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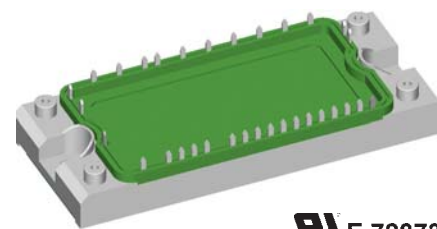
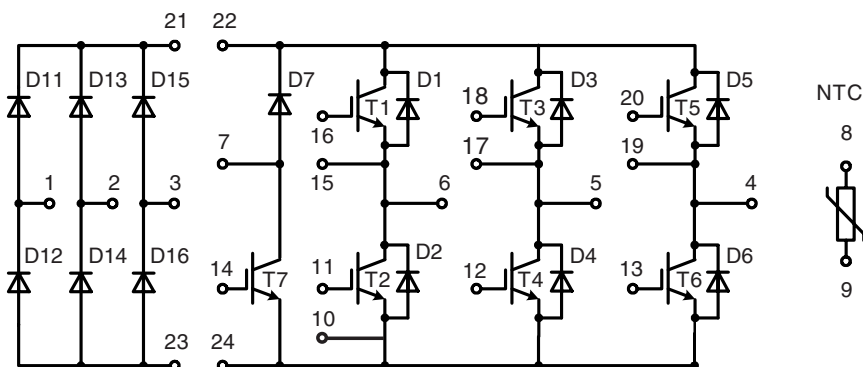
[MUBW25-12T7](#)

For any questions, you can email us directly:

sales@integrated-circuit.com

Converter - Brake - Inverter Module (CBI2) with Trench IGBT technology

Preliminary data



E 72873

| Three Phase Rectifier | Brake Chopper | Three Phase Inverter |
|----------------------------|-------------------------------|-------------------------------|
| $V_{RRM} = 1600 \text{ V}$ | $V_{CES} = 1200 \text{ V}$ | $V_{CES} = 1200 \text{ V}$ |
| $I_{FAVM} = 38 \text{ A}$ | $I_{C25} = 30 \text{ A}$ | $I_{C25} = 45 \text{ A}$ |
| $I_{FSM} = 300 \text{ A}$ | $V_{CE(sat)} = 1.7 \text{ V}$ | $V_{CE(sat)} = 1.7 \text{ V}$ |

Input Rectifier Bridge D11 - D16

| Symbol | Conditions | Maximum Ratings | |
|------------|--|-----------------|---|
| V_{RRM} | | 1600 | V |
| I_{FAV} | $T_C = 80^\circ\text{C}$; sine 180° | 25 | A |
| I_{DAVM} | $T_C = 80^\circ\text{C}$; rectangular; $d = 1/3$; bridge | 72 | A |
| I_{FSM} | $T_{VJ} = 25^\circ\text{C}$; $t = 10 \text{ ms}$; sine 50 Hz | 300 | A |
| P_{tot} | $T_C = 25^\circ\text{C}$ | 100 | W |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified) | | |
|------------|--|--|------|----------|
| | | min. | typ. | max. |
| V_F | $I_F = 25 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | 1.1 | 1.3 | V |
| | | 1.1 | | V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | 0.4 | 0.02 | mA mA |
| R_{thJC} | (per diode) | | 1.3 | K/W |

Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

Features

- High level of integration - only one power semiconductor module required for the whole drive
- Inverter with Trench IGBTs
 - low saturation voltage
 - positive temperature coefficient
 - fast switching
 - short tail current
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

Output Inverter T1 - T6

| Symbol | Conditions | Maximum Ratings | |
|-----------|--|-----------------|---|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| V_{GES} | Continuous | ± 20 | V |
| I_{C25} | $T_C = 25^{\circ}\text{C}$ | 45 | A |
| I_{C80} | $T_C = 80^{\circ}\text{C}$ | 25 | A |
| I_{CM} | $T_C = 80^{\circ}\text{C}; t_p = 1 \text{ ms}$ | 50 | A |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 170 | W |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | | |
|--|---|--|------------------------------------|------|
| | | min. | typ. | max. |
| $V_{CE(sat)}$ | $I_C = 25 \text{ A}; V_{GE} = 15 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | 1.7 | 2.15 | V |
| $V_{GE(th)}$ | $I_C = 1 \text{ mA}; V_{GE} = V_{CE}$ | 5 | 5.8 | 6.5 |
| I_{CES} | $V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | 0.7 | 2.7 | mA |
| I_{GES} | $V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$ | | 400 | nA |
| C_{ies} | $V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$ | 1.8 | | nF |
| Q_{Gon} | $V_{CE} = 600 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 25 \text{ A}$ | 240 | | nC |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_t E_{on} E_{off} | Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600 \text{ V}; I_C = 25 \text{ A}$ $V_{GE} = \pm 15 \text{ V}; R_G = 36 \Omega$ | 90 | | ns |
| | | 50 | | ns |
| | | 520 | | ns |
| | | 90 | | ns |
| | | 2.5 | | mJ |
| | | 3.4 | | mJ |
| RBSOA | $I_C = I_{CM}; V_{GE} = \pm 15 \text{ V}$ $R_G = 36 \Omega; T_{VJ} = 125^{\circ}\text{C}$ | | $V_{CEK} \leq V_{CES} - L_S di/dt$ | V |
| I_{SC} (SCSOA) | $V_{CE} = 720 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 36 \Omega;$ $t_p \leq 10 \mu\text{s}; \text{non-repetitive}; T_{VJ} = 125^{\circ}\text{C}$ | 100 | | A |
| R_{thJC} | (per IGBT) | | 0.73 | K/W |

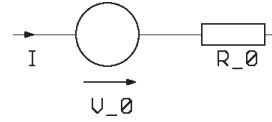
Output Inverter D1 - D6

| Symbol | Conditions | Maximum Ratings | |
|-----------|----------------------------|-----------------|---|
| I_{F25} | $T_C = 25^{\circ}\text{C}$ | 25 | A |
| I_{F80} | $T_C = 80^{\circ}\text{C}$ | 17 | A |

| Symbol | Conditions | Characteristic Values | | |
|---|--|-----------------------|------|---------------|
| | | min. | typ. | max. |
| V_F | $I_F = 25 \text{ A}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | 2.1 | 2.6 | V |
| I_{RM} Q_{rr} t_{rr} E_{rec} | $I_F = \text{tbd A}; di_F/dt = -\text{tbd A}/\mu\text{s}; T_{VJ} = 125^{\circ}\text{C}$ $V_R = 600 \text{ V}; V_{GE} = 0 \text{ V}$ | tbd | | A |
| | | tbd | | μC |
| | | tbd | | ns |
| | | tbd | | mJ |
| R_{thJC} | (per diode) | | 2.1 | K/W |

Equivalent Circuits for Simulation

Conduction



IGBT (typ. at $V_{GE} = 15 \text{ V}; T_J = 125^{\circ}\text{C}$)
T1-T6

$$V_0 = 0.92 \text{ V}; R_0 = 42.8 \text{ m}\Omega$$

T7

$$V_0 = 0.92 \text{ V}; R_0 = 72 \text{ m}\Omega$$

Diode (typ. at $T_J = 125^{\circ}\text{C}$)

D1-D6

$$V_0 = \text{tbd V}; R_0 = \text{tbd m}\Omega$$

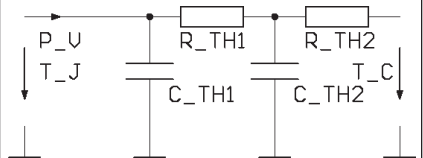
D7

$$V_0 = \text{tbd V}; R_0 = \text{tbd m}\Omega$$

D11-D16

$$V_0 = \text{tbd V}; R_0 = \text{tbd m}\Omega$$

Thermal Response



IGBT (typ.)

T1-T6

$$C_{th1} = \text{tbd J/K}; R_{th1} = \text{tbd K/W}$$

$$C_{th2} = \text{tbd J/K}; R_{th2} = \text{tbd K/W}$$

T7

$$C_{th1} = \text{tbd J/K}; R_{th1} = \text{tbd K/W}$$

$$C_{th2} = \text{tbd J/K}; R_{th2} = \text{tbd K/W}$$

Diode (typ.)

D1-D6

$$C_{th1} = \text{tbd J/K}; R_{th1} = \text{tbd K/W}$$

$$C_{th2} = \text{tbd J/K}; R_{th2} = \text{tbd K/W}$$

D7

$$C_{th1} = \text{tbd J/K}; R_{th1} = \text{tbd K/W}$$

$$C_{th2} = \text{tbd J/K}; R_{th2} = \text{tbd K/W}$$

D11-D16

$$C_{th1} = \text{tbd J/K}; R_{th1} = \text{tbd K/W}$$

$$C_{th2} = \text{tbd J/K}; R_{th2} = \text{tbd K/W}$$

Brake Chopper T7

| Symbol | Conditions | Maximum Ratings | |
|-----------|--|-----------------|---|
| V_{CES} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| V_{GES} | Continuous | ± 20 | V |
| I_{C25} | $T_C = 25^{\circ}\text{C}$ | 30 | A |
| I_{C80} | $T_C = 80^{\circ}\text{C}$ | 15 | A |
| I_{CM} | $T_C = 80^{\circ}\text{C}; t_p = 1 \text{ ms}$ | 30 | A |
| P_{tot} | $T_C = 25^{\circ}\text{C}$ | 120 | W |

| Symbol | Conditions | Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified) | | | |
|--|---|--|------------------------------|------------------------------------|---------|
| | | min. | typ. | max. | |
| $V_{CE(sat)}$ | $I_C = 15 \text{ A}; V_{GE} = 15 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 1.7 2.0 | 2.1 V V | |
| $V_{GE(th)}$ | $I_C = 0.5 \text{ mA}; V_{GE} = V_{CE}$ | 5 | 5.8 | 6.5 V | |
| I_{CES} | $V_{CE} = V_{CES}; V_{GE} = 0 \text{ V}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 0.25 | 0.1 mA mA | |
| I_{GES} | $V_{CE} = 0 \text{ V}; V_{GE} = \pm 20 \text{ V}$ | | | 400 nA | |
| C_{ies} | $V_{CE} = 25 \text{ V}; V_{GE} = 0 \text{ V}; f = 1 \text{ MHz}$ | | 1.1 | nF | |
| Q_{Gon} | $V_{CE} = 600 \text{ V}; V_{GE} = 15 \text{ V}; I_C = 15 \text{ A}$ | | 150 | nC | |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{off} | $\left. \begin{array}{l} \text{Inductive load, } T_{VJ} = 125^{\circ}\text{C} \\ V_{CE} = 600 \text{ V}; I_C = 15 \text{ A} \\ V_{GE} = \pm 15 \text{ V}; R_G = 75 \Omega \end{array} \right\}$ | | 90 50 520 90 1.5 | ns ns ns ns mJ | |
| RBSOA | | $I_C = I_{CM}; V_{GE} = \pm 15 \text{ V}$ $R_G = 75 \Omega; T_{VJ} = 125^{\circ}\text{C}$ | | $V_{CEK} \leq V_{CES} - L_S di/dt$ | V |
| I_{SC} (SCSOA) | | $V_{CE} = 720 \text{ V}; V_{GE} = \pm 15 \text{ V}; R_G = 75 \Omega$ $t_p \leq 10 \mu\text{s}; \text{non-repetitive}; T_{VJ} = 125^{\circ}\text{C}$ | | 60 | A |
| R_{thJC} | | | | | 1.05 KW |

Brake Chopper D7

| Symbol | Conditions | Maximum Ratings | |
|-----------|--|-----------------|---|
| V_{RRM} | $T_{VJ} = 25^{\circ}\text{C}$ to 150°C | 1200 | V |
| I_{F25} | $T_C = 25^{\circ}\text{C}$ | 16 | A |
| I_{F80} | $T_C = 80^{\circ}\text{C}$ | 11 | A |

| Symbol | Conditions | Characteristic Values | | |
|------------|---|-----------------------|------------|---------------|
| | | min. | typ. | max. |
| V_F | $I_F = 65 \text{ A}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 3.0 2.6 | 3.3 V V |
| I_R | $V_R = V_{RRM}; T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$ | | 0.07 | 0.06 mA mA |
| R_{thJC} | | | | 3.2 KW |



MUBW 25-12 T7

Temperature Sensor NTC

| Symbol | Conditions | Characteristic Values | | |
|-------------------------|------------|-----------------------|-------------|--------------|
| | | min. | typ. | max. |
| R_{25} $B_{25/50}$ | T = 25°C | 4.75 | 5.0 3375 | 5.25 kΩ K |

Module

| Symbol | Conditions | Maximum Ratings | |
|------------|--------------------------------|-----------------|----|
| T_{VJ} | operating | -40...+125 | °C |
| T_{JM} | | 150 | °C |
| T_{stg} | | -40...+125 | °C |
| V_{ISOL} | $I_{ISOL} \leq 1$ mA; 50/60 Hz | 2500 | V~ |
| M_d | Mounting torque (M5) | 2.7 - 3.3 | Nm |

| Symbol | Conditions | Characteristic Values | | |
|----------------|------------------------------|-----------------------|------|------|
| | | min. | typ. | max. |
| $R_{pin-chip}$ | | | 5 | mΩ |
| d_s | Creepage distance on surface | 6 | | mm |
| d_A | Strike distance in air | 6 | | mm |
| R_{thCH} | with heatsink compound | | 0.02 | K/W |
| Weight | | | 180 | g |

Dimensions in mm (1 mm = 0.0394")

