NHD-0216K1Z-FL-YBW

Character Liquid Crystal Display Module

NHD-	Newhaven Display
0216-	2 Lines x 16 Characters
K1Z-	Model
F-	Transflective
L-	Yellow/Green LED Backlight
Y-	STN- Yellow/Green
B-	6:00 Optimal View
W-	Wide Temperature
	RoHS Compliant

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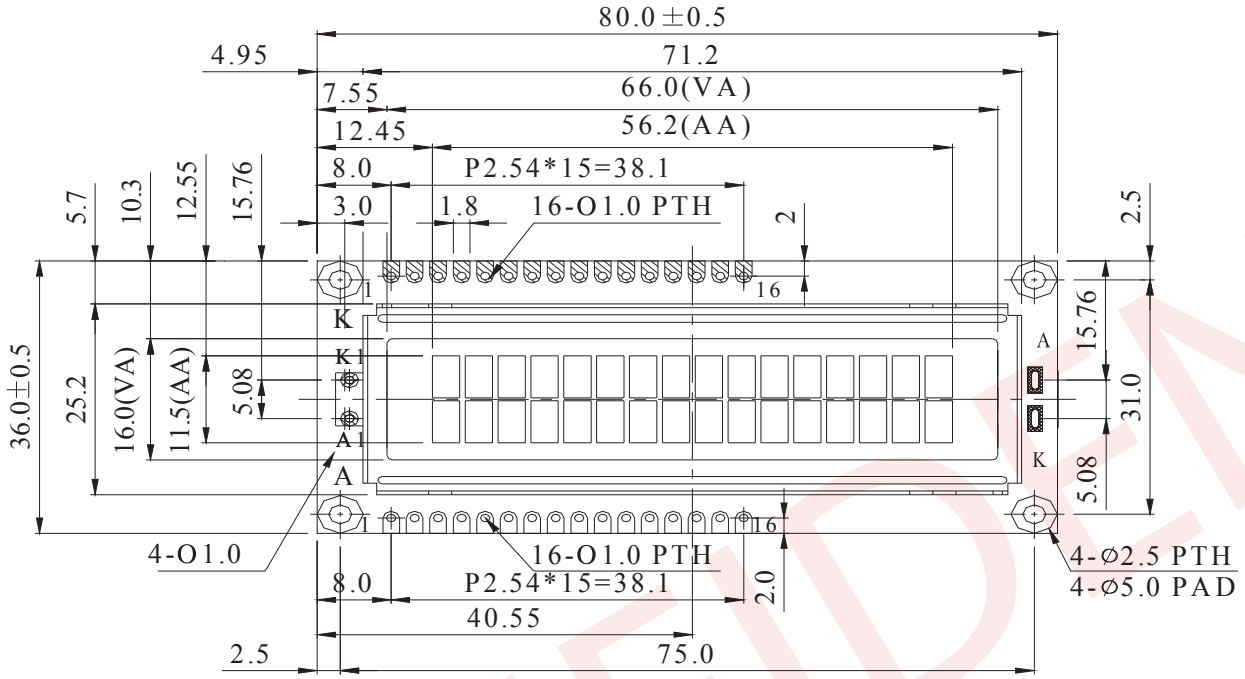
Document Revision History

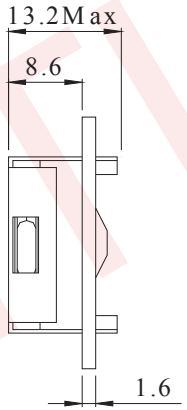
Revision	Date	Description	Changed by
0	**10/5/2007**	**Initial Release**	**-**
1	**10/9/2009**	**User Guide Reformat**	**BE**
2	**10/23/2009**	**Block Diagram Revision**	**BE**
3	**12/8/2009**	**Pin description/backlight updated**	**BE**
4	**1/7/2010**	**Optical updated**	**BE**
5	**1/6/2011**	**Alternate controller information updated**	**AK**
6	**4/6/2011**	**Mechanical drawing updated**	**AK**
7	**4/8/2011**	**Electrical/Optical characteristics & Pin Description updated**	**AK**
8	**12/15/15**	**Electrical Characteristics updated, Timing characteristics added**	**SB**

Functions and Features

- **2 lines x 16 characters**
- **Built-in controller (ST7066U)**
- **+5.0V Power Supply**
- **1/16 duty, 1/5 bias**
- **RoHS compliant**

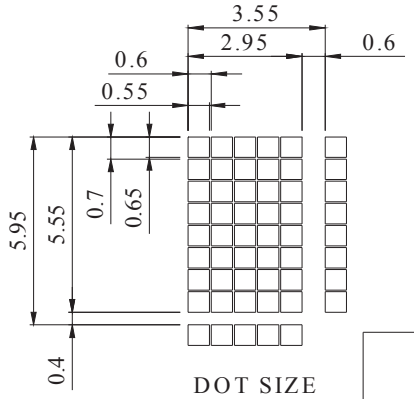
Mechanical Drawing





LED B/L

PIN NO.	SYMBOL
1	Vss
2	Vdd
3	Vo
4	RS
5	R/$\overline{W}$
6	E
7	DB0
8	DB1
9	DB2
10	DB3
11	DB4
12	DB5
13	DB6
14	DB7
15	A
16	K



DOT SIZE

NOTES:
1. Driving Mode: Duty 1/16, Bias 1/5, VLCD = 3.7V, VDD = 5V
2. Optimal Viewing Direction: 6:00
3. Display Mode: STN / Positive / Yellow-Green
4. Controller IC: ST7066U
5. Backlight: Array / Yellow-Green

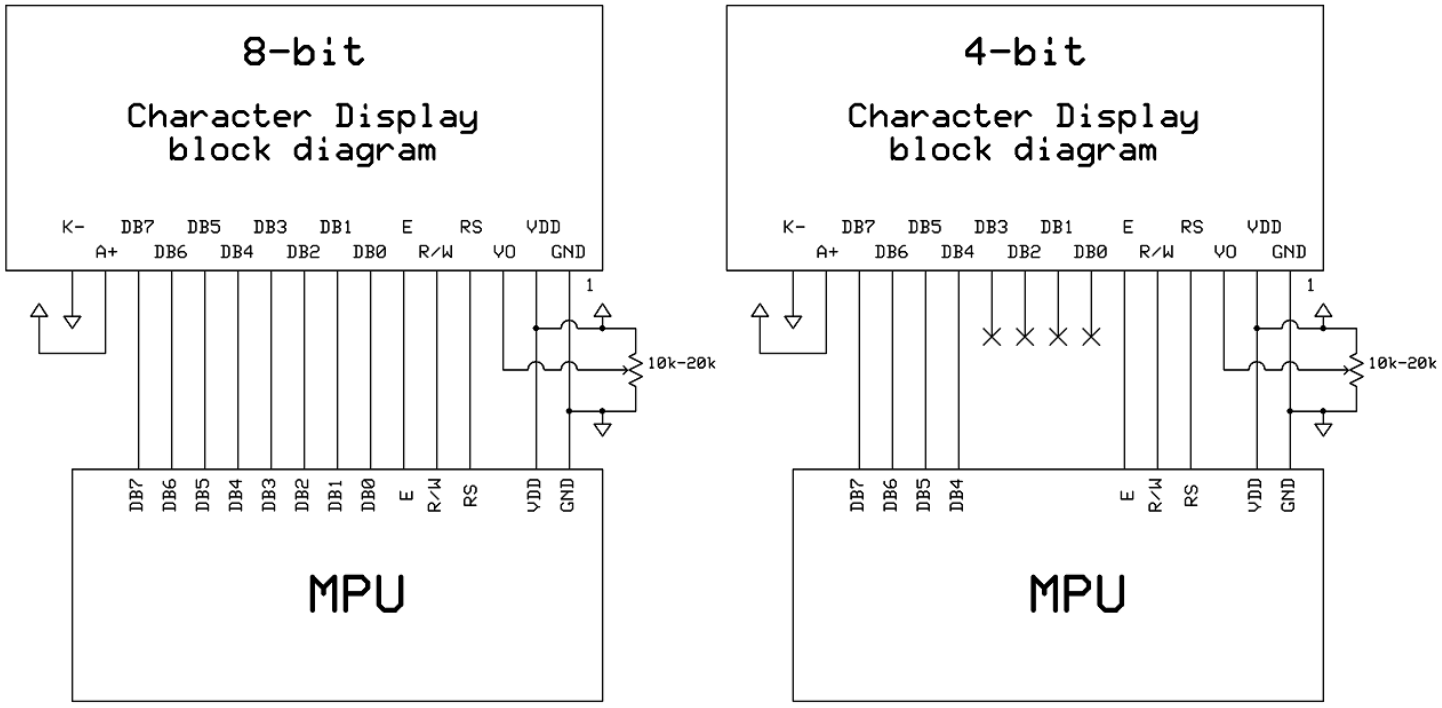
Rev	Description	Date

	Date	
	12/15/15	NEWHAVEN DISPLAY INTERNATIONAL
Gen. Tolerance ±0.3mm	Unit mm	Model: NHD-0216K1Z-FL-YBW

Pin Description and Wiring Diagram

Pin No.	Symbol	External Connection	Function Description
1	VSS	Power Supply	Ground
2	VDD	Power Supply	Supply Voltage for logic (+5.0V)
3	V0	Adj Power Supply	Supply Voltage for contrast (approx. 1.3V)
4	RS	MPU	Register Select signal. RS=0: Command, RS=1: Data
5	R/W	MPU	Read/Write select signal, R/W=1: Read R/W: =0: Write
6	E	MPU	Operation Enable signal. Falling edge triggered.
7-10	DB0 – DB3	MPU	Four low order bi-directional three-state data bus lines. These four are not used during 4-bit operation.
11-14	DB4 – DB7	MPU	Four high order bi-directional three-state data bus lines.
15	LED+	Power Supply	Backlight Anode(+5.0V via on-board resistor)
16	LED-	Power Supply	Backlight Cathode (Ground)

Recommended LCD connector: 2.54mm pitch pins
Backlight connector: --- **Mates with:** ---



Electrical Characteristics

Item	Symbol	Condition	Min.	Typ.	Max.	Unit
Operating Temperature Range	Top	Absolute Max	-20	-	+70	ºC
Storage Temperature Range	Tst	Absolute Max	-30	-	+80	ºC
Supply Voltage	VDD	-	4.5	5.0	5.5	V
Supply Current	IDD	Ta=25°C, VDD=5.0V	1.0	1.2	1.5	mA
Supply for LCD (contrast)	VDD-V0	Ta=25°C	3.6	3.7	3.8	V
"H" Level input	Vih	-	0.7*VDD	-	VDD	V
"L" Level input	Vil	-	VSS	-	0.6	V
"H" Level output	Voh	-	3.9	-	VDD	V
"L" Level output	Vol	-	VSS	-	0.4	V
Backlight Supply Voltage	Vled	-	4.9	5.0	5.1	V
Backlight Supply Current	Iled	Vled=5.0V	117	130	156	mA

Optical Characteristics

Item		Symbol	Condition	Min.	Typ.	Max.	Unit
Optimal Viewing Angles	Top	φY+	Cr ≥ 2	-	20	-	º
	Bottom	φY-		-	40	-	º
	Left	θX-		-	30	-	º
	Right	θX+		-	30	-	º
Contrast Ratio		Cr	-	-	3	-	-
Response Time	Rise	Tr	-	-	150	200	ms
	Fall	Tf	-	-	150	200	ms

Controller Information

Built-in ST7066U Controller.
Please download specification at http://www.newhavendisplay.com/app_notes/ST7066U.pdf

DDRAM Address

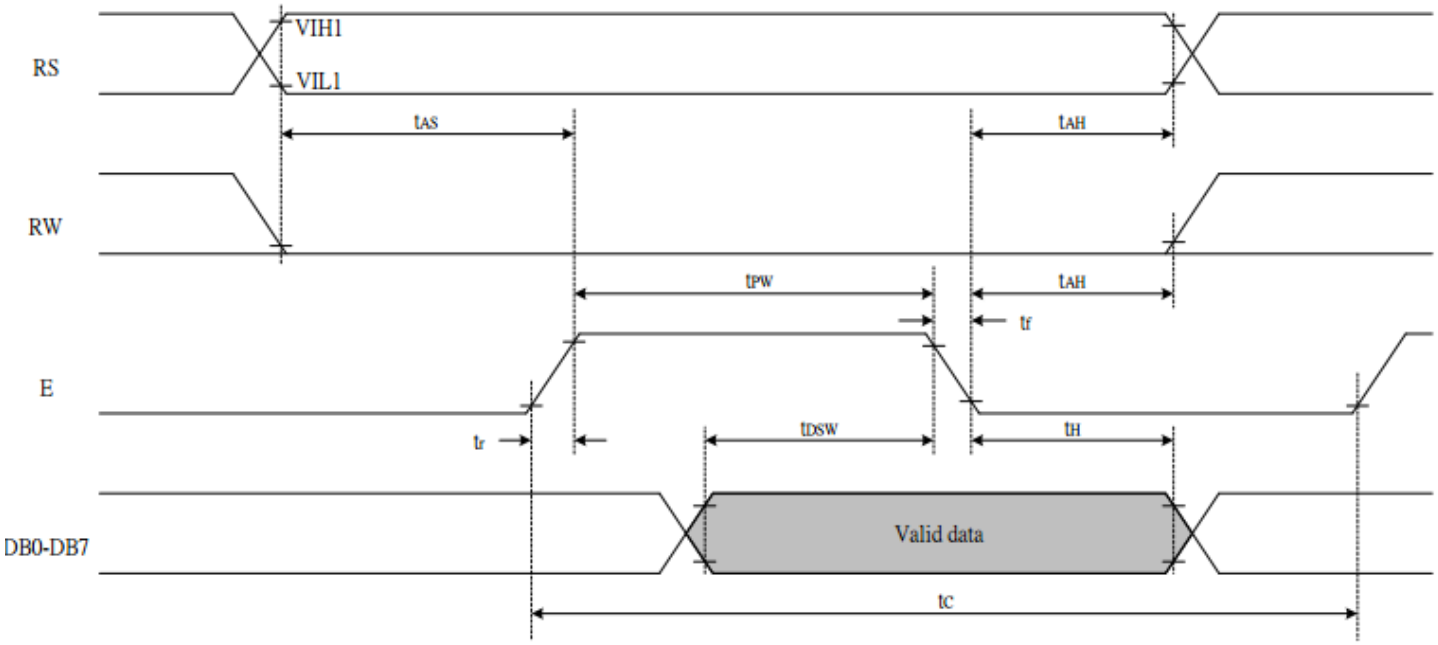
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F
40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F

Table of Commands

Instruction	Instruction code										Description	Execution time (fosc= 270 KHZ
	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0		
Clear Display	0	0	0	0	0	0	0	0	0	1	Write “20H” to DDRAM and set DDRAM address to “00H” from AC	1.52ms
Return Home	0	0	0	0	0	0	0	0	1	-	Set DDRAM Address to “00H” from AC and return cursor to its original position if shifted. The contents of DDRAM are not changed.	1.52ms
Entry mode Set	0	0	0	0	0	0	0	1	I/D	SH	Sets cursor move direction and specifies display shift. These parameters are performed during data write and read.	37μs
Display ON/ OFF control	0	0	0	0	0	0	1	D	C	B	D=1: Entire display on C=1: Cursor on B=1: Blinking cursor on	37μs
Cursor or Display shift	0	0	0	0	0	1	S/C	R/L	-	-	Sets cursor moving and display shift control bit, and the direction without changing DDRAM data.	37μs
Function set	0	0	0	0	1	DL	N	F	-	-	DL: Interface data is 8/4 bits N: Number of lines is 2/1 F: Font size is 5x11/5x8	37μs
Set CGRAM Address	0	0	0	1	AC5	AC4	AC3	AC2	AC1	AC0	Set CGRAM address in address counter	37μs
Set DDRAM Address	0	0	1	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Set DDRAM address in address counter.	37μs
Read busy Flag and Address	0	1	BF	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Whether during internal operation or not can be known by reading BF. The contents of address counter can also be read.	0s
Write data To Address	1	0	D7	D6	D5	D4	D3	D2	D1	D0	Write data into internal RAM (DDRAM/CGRAM).	37μs
Read data From RAM	1	1	D7	D6	D5	D4	D3	D2	D1	D0	Read data from internal RAM (DDRAM/CGRAM).	37μs

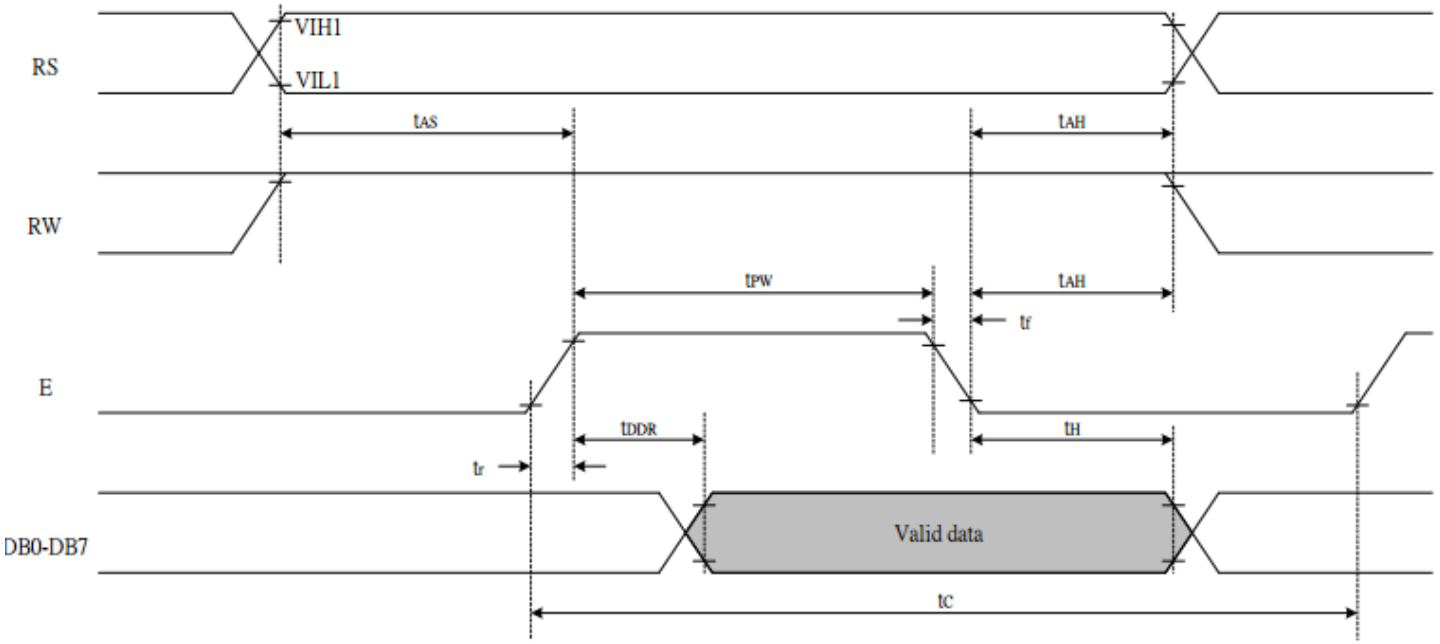
Timing Characteristics

Writing data from MPU to ST7066U



Write Mode (Writing data from MPU to ST7066U)						
T_C	Enable Cycle Time	Pin E	1200	-	-	ns
T_{PW}	Enable Pulse Width	Pin E	140	-	-	ns
T_R, T_F	Enable Rise/Fall Time	Pin E	-	-	25	ns
T_{AS}	Address Setup Time	Pins: RS,RW,E	0	-	-	ns
T_{AH}	Address Hold Time	Pins: RS,RW,E	10	-	-	ns
T_{DSW}	Data Setup Time	Pins: DB0 - DB7	40	-	-	ns
T_H	Data Hold Time	Pins: DB0 - DB7	10	-	-	ns

Reading data from ST7066U to MPU



Read Mode (Reading Data from ST7066U to MPU)						
T_C	Enable Cycle Time	Pin E	1200	-	-	ns
T_{PW}	Enable Pulse Width	Pin E	140	-	-	ns
T_R, T_F	Enable Rise/Fall Time	Pin E	-	-	25	ns
T_{AS}	Address Setup Time	Pins: RS,RW,E	0	-	-	ns
T_{AH}	Address Hold Time	Pins: RS,RW,E	10	-	-	ns
T_{DDR}	Data Setup Time	Pins: DB0 - DB7	-	-	100	ns
T_H	Data Hold Time	Pins: DB0 - DB7	10	-	-	ns

Built-in Font Table

Example Initialization Program

```
8-bit Initialization:
/*********************************************************/
void command(char i)
{
      P1 = i;                       //put data on output Port
      D_I =0;                       //D/I=LOW : send instruction
      R_W =0;                       //R/W=LOW : Write
      E  = 1;
      Delay(1);                     //enable pulse width  >= 300ns
        E  = 0;                     //Clock enable: falling edge
}
/*********************************************************/
void write(char i)
{
      P1 = i;                       //put data on output Port
      D_I =1;                       //D/I=HIGH: send data
      R_W =0;                       //R/W=LOW : Write
      E  = 1;
      Delay(1);                     //enable pulse width  >= 300ns
      E  = 0;                       //Clock enable: falling edge
}
/*********************************************************/
void init()
{
      E = 0;
      Delay(100);                   //Wait >40 msec after power is applied
      command(0x30);                //command 0x30 = Wake up
      Delay(30);                    //must wait 5ms, busy flag not available
      command(0x30);                //command 0x30 = Wake up #2
      Delay(10);                    //must wait 160us, busy flag not available
      command(0x30);                //command 0x30 = Wake up #3
      Delay(10);                    //must wait 160us, busy flag not available
      command(0x38);                //Function set: 8-bit/2-line
      command(0x10);                //Set cursor
      command(0x0c);                //Display ON; Cursor ON
      command(0x06);                //Entry mode set
}
/*********************************************************/
```

4-bit Initialization:

```
/*********************************************************/
void command(char i)
{
      P1 = i;                         //put data on output Port
      D_I =0;                         //D/I=LOW : send instruction
      R_W =0;                         //R/W=LOW : Write
      Nybble();                       //Send lower 4 bits
      i = i<<4;                       //Shift over by 4 bits
      P1 = i;                         //put data on output Port
      Nybble();                       //Send upper 4 bits
}
/*********************************************************/
void write(char i)
{
      P1 = i;                         //put data on output Port
      D_I =1;                         //D/I=HIGH : send data
      R_W =0;                         //R/W=LOW : Write
      Nybble();                       //Clock lower 4 bits
      i = i<<4;                       //Shift over by 4 bits
      P1 = i;                         //put data on output Port
      Nybble();                       //Clock upper 4 bits
}
/*********************************************************/
void Nybble()
{
      E = 1;
      Delay(1);                       //enable pulse width  >= 300ns
      E = 0;                          //Clock enable: falling edge
}
/*********************************************************/
void init()
{
      P1 = 0;
      P3 = 0;
      Delay(100);                     //Wait >40 msec after power is applied
      P1 = 0x30;                      //put 0x30 on the output port
      Delay(30);                      //must wait 5ms, busy flag not available
      Nybble();                       //command 0x30 = Wake up
      Delay(10);                      //must wait 160us, busy flag not available
      Nybble();                       //command 0x30 = Wake up #2
      Delay(10);                      //must wait 160us, busy flag not available
      Nybble();                       //command 0x30 = Wake up #3
      Delay(10);                      //can check busy flag now instead of delay
      P1= 0x20;                       //put 0x20 on the output port
      Nybble();                       //Function set: 4-bit interface
      command(0x28);                  //Function set: 4-bit/2-line
      command(0x10);                  //Set cursor
      command(0x0F);                  //Display ON; Blinking cursor
      command(0x06);                  //Entry Mode set
}
/*********************************************************/
```

Quality Information

Test Item	Content of Test	Test Condition	Note
High Temperature storage	Endurance test applying the high storage temperature for a long time.	+80°C , 48hrs	2
Low Temperature storage	Endurance test applying the low storage temperature for a long time.	-30°C , 48hrs	1,2
High Temperature Operation	Endurance test applying the electric stress (voltage & current) and the high thermal stress for a long time.	+70°C 48hrs	2
Low Temperature Operation	Endurance test applying the electric stress (voltage & current) and the low thermal stress for a long time.	-20°C , 48hrs	1,2
High Temperature / Humidity Operation	Endurance test applying the electric stress (voltage & current) and the high thermal with high humidity stress for a long time.	+40°C , 90% RH , 48hrs	1,2
Thermal Shock resistance	Endurance test applying the electric stress (voltage & current) during a cycle of low and high thermal stress.	0°C,30min -> 25°C,5min -> 50°C,30min = 1 cycle 10 cycles	
Vibration test	Endurance test applying vibration to simulate transportation and use.	10-55Hz , 15mm amplitude. 60 sec in each of 3 directions X,Y,Z For 15 minutes	3
Static electricity test	Endurance test applying electric static discharge.	VS=800V, RS=1.5kΩ, CS=100pF One time	

Note 1: No condensation to be observed.
Note 2: Conducted after 4 hours of storage at 25°C, 0%RH.
Note 3: Test performed on product itself, not inside a container.

Precautions for using LCDs/LCMs

See Precautions at www.newhavendisplay.com/specs/precautions.pdf

Warranty Information and Terms & Conditions

http://www.newhavendisplay.com/index.php?main_page=terms