			-40...+125 °C
T_{VJM}	for 10 sec.		150 °C
T_{stg}			-40...+125 °C
V_{ISOL}	50/60 Hz, RMS	$t = 1 \text{ min}$	3000 V~
	$I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ s}$	3600 V~
M_d	Mounting torque (M5)		2-2.5 Nm.
			18-22 lb.in.
Weight	typ.		80 g

Features

- Thyristor controller for AC (circuit W3C acc.to IEC) for mains frequency
- Package with DCB base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- UL applied

Applications

- Switching and control of three phase AC circuits
- Softstart AC motor controller
- Solid state switches
- Light and temperature control

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density

Symbol	Test Conditions	Characteristic Values	
I_D, I_R	$T_{VJ} = 125^\circ\text{C}; V_R = V_{RRM}; V_D = V_{DRM}$	$\leq$	5 mA
V_T	$I_T = 85 \text{ A}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.67 V
V_{T0}	For power-loss calculations only	0.85	V
r_T		11	mΩ
V_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	1.5 V
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	1.6 V
I_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	$\leq$	100 mA
	$T_{VJ} = -40^\circ\text{C}$	$\leq$	200 mA
V_{GD}	$T_{VJ} = 125^\circ\text{C}; V_D = 2/3 V_{DRM}$	$\leq$	0.2 V
I_{GD}		$\leq$	5 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	$\leq$	450 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	$\leq$	200 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	$\leq$	2 μs
t_q	$T_{VJ} = 125^\circ\text{C}; I_T = 20 \text{ A}; t_p = 200 \mu\text{s}; di/dt = -10 \text{ A}/\mu\text{s}$ typ. $V_R = 100 \text{ V}; dv/dt = 15 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$	150	μs
R_{thJC}	per thyristor	0.92	K/W
	per module	0.154	K/W
R_{thJK}	per thyristor	1.22	K/W
	per module	0.204	K/W
d_s	Creeping distance on surface	12.7	mm
d_A	Creepage distance in air	9.4	mm
a	Max. allowable acceleration	50	m/s ²

Dimensions in mm (1 mm = 0.0394")

