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ON Semiconductor CAT28LV256G25

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ON Semiconductor[®]



CAT28LV256

256K-Bit CMOS PARALLEL EEPROM



FEATURES

- 3.0V to 3.6V Supply
- Read Access Times: 200/250/300 ns
- Low Power CMOS Dissipation:
 - Active: 15 mA Max.
 - Standby: 150 μA Max.
- Simple Write Operation:
 - On-Chip Address and Data Latches
 - Self-Timed Write Cycle with Auto-Clear
- Fast Write Cycle Time:
 - 10ms Max.
- Commercial, Industrial and Automotive Temperature Ranges

- CMOS and TTL Compatible I/O
- Automatic Page Write Operation:
 1 to 64 Bytes in 10ms
 - Page Load Timer
- End of Write Detection:
 - Toggle Bit
 - DATA Polling
- Hardware and Software Write Protection
- 100,000 Program/Erase Cycles
- 100 Year Data Retention

DESCRIPTION

The CAT28LV256 is a fast, low power, low voltage CMOS Parallel E²PROM organized as 32K x 8-bits. It requires a simple interface for in-system programming. On-chip address and data latches, self-timed write cycle with auto-clear and V_{CC} power up/down write protection eliminate additional timing and protection hardware. DATA Polling and Toggle status bits signal the start and end of the self-timed write cycle. Additionally, the CAT28LV256 features hardware and software write protection.

The CAT28LV256 is manufactured using Catalyst's advanced CMOS floating gate technology. It is designed to endure 100,000 program/erase cycles and has a data retention of 100 years. The device is available in JEDEC–approved 28-pin DIP, 28-pin TSOP or 32-pin PLCC packages.

BLOCK DIAGRAM





CAT28LV256

PIN CONFIGURATION



TSOP Top View (8mm X 13.4mm) (H)

	10	28	□ A ₁₀
A ₁₁ 🖵	2	27	
Ag 🖂	3	26	□ I/O ₇
A8 💷	4	25	⊥ I/O ₆
A ₁₃	5	24	⊥ I/O ₅
WE 🗆	6	23	⊥ I/O4
Vсс □□	7	22	⊥ I/O3
A14 🖵	8	21	III GND
A12 🖵	9	20	⊥ I/O ₂
A7 🖵	10	19	⊥ I/O ₁
A6 💷	11	18	□ I/O ₀
A5 💷	12	17	$\square A_0$
A4 💷	13	16	$\square A_1$
A3 🖵	14	15	$\square A_2$

PIN FUNCTIONS

Pin Name	Function	Pin Name	Function
A ₀ -A ₁₄	Address Inputs	WE	Write Enable
I/O ₀ —I/O ₇	Data Inputs/Outputs	V _{CC}	3.0 to 3.6 V Supply
CE	Chip Enable	V _{SS}	Ground
ŌĒ	Output Enable	NC	No Connect

Doc. No. MD-1071, Rev. E



ABSOLUTE MAXIMUM RATINGS*

Temperature Under Bias –55°C to +125°C
Storage Temperature –65°C to +150°C
Voltage on Any Pin with Respect to Ground ⁽²⁾ –2.0V to +V _{CC} + 2.0V
V _{CC} with Respect to Ground $-2.0V$ to $+7.0V$ Package Power Dissipation Capability (Ta = 25° C) 1.0W
Lead Soldering Temperature (10 secs)
Output Short Circuit Current ⁽³⁾ 100 mA

*COMMENT

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions outside of those listed in the operational sections of this specification is not implied. Exposure to any absolute maximum rating for extended periods may affect device performance and reliability.

RELIABILITY CHARACTERISTICS

Symbol	Parameter	Min.	Max.	Units	Test Method
N _{END} ⁽¹⁾	Endurance	100,000		Cycles/Byte	MIL-STD-883, Test Method 1033
T _{DR} ⁽¹⁾	Data Retention	100		Years	MIL-STD-883, Test Method 1008
VZAP ⁽¹⁾	ESD Susceptibility	2000		Volts	MIL-STD-883, Test Method 3015
ILTH ⁽¹⁾⁽⁴⁾	Latch-Up	100		mA	JEDEC Standard 17

CAPACITANCE $T_A = 25^{\circ}C$, f = 1.0 MHz

Symbol	Test	Max.	Units	Conditions
C _{I/O} ⁽¹⁾	Input/Output Capacitance	10	pF	$V_{I/O} = 0V$
C _{IN} ⁽¹⁾	Input Capacitance	6	pF	$V_{IN} = 0V$

MODE SELECTION

Mode	CE	WE	OE	I/O	Power
Read	L	Н	L	Dout	ACTIVE
Byte Write (WE Controlled)	L	\sim	Н	D _{IN}	ACTIVE
Byte Write (CE Controlled)		L	Н	DIN	ACTIVE
Standby, and Write Inhibit	Н	X	X	High-Z	STANDBY
Read and Write Inhibit	Х	Н	Н	High-Z	ACTIVE

Note:

(1) This parameter is tested initially and after a design or process change that affects the parameter.

(2) The minimum DC input voltage is -0.5V. During transitions, inputs may undershoot to -2.0V for periods of less than 20 ns. Maximum DC voltage on output pins is V_{CC} +0.5V, which may overshoot to V_{CC} +2.0V for periods of less than 20 ns.

(3) Output shorted for no more than one second. No more than one output shorted at a time.

(4) Latch-up protection is provided for stresses up to 100mA on address and data pins from -1V to V_{CC} +1V.



D.C. OPERATING CHARACTERISTICS

 V_{CC} = 3.0V to 3.6V, unless otherwise specified

		Limits				
Symbol	Parameter	Min.	Тур.	Max.	Units	Test Conditions
Icc	V _{CC} Current (Operating, TTL)			15	mA	$\overline{CE} = \overline{OE} = V_{IL},$ f = 1/t _{RC} min, All I/O's Open
I _{SBC} ⁽²⁾	V _{CC} Current (Standby, CMOS)			150	μA	CE = V _{IHC} , All I/O's Open
ILI	Input Leakage Current	-1		1	μA	$V_{IN} = GND$ to V_{CC}
ILO	Output Leakage Current	-5		5	μA	$\frac{V_{OUT} = GND \text{ to } V_{CC},}{\overline{CE}} = V_{IH}$
VIH ⁽²⁾	High Level Input Voltage	2		Vcc +0.3	V	
VIL	Low Level Input Voltage	-0.3		0.6	V	
Voн	High Level Output Voltage	2			V	I _{OH} = -100μA
Vol	Low Level Output Voltage			0.3	V	I _{OL} = 1.0mA
Vwi	Write Inhibit Voltage	2			V	

A.C. CHARACTERISTICS, Read Cycle

 V_{CC} = 3.0V to 3.6V, unless otherwise specified

		28LV256-20		28LV256-25		28LV256-30		
Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Units
t _{RC}	Read Cycle Time	200		250		300		ns
t _{CE}	CE Access Time		200		250		300	ns
t _{AA}	Address Access Time		200		250		300	ns
t _{OE}	OE Access Time		80		100		110	ns
tLZ ⁽¹⁾	CE Low to Active Output	0		0		0		ns
t _{OLZ} ⁽¹⁾	OE Low to Active Output	0		0		0		ns
t _{HZ} ⁽¹⁾⁽³⁾	CE High to High-Z Output		50		55		60	ns
tонz ⁽¹⁾⁽³⁾	OE High to High-Z Output		50		55		60	ns
t _{OH} ⁽¹⁾	Output Hold from Address Change	0		0		0		ns

Note:

(2) $V_{IHC} = V_{CC} - 0.3V$ to $V_{CC} + 0.3V$.

⁽¹⁾ This parameter is tested initially and after a design or process change that affects the parameter.

⁽³⁾ Output floating (High-Z) is defined as the state when the external data line is no longer driven by the output buffer.





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28LV256 F05

A.C. CHARACTERISTICS, Write Cycle

 V_{CC} = 3.0V to 3.6V, unless otherwise specified

		28LV256-20		28LV256-25		28LV256-30		
Symbol	Parameter	Min.	Min. Max.		Max.	Min.	Max.	Units
t _{WC}	Write Cycle Time		10		10		10	ms
t _{AS}	Address Setup Time	0		0		0		ns
t _{AH}	Address Hold Time	100		100		100		ns
t _{CS}	CE Setup Time	0		0		0		ns
t _{CH}	CE Hold Time	0		0		0		ns
tcw ⁽³⁾	CE Pulse Time	150		150		150		ns
t _{OES}	OE Setup Time	0		0		0		ns
t _{OEH}	OE Hold Time	0		0		0		ns
twp ⁽³⁾	WE Pulse Width	150		150		150		ns
tDS	Data Setup Time	50		50		50		ns
t _{DH}	Data Hold Time	0		0		0		ns
t _{INIT} ⁽¹⁾	Write Inhibit Period After Power-up	5	10	5	10	5	10	ms
t _{BLC} ⁽¹⁾⁽⁴⁾	Byte Load Cycle Time	0.15 100		0.15	100	0.15	100	μs

Note:

(2) Input rise and fall times (10% and 90%) < 10 ns.

⁽¹⁾ This parameter is tested initially and after a design or process change that affects the parameter.

⁽³⁾ A write pulse of less than 20ns duration will not initiate a write cycle.

⁽⁴⁾ A timer of duration t_{BLC} max. begins with every LOW to HIGH transition of \overline{WE} . If allowed to time out, a page or byte write will begin; however a transition from HIGH to LOW within t_{BLC} max. stops the timer.



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DEVICE OPERATION

Read

Data stored in the CAT28LV256 is transferred to the data bus when \overline{WE} is held high, and both \overline{OE} and \overline{CE} are held low. The data bus is set to a high impedance state when either \overline{CE} or \overline{OE} goes high. This 2-line control architecture can be used to eliminate bus contention in a system environment.

Byte Write

A write cycle is executed when both \overline{CE} and \overline{WE} are low, and \overline{OE} is high. Write cycles can be initiated using either \overline{WE} or \overline{CE} , with the address input being latched on the falling edge of \overline{WE} or \overline{CE} , whichever occurs last. Data, conversely, is latched on the rising edge of \overline{WE} or \overline{CE} , whichever occurs first. Once initiated, a byte write cycle automatically erases the addressed byte and the new data is written within 10 ms.



Figure 4. Byte Write Cycle [WE Controlled] twr ADDRESS tAS ^tAH tcs ⁺CH → CE ŌE ^tOEH +tOES→ twp WE tBI C HIGH-Z DATA OUT DATA IN DATA VALID tDS -tDH 28LV256 F07



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Page Write

The page write mode of the CAT28LV256 (essentially an extended BYTE WRITE mode) allows from 1 to 64 bytes of data to be programmed within a single E^2PROM write cycle. This effectively reduces the byte-write time by a factor of 64.

Following an initial WRITE operation ($\overline{\text{WE}}$ pulsed low, for t_{WP}, and then high) the page write mode can begin by issuing sequential $\overline{\text{WE}}$ pulses, which load the address and data bytes into a 64 byte temporary buffer. The page address where data is to be written, specified by bits A₆ to A₁₄, is latched on the last falling edge of $\overline{\text{WE}}$. Each byte within the page is defined by address bits A₀ to A₅

(which can be loaded in any order) during the first and subsequent write cycles. Each successive byte load cycle must begin within $t_{BLC\,MAX}$ of the rising edge of the preceding \overline{WE} pulse. There is no page write window limitation as long as \overline{WE} is pulsed low within $t_{BLC\,MAX}$.

Upon completion of the page write sequence, $\overline{\text{WE}}$ must stay high a minimum of t_{BLC MAX} for the internal automatic program cycle to commence. This programming cycle consists of an erase cycle, which erases any data that existed in each addressed cell, and a write cycle, which writes new data back into the cell. A page write will only write data to the locations that were addressed and will not rewrite the entire page.







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DATA Polling

DATA polling is provided to indicate the completion of write cycle. Once a byte write or page write cycle is initiated, attempting to read the last byte written will output the complement of that data on I/O_7 ($I/O_0-I/O_6$ are indeterminate) until the programming cycle is complete. Upon completion of the self-timed write cycle, all I/O's will output true data during a read cycle.

Toggle Bit

In addition to the DATA Polling feature, the device can determine the completion of a write cycle, while a write cycle is in progress, by reading data from the device. This results in I/O_6 toggling between one and zero. Once the write is complete, however, I/O_6 stops toggling and valid data can be read from the device.



Figure 8. Toggle Bit



Note:

(1) Beginning and ending state of I/O_6 is indeterminate.



HARDWARE DATA PROTECTION

The following hardware data protection features are incorporated into the CAT28LV256.

- (1) V_{CC} sense provides write protection when V_{CC} falls below 2.0V min.
- (2) A power on delay mechanism, t_{INIT} (see AC characteristics), provides a 5 to 10 ms delay before a write sequence, after V_{CC} has reached 2.4V min.
- (3) Write inhibit is activated by holding any one of OE low, CE high, or WE high.

Figure 9. Write Sequence for Activating Software Data Protection

(4) Noise pulses of less than 20 ns on the \overline{WE} or \overline{CE} inputs will not result in a write cycle.

SOFTWARE DATA PROTECTION

The CAT28LV256 features a software controlled data protection scheme which, once enabled, requires a data algorithm to be issued to the device before a write can be performed. The device is shipped from Catalyst with the software protection NOT ENABLED (the CAT28LV256 is in the standard operating mode).

AA

55

80

5555

AA

55

20

5555

2AAA

5555

2AAA

5555

Figure 10. Write Sequence for Deactivating Software Data Protection



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Note:

(1) Write protection is activated at this point whether or not any more writes are completed. Writing to addresses must occur within t_{BLC} Max., after SDP activation.



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To activate the software data protection, the device must be sent three write commands to specific addresses with specific data (Figure 9). This sequence of commands (along with subsequent writes) must adhere to the page write timing specifications (Figure 11). Once this is done, all subsequent byte or page writes to the device must be preceded by this same set of write commands. The data protection mechanism is activated until a deactivate sequence is issued, regardless of power on/off transitions. This gives the user added inadvertent write protection on power-up in addition to the hardware protection provided. To allow the user the ability to program the device with an E²PROM programmer (or for testing purposes) there is a software command sequence for deactivating the data protection. The six step algorithm (Figure 10) will reset the internal protection circuitry, and the device will return to standard operating mode (Figure 12 provides reset timing). After the sixth byte of this reset sequence has been issued, standard byte or page writing can commence.

Figure 11. Software Data Protection Timing



Figure 12. Resetting Software Data Protection Timing





EXAMPLE OF ORDERING INFORMATION⁽¹⁾



ORDERING INFORMATION

Orderable Part Numbers (for Pb-Free Devices)					
CAT28LV256GI-20T	CAT28LV256HE25T				
CAT28LV256GI-25T	CAT28LV256HE30T				
CAT28LV256GI-30T	CAT28LV256LI20				
CAT28LV256GA-25T	CAT28LV256LI25				
CAT28LV256GA-30T	CAT28LV256LI30				
CAT28LV256GE-25T	CAT28LV256LA25				
CAT28LV256GE-30T	CAT28LV256LA30				
CAT28LV256HI20T	CAT28LV256LE25				
CAT28LV256HI25T	CAT28LV256LE30				
CAT28LV256HI30T					
CAT28LV256HA25T					
CAT28LV256HA30T					

Notes:

- (1) The device used in the above example is a CAT28LV256NI-25T (100,000 Cycle Endurance, PLCC, Industrial temperature, 250 ns Access Time, Tape & Reel).
- (2) Solder-plate (tin-lead) packages, contact Factory for availability.
- (3) Commercial and industrial temperature range only.



REVISION HISTORY

Date	Revision	Description
03-Feb-04	A	Assigned doc number Updated Ordering Info
27-Feb-04	В	Added Green Packages
15-Oct-08	С	Eliminate TSOP (8mm x 13.4mm) SnPb package.
18-Nov-08	D	Change logo and fine print to ON Semiconductor
30-Jul-09	E	Update Example of Ordering Information Update Ordering Information table

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