## 8-Channel White LED Driver with Integrated FET for up to 80 LEDs

## BD6142AMUV

## -General Description

This IC is white LED driver IC with PWM step-up DC/DC converter that can boost max 41V and current driver that can drive max 30 mA . The wide and precision brightness can be controlled by external PWM pulse. This IC has very accurate current drivers, and it has few current errors between each strings. So, it will be helpful to reduce brightness spots on the LCD panel. Small package is suited for saving space.

## -Features

- High accuracy \& good matching current drivers 8ch (MAX30mA/ch)
- Integrated 50V power Nch MOSFET
- Soft Start function
- Drive up to 11 LEDs in series, 8 strings in parallel
- Rich safety functions
- Over-voltage protection
- External SBD open detect / Output Short protection
- Over current limit
- CH Terminal open / GND short protect
- CH over voltage protect / LED short protect
- Thermal shutdown
- UVLO
- Analog Brightness Control


## OKey Specifications

■ Operating power supply voltage range: 4.2 V to 27.0 V

- LED maximum current:

30mA (Max.)

- Quiescent Current:
- Switching frequency:
$1.6 \mu \mathrm{~A}$ (Тур.)
. 1.25 Mzz (Typ.)
- Package W(Typ.) x D (Typ.) $\times \mathrm{H}$ (Max.)

VQFN024V4040 $4.00 \mathrm{~mm} \times 4.00 \mathrm{~mm} \times 1.00 \mathrm{~mm}$


VQFN024V4040
Figure 1. Package

## - Applications

All medium sized LCD equipments, Backlight of Notebook PC, net book, monitor, light, Portable DVD player, light source etc.

## -Typical Application Circuit (8 Parallel)



Figure 2. Typical Application Circuit

## - Absolute Maximum Ratings ( $\mathrm{Ta}=25^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Ratings | Unit | Condition |
| :--- | :---: | :---: | :---: | :--- |
| Terminal voltage 1 | VMAX1 | 7 | V | VDC, ISET, ABC, <br> COMP, FSET, TEST, FAULT |
| Terminal voltage 2 | VMAX2 | 45 | V | CH1 to CH8, LX, OVP |
| Terminal voltage 3 | VMAX3 | 30.5 | V | VIN, ENABLE |
| Terminal voltage 4 | VMAX4 | 15 | V | PWM |
| Power dissipation 1 | Pd1 | $500^{* 1}$ | mW |  |
| Power dissipation 2 | Pd2 | $780^{* 2}$ | mW |  |
| Power dissipation 3 | Pd3 | $1510^{* 3}$ | mW |  |
| Operating temperature range | Topr | -40 to +85 | ${ }^{\circ} \mathrm{C}$ |  |
| Storage temperature range | Tstg | -55 to+150 | ${ }^{\circ} \mathrm{C}$ |  |

*1 Reduced $4.0 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ With $\mathrm{Ta}>25^{\circ} \mathrm{C}$ when not mounted on a heat radiation Board.
*2 1 layer (ROHM Standard board) has been mounted. Copper foil area $0 \mathrm{~mm}^{2}$, When it's used by more than $\mathrm{Ta}=25^{\circ} \mathrm{C}$, it's reduced by $6.2 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$.
*3 4 layer (JEDEC Compliant board) has been mounted. Copper foil area 1layer $6.28 \mathrm{~mm}^{2}$, Copper foil area 2 to 4 layers $5655.04 \mathrm{~mm}^{2}$, When it's used by more than $\mathrm{Ta}=25^{\circ} \mathrm{C}$, it's reduced by $12.1 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$.

- Recommended Operating Rating ( $\mathrm{Ta}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Limits |  |  | Unit | Conditions |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Typ. | Max. |  |  |
| Power supply voltage | VIN | 4.2 | 12.0 | 27.0 | V |  |

- Electrical Characteristics (Unless otherwise specified, $\mathrm{VIN}=12 \mathrm{~V}, \mathrm{Ta}=+25^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Limits |  |  | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Typ. | Max. |  |  |
| [General] |  |  |  |  |  |  |
| Quiescent Current | 19 | - | 1.6 | 4.4 | $\mu \mathrm{A}$ | ENABLE $=0 \mathrm{~V}$ |
| Current Consumption | Idd | - | 3.6 | 5.4 | mA | OVP $=0 \mathrm{~V}, \mathrm{ISET}=36 \mathrm{k} \Omega$ |
| Max. Output Voltage | MOV | - | - | 41 | V |  |
| Under Voltage Lock Out | UVLO | 3.1 | 3.7 | 4.1 | V | VIN falling edge |
| [ENABLE Terminal] |  |  |  |  |  |  |
| Low Input Voltage range | EnL | 0.0 | - | 0.8 | V |  |
| High Input Voltage range1 | EnH | 2.0 | - | VIN | V |  |
| Pull down resistor | EnR | 100 | 300 | 500 | $\mathrm{k} \Omega$ | ENABLE=3V |
| Output Current | ENIout | - | 0 | 2 | $\mu \mathrm{A}$ | ENABLE=0V |
| [PWM Terminal] |  |  |  |  |  |  |
| Low Input Voltage range | PWML | 0.0 | - | 0.8 | V |  |
| High Input Voltage range2 | PWMH | 1.3 | - | 12.0 | V |  |
| Pull down resistor | PWMR | 100 | 300 | 500 | k $\Omega$ | PWM $=3 \mathrm{~V}$ |
| Output Current | PWMlout | - | 0 | 2 | $\mu \mathrm{A}$ | PWM $=0 \mathrm{~V}$ |
| [FAULT] |  |  |  |  |  |  |
| Nch RON | FFCR | - | - | 3 | k $\Omega$ | ENABLE $=P W M=3 \mathrm{~V}, \mathrm{OVP}=2 \mathrm{~V}$ |
| [Regulator] |  |  |  |  |  |  |
| VDC Voltage | VREG | 4.2 | 5.0 | 6.0 | V | No load, VIN $>6 \mathrm{~V}$ |

-Electrical Characteristics - continued (Unless otherwise specified, $\mathrm{VIN}=12 \mathrm{~V}, \mathrm{Ta}=+25^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Limits |  |  | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Typ. | Max. |  |  |
| [Switching Regulator] |  |  |  |  |  |  |
| LED Control voltage | VLED | 0.64 | 0.80 | 0.96 | v |  |
| Switching frequency accuracy | Fsw | 1.00 | 1.25 | 1.50 | MHz | FSET=56k $\Omega$ |
| Duty cycle limit | Duty | 91.0 | 95.0 | 99.0 | \% | CH1-8=0.3V, FSET=56k $\Omega$ |
| LX Nch FET RON | RON | - | 0.48 | 0.58 | $\Omega$ | ILX $=80 \mathrm{~mA}$ |
| [Protection] |  |  |  |  |  |  |
| Over Current Limit | Ocp | 1.5 | 2.5 | - | A | ${ }_{1}$ |
| Over voltage limit Input | ovp | 1.16 | 1.20 | 1.24 | v | Detect voltage of OVP |
| Output Short Protect | OVPfault | 0.02 | 0.05 | 0.08 | V | Detect voltage of OVP |
| OVP leak current | OVIL | - | 0.1 | 1.0 | $\mu \mathrm{A}$ |  |
| CH Terminal Over Voltage Protect accuracy | VSC | -15 | 0 | +15 | \% | VSC=5V |
| [Current driver] |  |  |  |  |  |  |
| LED maximum current | ILMAX | - | - | 30 | mA |  |
| LED current accuracy | ILACCU | - | - | $\pm 2.5$ | \% | ILED=20mA (36k $)$ |
| LED current matching | ILMAT | - | - | 2.5 | \% | (Max LED current - Min LED current)/ Ideal current ( 20 mA ) ILED=20mA |
| LED current matching2 | ILMAT2 | - | - | 1.5 | \% | -Each LED current/Average <br> (CH1-8) <br> - ILED $=20 \mathrm{~mA}$ |
| LED current limiter | ILOCP | - | 0 | 0.1 | mA | Current limit value at ISET Resistance $1 \mathrm{k} \Omega$ setting |
| ISET voltage | Iset | - | 0.733 | - | v |  |
| LED current accuracy2 | ILACCU2 | - | $\pm 3.0$ | - | \% | ILED $=20 \mathrm{~mA}, \mathrm{ABC}=0.733 \mathrm{~V}$ |

*1 This parameter is tested with DC measurement.

## -Pin Descriptions

| Pin No. | Pin Name | 10 | Function | Terminal diagram |
| :---: | :---: | :---: | :---: | :---: |
| 1 | ENABLE | In | PWM input pin for power ON/OFF or Power control | E |
| 2 | TEST | In | TEST signal (Pull down 100k 2 within IC) | E |
| 3 | FSET | In | Resister connection for frequency setting | A |
| 4 | ABC | In | Analog Brightness Control | C |
| 5 | GND | - | GND for Switching Regulator | B |
| 6 | PWM | In | PWM input pin for power ON/OFF only driver | E |
| 7 | CH8 | In | Current sink for CH8 | C |
| 8 | CH7 | In | Current sink for CH7 | C |
| 9 | CH6 | In | Current sink for CH6 | C |
| 10 | CH5 | In | Current sink for CH5 | C |
| 11 | ISET | In | Resister connection for LED current setting | A |
| 12 | CH 4 | In | Current sink for CH 4 | C |
| 13 | CH3 | In | Current sink for CH3 | C |
| 14 | CH2 | In | Current sink for CH 2 | C |
| 15 | CH1 | In | Current sink for CH1 | C |
| 16 | OVP | In | Detect input for SBD open and OVP | C |
| 17 | PGND | - | PGND for switching Tr | D |
| 18 |  |  | PGND for swithing Tr |  |
| 19 |  | Out | Switching $\operatorname{Tr}$ drive terminal | F |
| 20 |  | Out | Switching $\operatorname{Tr}$ drive terminal | F |
| 21 | FAULT | Out | Fault signal | C |
| 22 | COMP | Out | ERRAMP output | A |
| 23 | VIN | In | Battery input | G |
| 24 | VDC | Out | Regulator output / Internal power-supply | C |
| - | Thermal PAD | - | Heat radiation PAD of back side Connect to GND |  |

## -Pin ESD Type



A


E


F


C

D


G

Figure 3. Pin ESD Type

## -Block Diagram



Pin number 24pin
Figure 4. Block diagram

## - Typical Performance Curves


<Condition>
■10serial $\times$ 8parallel
-Ta $=25^{\circ} \mathrm{C}$
■LED Current $=20 \mathrm{~mA}$
■PWM frequency $=200 \mathrm{~Hz}$
■Frequency $=1.25 \mathrm{MHz}($ FSET $=56 \mathrm{k} \Omega)$
■Coil $=10 \mu \mathrm{H}$

Figure 5. LED current characteristics PWM dimming

<Condition>
■10 serial $\times 8$ parallel
-Ta $=25^{\circ} \mathrm{C}$
■LED Current $=20 \mathrm{~mA}$
■PWM frequency $=30 \mathrm{kHz}$
■Frequency $=1.25 \mathrm{MHz}($ FSET $=56 \mathrm{k} \Omega)$
■Coil $=4.7 \mu \mathrm{H}$

Figure 6. LED current characteristics PWM dimming


Figure 8. LED maximum current
<Condition>
-VIN = 12 V

- $\mathrm{CH} 1=0.8 \mathrm{~V}$

> <Condition>
> $■ \mathrm{Ta}=25^{\circ} \mathrm{C}$
> ISET $=36 \mathrm{k} \Omega$
> $\square \mathrm{CH} 1=0.8 \mathrm{~V}$

Figure 7. LED Current Characteristics Analog Dimming


Figure 9. Efficiency

## - Application example

Figure 11, Figure 12 and Figure 13 are Application examples (15.4inch and 12inch and 10.1inch model). Recommended schematics and Layout are shown in P22.


Figure 11. BD6142AMUV Application example (8 parallel)


Figure 12. BD6142AMUV Application example (6 parallel)


Figure 13. BD6142AMUV Application example (3 parallel)

## -Functional descriptions

## 1) PWM current mode DC/DC converter

While this IC is power ON, the lowest voltage of $\mathrm{CH} 1,2,3,4,5,6,7,8$ is detected, PWM duty is decided to be 0.8 V and output voltage is kept invariably. As for the inputs of the PWM comparator as the feature of the PWM current mode, one is overlapped with error components from the error amplifier, and the other is overlapped with a current sense signal that controls the inductor current into Slope waveform to prevent sub harmonic oscillation. This output controls internal Nch Tr via the RS latch. In the period where internal Nch $\operatorname{Tr}$ gate is ON, energy is accumulated in the external inductor, and in the period where internal Nch $\operatorname{Tr}$ gate is OFF, energy is transferred to the output capacitor via external SBD.
This IC has many safety functions, and their detection signals stop switching operation at once.

## 2) Pulse skips control

This IC regulates the output voltage using an improved pulse-skip. In "pulse-skip" mode the error amplifier disables "switching" of the power stages when it detects low output voltage and high input voltage. The oscillator halts and the controller skip switching cycles. The error amplifier reactivates the oscillator and starts switching of the power stages again when this IC detects low input voltage.
At light loads a conventional "pulse-skip" regulation mode is used. The "pulse-skip" regulation minimizes the operating current because this IC does not switch continuously and hence the losses of the switching are reduced. When the error amplifier disables "switching", the load is also isolated from the input. This improved "pulse-skip" control is also referred to as active-cycle control.


Figure 14. Pulse-skip
3) Soft start

This IC has soft start function.
The soft start function prevents large coil current.
Rush current at turning on is prevented by the soft start function.
After ENABLE, PWM is changed ' L ' $\rightarrow$ ' $H$ ', and UVLO is detected, soft start becomes effective for within typ 4.3 ms and soft start doesn't become effective even if ENABLE is changed ' L ' $\rightarrow$ ' H ' after that.


Figure 15. Soft start

## 4) FAULT

When the error condition occurs, boost operating is stopped by the protection function, and the error condition is outputted from FAULT. After power ON, when the protection function is operating under about $4.3 \mathrm{~ms}($ typ.) have passed.
Once ENABLE change to ' L ', FAULT status is reset
Object of protect function is as shown below.

- Over-voltage protection (OVP)
- Thermal shut down (OTP)
- Over current limit (OCP)
- Output short protect
- LED Short (Latch)
- LED Open (Latch)


Figure 16. FAULT operating description

## - Protection

PROTECTION TABLE

| CASE | FAILURE MODE | DETECTION MODE | FAIL CHANNEL | $\begin{gathered} \text { GOOD } \\ \text { CHANNEL } \end{gathered}$ | $\begin{gathered} \text { VOUT } \\ \text { REGULATED BY } \end{gathered}$ | FAULT Terminal |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | LED Short connected CH1 | $\mathrm{CH} 1>\mathrm{VSC}(5 \mathrm{~V})$ | LED current stop and DC/DC feedback doesn't return | CH 2 to CH 8 Normal | Highest VF of CH 2 to CH 8 | $\begin{aligned} & \text { 'H' } \rightarrow \text { 'L' ' } \\ & \text { (Latch) } \end{aligned}$ <br> (Latch) |
| 2 | LED OPEN connected CH1 | $\begin{aligned} & \hline \mathrm{CH} 1<0.2 \mathrm{~V} \\ & \text { and } \\ & \text { VOUT > VOVP } \\ & \hline \end{aligned}$ | LED current stop and DC/DC feedback doesn't return | CH 2 to CH 8 Normal | $\begin{aligned} & \text { Highest VF } \\ & \text { of } \mathrm{CH} 2 \text { to } \mathrm{CH} 8 \end{aligned}$ | ${ }^{\prime} \mathrm{H}^{\prime} \rightarrow \text { ' } \mathrm{L} \text { ' }$ <br> (Latch) |
| 3 | VOUT/LX GND SHORT | OVP < 50mV | FAULT change from L to H , and switching is stopped. When OVP $>50 \mathrm{mV}$, FAULT return L |  | - | 'H' ${ }^{\text {' ' }}$ ' |
| 4 | Output LED stack voltage too high | VOUT > VOVP | FAULT change from L to H , and switching is stopped. <br> Even if OVP $<1.2 \mathrm{~V}$, FAULT don't return L |  | - | 'H' ${ }^{\text {' }}$ ' |
| 5 | LX current too high | $\begin{aligned} & \text { OCP }>2.5 \mathrm{~A} \\ & \text { or } \\ & \text { OTP }>130^{\circ} \mathrm{C} \end{aligned}$ | FAULT change from L to H , and switching is stopped. <br> Even if IC return normal status, FAULT don't return L |  | - | ' H ' $\rightarrow$ ' ${ }^{\text {' }}$ |

- Over voltage protection (OVP)

At such an error of output open as the output DC/DC and the LED is not connected to IC, the DC/DC will boost too much and the OVP terminal exceed the absolute maximum ratings, and may destruct the IC. Therefore, when OVP terminal becomes sensing voltage or higher, the over voltage limit protection works, and turns off the switching Tr, and DC/DC will be stopped.
At this moment, the IC changes from activation into non-activation, and the output voltage goes down slowly. And, when the Feedback of CH 1 isn't returned, so that VOUT will return normal voltage.


Figure 17. OVP operating description

This section is especially mentioned here because the spec shown electrical characteristic is necessary to explain this section.

Over voltage limit
LED control voltage
LED terminal over voltage protect

```
min 1.16V typ 1.20V max 1.24V
min 0.64V typ 0.80V max 0.96V
min 4.25V typ 5.00V max 5.75V
```

1. Calculate the conditions that the total value of LED VF is MAX. Example) In the case of serial 8 LEDs with $\mathrm{VF}=2.9 \mathrm{~V}(\mathrm{~min}), 3.2 \mathrm{~V}$ (typ), $3.5 \mathrm{~V}(\mathrm{max})=>3.5 \mathrm{~V} \times 8=28 \mathrm{~V}$
2. Then calculate the biggest value of output with the following formula.

The biggest value of output $=$ the biggest value calculated for $1+$ the biggest value of LED terminal voltage. ( 0.96 V ) Example) The biggest value of output $=28 \mathrm{~V}+0.96 \mathrm{~V}=28.96 \mathrm{~V}$
3. Set the smallest value of over voltage larger than the biggest value of output.

If over voltage is closer to the total value of VF, it could be occurred to detect over voltage by ripple, noise, and so on. It is recommended that some margins should be left on the difference between over voltage and the total value of VF. This time around 6\% margin is placed.
Example) Against the biggest value of output $=28.96 \mathrm{~V}$, the smallest value of over voltage $=28.96 \mathrm{~V} \times 1.06=30.70 \mathrm{~V}$ Ic over voltage limit min=1.16V, typ=1.20V, max=1.24V

$$
\operatorname{typ}=30.70 \mathrm{~V} \times(1.20 \mathrm{~V} / 1.16 \mathrm{~V})=31.76 \mathrm{~V}
$$

$$
\max =31.76 \mathrm{~V} \times(1.26 \mathrm{~V} / 1.20 \mathrm{~V})=33.35 \mathrm{~V}
$$

4. The below shows how to control resistor setting over voltage Please fix resistor high between OVP terminal and output and then set over voltage after changing resistor between OVP terminal and GND. While PWM is off, output voltage decreases by minimizing this resistor. Due to the decrease of output voltage, ripple of output voltage increases, and singing of output condenser also becomes bigger.
Example) Selecting OVP resistor.

## - OVP resistor selection

(Example. 1) $\mathrm{VF}=3.5 \mathrm{~V}$ max, serial $=7 \mathrm{LED}$ $\mathrm{OVP}=1.2 \mathrm{~V}, \mathrm{R} 1=2.2 \mathrm{M} \Omega, \mathrm{R} 2=95.3 \mathrm{k} \Omega$ VOUT $=1.2 \times(2.2 \mathrm{M} \Omega+95.3 \mathrm{k} \Omega) / 95.3 \mathrm{k} \Omega=28.90 \mathrm{~V}$
(Example. 2) $\mathrm{VF}=3.5 \mathrm{~V}$ max, serial $=8 \mathrm{LED}$ $\mathrm{OVP}=1.2 \mathrm{~V}, \mathrm{R} 1=2.2 \mathrm{M} \Omega, \mathrm{R} 2=82 \mathrm{k} \Omega$ VOUT $=1.2 \times(2.2 \mathrm{M} \Omega+82 \mathrm{k} \Omega) / 82 \mathrm{k} \Omega=33.40 \mathrm{~V}$
(Example. 3) $\mathrm{VF}=3.5 \mathrm{~V}$ max, serial $=9 \mathrm{LED}$ $\mathrm{OVP}=1.2 \mathrm{~V}, \mathrm{R} 1=2.2 \mathrm{M} \Omega, \mathrm{R} 2=73.2 \mathrm{k} \Omega$ VOUT $=1.2 \times(2.2 \mathrm{M} \Omega+73.2 \mathrm{k} \Omega) / 73.2 \mathrm{k} \Omega=37.27 \mathrm{~V}$
(Example. 4) $\mathrm{VF}=3.5 \mathrm{~V}$ max, serial $=10 \mathrm{LED}$ $\mathrm{OVP}=1.2 \mathrm{~V}, \mathrm{R} 1=2.2 \mathrm{M} \Omega, \mathrm{R} 2=68 \mathrm{k} \Omega$ $\mathrm{VOUT}=1.2 \times(2.2 \mathrm{M} \Omega+68 \mathrm{k} \Omega) / 68 \mathrm{k} \Omega=40.02 \mathrm{~V}$


## - External SBD open detect / Output Short protection

In the case of external SBD is not connected to IC, or VOUT is shorted to GND, the coil or internal Tr may be destructed. Therefore, at such an error as OVP becoming 50 mV (typ.) or below, turns off the output Tr , and prevents the coil and the IC from being destructed.
And the IC changes from activation into non-activation, and current does not flow to the coil ( 0 mA ).

## - Thermal shut down

This IC has thermal shut down function.
The thermal shut down works at $130^{\circ} \mathrm{C}$ (typ.) or higher, and the IC changes from activation into non-activation.

## -Operating of the application deficiency

1) When 1 LED or 1string OPEN during the operating

The LED string which became OPEN isn't lighting, but other LED strings are lighting.
Then LED terminal is OVOUTput boosts up to the over voltage protection voltage. When over voltage is detected, the feedback of open string isn't returned, so that VOUT will return normal voltage.


Figure 18. LED open protect
2) When LED short-circuited in the plural

All LED strings is turned on unless CH 1 to 8 terminal voltage is more than 5 V (typ.).
When it was more than 5 V only the strings which short-circuited is turned off normally and LED current of other lines continue to turn on. Short line(CH1) current is changed from 20 mA to 0.05 mA (typ.), so CH 1 terminal don't heat.


Figure 19. LED short protect
3)When Schottky diode remove

All LED strings aren't turned on. Also, IC and a switching transistor aren't destroyed because boost operating stops by the Schottky diode open protected function.

## -Control Signal input timing

Timing sequence1
Referring to Figure 20, the recommended turn "on" sequence is VIN followed by ENABLE and PWM.
The recommended turn "off" sequence is ENABLE and PWM followed by VIN. This sequence is recommendation.
LED IC Timing Sequence for PWM Control Turn-on


Figure 20. Timing sequence1

*other signal is input after a signal turned on.

LED IC Timing Sequence for PWM Control Turn-off

*other signal is input after a signal turned off.

Timing sequence2
Referring to Figure 21, the recommended turn "on" sequence is VIN, ENABLE followed by PWM. The recommended turn "off" sequence is followed ENABLE and VIN by PWM.


Figure 21. Timing sequence2

LED IC Timing Sequence for PWM Control Turn-on

*other signal is input after a signal turned on.


Timing sequence3
Referring to Figure 22, the recommended turn "on" sequence is VIN, PWM followed by ENABLE. The recommended turn "off" sequence is followed ENABLE and VIN by PWM.

LED IC Timing Sequence for PWM Control Turn-on


Figure 22. Timing sequence3

*other signal is input after a signal turned on.


VIN wake up speed
*other signal is input after a signal turned off.


Figure 23. control Signal timing

In case, there is PWM OFF status (min: 10ms) during operation as Figure 24, ENABLE should turn from ' H ' to 'L' as Figure 24.

If PWM stops and VOUT voltage is dropped, this IC will be condition of current limiter when PWM starts (no soft start). If soft start isn't needed, reset is no need.


Figure 24. PWM stop and ENABLE turn "off"

## -How to activate

Please be careful about the following when being activated.

- Regulator (VDC) operates after ENABLE=H. Inside circuit operates after releasing UVLO. When IC boosts after releasing UVLO, soft start function operates. (Refer to Figure 15, 9P). Soft start circuit needs $\mathrm{t}_{15}$ (more than $15 \mu \mathrm{~s}$ ) as Figure 25. shows. Soft start operates for $\mathrm{t}_{\text {soft }}$ time. Please make H width of PWM more than $15 \mu \mathrm{~s}$ until soft start finishes.
- Please input PWM signal according to Figure 26. after soft start finishes.


Figure 25. Soft start
Example) Time until soft start finishes at PWM frequency 25 kHz and $\mathrm{PWM}=\mathrm{H}$ time $16 \mu \mathrm{~s}$
According to soft start time typ4.3ms
$\mathrm{t}_{\text {soft }}=16 \mu \mathrm{~s}-15 \mu \mathrm{~s}=1 \mu \mathrm{~s}$
Soft start time/ $\mathrm{t}_{\text {soff }} /$ PWM frequency $=4300 \mu \mathrm{~s} / 1 \mu \mathrm{~s} / 25 \mathrm{kHz}=4300 / 25 \mathrm{kHz}=172 \mathrm{~ms}$

At light dimming of PWM terminal (after soft start finishes)


Figure 26. Input timing (after soft start)

|  | Name | Unit | Min. | Typ. | Max. |
| :---: | :--- | :---: | :---: | :---: | :---: |
| t1 | Power supply rising time | $\mu \mathrm{s}$ | 100 | - | - |
| t2 | Power supply-ENABLE time | $\mu \mathrm{s}$ | 0 | - | - |
| t3 | ENABLE rising time | $\mu \mathrm{s}$ | 0 | - | 100 |
| t4 | ENABLE falling time | $\mu \mathrm{s}$ | 0 | - | 100 |
| t5 | ENABLE low width | $\mu \mathrm{s}$ | 50 | - | - |
| t6 | Power supply-PWM time | $\mu \mathrm{s}$ | 0 | - | - |
| t7 | PWM rising time | $\mu \mathrm{s}$ | 0 | - | 100 |
| t8 | PWM high width | $\mu \mathrm{s}$ | 5 | - | - |
| t9 | PWM falling time | $\mu \mathrm{s}$ | 0 | - | 100 |
| t10 | PWM low width | $\mu \mathrm{s}$ | 5 | - | - |
| t11 | PWM frequency | $\mu \mathrm{s}$ | 40 | 5000 | 10000 |
| t12 | ENABLE (H)->PWM (H) time | $\mu \mathrm{s}$ | 0 | - | - |
| t13 | ENABLE (L)->PWM (L) time | $\mu \mathrm{s}$ | 0 | - | - |
| t14 | PWM (L)->ENABLE (L) time | $\mu \mathrm{s}$ | 0 | - | - |
| t15 | PWM high width (while soft start) | $\mu \mathrm{s}$ | 15 | - | - |
| H | Operating voltage | V | 4.2 | 12 | 27 |
| L | Non operating voltage | V | - | - | 4.2 |

## -How to select the number of LED strings of the current driver

When the number of LED strings of the current driver is reduced, the un-select can be set the matter that the unnecessary CH 1 to 8 terminal is opened. When it uses with 6 lines and so on, it can correspond to it by becoming 2 unnecessary lines to open.

When VOUT wake up, VOUT boost up until OVP voltage. Once IC detect OVP, VOUT don't boost up until OVP from next start up. To set PWM and ENABLE to L, IC reset CH7, 8 status as Figure 27. When VOUT wake up, CH8 (open terminal) and CH 1 are selected as Figure 28.


Figure 27. Select the number of CH lines 1


Figure 28. Select the number of CH lines 2 (wake up)

## - Start control (ENABLE) and select LED current driver (PWM)

This IC can control the IC system by ENABLE, and IC can power off compulsory by setting 0.8 V or below. Also, It powers on ENABLE is at more than 2.0 V .
After it's selected to ENABLE=H, When it is selected at PWM=H, LED current decided with ISET resistance flow. Next, When it is selected at PWM=L, LED current stop to flow.

| ENABLE | PWM | IC |  |
| :---: | :---: | :---: | :--- |
| 0 | 0 | Off | OFF |
| 1 | 0 | On | OFF |
| 0 | 1 | Off | OFF |
| 1 | 1 | On | Current decided with ISET |

## -LED current setting range

LED current can set up Normal current by resistance value (RISET) connecting to ISET voltage.
Setting of each LED current is given as shown below.
RISET = 720/ILEDmax
Also, Normal current setting range is 10 mA to 30 mA . LED current becomes a leak current MAX $2 \mu \mathrm{~A}$ at OFF setting.
ISET Normal current setting example

| RISET | LED current |
| :---: | :---: |
| $24 \mathrm{k} \Omega(E 24)$ | 30.0 mA |
| $30 \mathrm{k} \Omega(E 24)$ | 24.0 mA |
| $36 \mathrm{k} \Omega(E 24)$ | 20.0 mA |
| $43 \mathrm{k} \Omega(E 24)$ | 16.7 mA |
| $68 \mathrm{k} \Omega(E 12)$ | 10.6 mA |

## - Frequency setting range

Switching frequency can be set up by resistance value (RFSET) connecting to FSET port. Setting of frequency is given as shown below.
Also, Frequency setting range is 0.60 MHz to 1.60 MHz .
FSET frequency setting example

| RFSET | frequency |
| :---: | :---: |
| $130 \mathrm{k} \Omega(E 96)$ | 0.57 MHz |
| $56 \mathrm{k} \Omega(E 24)$ | 1.25 MHz |
| $43 \mathrm{k} \Omega(E 24)$ | 1.59 MHz |

Max Duty example

| Frequency | Max Duty[\%] |  |  |
| :---: | :---: | :---: | :---: |
|  | Min | Typ | Max |
| 0.57 MHz | - | 96.0 | - |
| 1.25 MHz | 91.0 | 95.0 | 99.0 |
| 1.59 MHz | - | 92.0 | - |

Min Duty example

| Frequency | Min Duty[\%] |  |  |
| :---: | :---: | :---: | :---: |
|  | Min | Typ | Max |
| 1.25 MHz | - | 20 | - |

## -PWM dimming

Current driver PWM control is controlled by providing PWM signal to PWM port, as it is show in Figure 29. The current set up with ISET is chosen as the H section of PWM and the current is off as the L section. Therefore, the average LED current is increasing in proportion to duty cycle of PWM signal. This method that it lets internal circuit and DC/DC to work, because it becomes to switch the driver, the current tolerance is a few when the PWM brightness is adjusted, it makes it possible to brightness control until $5 \mu \mathrm{~s}$ ( $\mathrm{Min} 0.1 \%$ at 200 Hz ). And, don't use for the brightness control, because effect of ISET changeover is big under $1 \mu \mathrm{~s}$ ON time and under $1 \mu \mathrm{~s}$ OFF time. Typical PWM frequency is 100 Hz to 25 kHz .


Figure 29. PWM sequence
Conditions : 8serial 6parallel, LED current=20mA/ch, $\mathrm{VIN}=7 \mathrm{~V}, \mathrm{Ta}=25^{\circ} \mathrm{C}$, Output capacitor $=2.2 \mu \mathrm{~F}(50 \mathrm{~V} / \mathrm{B} 3)$

## - Analog dimming

BD6142AMUV control LED current according analog input (ABC terminal). For ABC voltage = typ 0.733 V , LED current can set up Normal current by resistance value (RISET) connecting to ISET voltage. To decrease ABC voltage, LED current decrease, and to increase $A B C$ voltage, LED current increase.

Please set max LED current to check LED current setting range of P. 17
Please care that ABC voltage of max LED current is 0.733 V
ABC input range is 0.05 V to 0.9 V (Target).
This dimming is effected by ISET tolerance as follows.
When you don't use analog dimming, please set condenser to $A B C$ terminal. Until the condenser of ABC terminal is finished to charge, LED current increase with that speed.
The resister between 1.2 V and ABC terminal is $120.9 \mathrm{k} \Omega$.
Please select the capacitor to care charge time.


Figure 30. Analog dimming application


Figure 31. PWM dimming application


Figure 32. ILED vs $A B C$ voltage

## -Coil selection

The DC/DC is designed by more than $4.7 \mu \mathrm{H}$. When L value sets to a lower value, it is possibility that the specific sub-harmonic oscillation of current mode DC / DC will be happened. Please do not let $L$ value to $3.3 \mu \mathrm{H}$ or below.
And, $L$ value increases, the phase margin of DC / DC becomes to zero. Please enlarge the output capacitor value when you increase L value. Please select lower DC resistance (DCR) type, efficiency still relies on the DCR of Inductor.
Please estimate Peak Current of Coil. Peak current can be calculated as following.

## Peak Current calculation

<The estimate of the current value which need for the normal operation>
As over current detector of this IC is detected the peak current, it have to estimate peak current to flow to the coil by operating condition.
In case of, $\quad$ - Supply voltage of coil $=$ Vın

- Inductance value of coil = L
- Switching frequency $=$ fsw $(\mathrm{Min}=1.0 \mathrm{MHz}, \operatorname{Typ}=1.25 \mathrm{MHz}, \mathrm{Max}=1.5 \mathrm{MHz})$
- Output voltage = VOUT
- Total LED current = ILED
- Average current of coil = lave
- Peak current of coil = Ipeak
- Cycle of Switching = T
- Efficiency = eff (Please set up having margin)
- ON time of switching transistor = Ton
- ON Duty = D

```
CCM: Ipeak = (Vın / L) }\times(1/fsw)\times(1-( Vın / VOUT)), DCM: Ipeak = (Vın / L) > Ton
lave=( VOUT \times IOUT / VIn) / eff
Ton=(lave }\times(1-\textrm{V}\mathrm{ In / VOUT) }\times(1/fsw)\times(L/VIn)\times2) 1/2
```


## Each current is calculated.

As peak current varies according to whether there is the direct current superposed, the next is decided.
CCM: $\quad(1-\mathrm{VIn} / \mathrm{VOUT}) \times(1 / f s w)<$ Ton $\rightarrow$ peak current $=$ Ipeak $/ 2+$ lave
DCM: $\quad(1-\mathrm{V}$ ın $/ \mathrm{VOUT}) \times(1 / \mathrm{fsw})>$ Ton $\rightarrow$ peak current $=\mathrm{V} \mathrm{In} / \mathrm{L} \times$ Ton
(Example 1)
In case of, $\mathrm{V} \mathrm{In}=7.0 \mathrm{~V}, \mathrm{~L}=10 \mu \mathrm{H}, \mathrm{fsw}=1.2 \mathrm{MHz}, \mathrm{VOUT}=32 \mathrm{~V}$, $\mathrm{ILED}=120 \mathrm{~mA}$, Efficiency $=88 \%$
lave $=(32 \times 120 \mathrm{~m} / 7) / 88 \%=0.62 \mathrm{~A}$
Ton $=(0.62 \times(1-7 / 32) \times(1 / 1.2 \mathrm{M}) \times(10 \mu / 7) \times 2)^{1 / 2}=1.07 \mu \mathrm{~s}$
(1- Vin $/ \mathrm{VOUT}) \times(1 / \mathrm{fsw})=0.65 \mu \mathrm{~s}<\operatorname{Ton}(1.07 \mu \mathrm{~s}) \mathrm{CCM}$
Ipeak $=(7 / 10 \mu) \times(1 / 1.2 \mathrm{M}) \times(1-(7 / 32))=0.46 \mathrm{~A}$
Peak current $=0.46 \mathrm{~A} / 2+0.62 \mathrm{~A}=0.85 \mathrm{~A}$
(Example 2)
In case of, $\mathrm{VIn}=16.0 \mathrm{~V}, \mathrm{~L}=10 \mu \mathrm{H}, \mathrm{fsw}=1.2 \mathrm{MHz}, \mathrm{VOUT}=32 \mathrm{~V}, \mathrm{ILED}=120 \mathrm{~mA}$, Efficiency $=88 \%$
lave $=(32 \times 120 \mathrm{~m} / 16.0) / 88 \%=0.27 \mathrm{~A}$
Ton $=(0.27 \times(1-16 / 32) \times(1 / 1.2 \mathrm{M}) \times(10 \mu / 16) \times 2)^{1 / 2}=0.37 \mu \mathrm{~s}$
(1- Vin $/ \mathrm{VOUT}) \times(1 / \mathrm{fsw})=0.41 \mu \mathrm{~s}>\operatorname{Ton}(0.37 \mu \mathrm{~s}) \quad \mathrm{DCM}$
Ipeak $=$ Vin $/ \mathrm{L} \times$ Ton $=16 / 10 \mu \times 0.37 \mu \mathrm{~s}=0.59 \mathrm{~A}$
Peak current $=0.59 \mathrm{~A}$
*When too large current is set, output overshoot is caused, be careful enough because it is led to break down of the IC in case of the worst.

DCM/CCM calculation
Discontinuous Condition Mode (DCM) and Continuous Condition Mode (CCM) are calculated as following.
CCM: $\quad L>$ VOUT $\times D \times(1-D)^{2} \times T /(2 \times$ LLED $)$
DCM: $\quad \mathrm{L}<$ VOUT $\times \mathrm{D} \times(1-\mathrm{D})^{2} \times \mathrm{T} /(2 \times$ ILED $)$
*D $=1-$ VIn $/$ VOUT
(Example 1)
In case of, $\mathrm{VIn}=7.0 \mathrm{~V}, \mathrm{~L}=10 \mu \mathrm{H}, \mathrm{fsw}=1.2 \mathrm{MHz}$, VOUT $=32 \mathrm{~V}$, ILED $=120 \mathrm{~mA}$

$$
\begin{aligned}
& \operatorname{VOUT} \times \mathrm{D} \times(1-\mathrm{D})^{2} \times \mathrm{T} /(2 \times \mathrm{ILED})=32 \times(1-7 / 32) \times(7 / 32)^{2} \times 1 /\left(1.2 \times 10^{6}\right) /(2 \times 0.12)=4.15 \mu<\mathrm{L}(10 \mu \mathrm{H}) \\
& \rightarrow \mathrm{CCM}
\end{aligned}
$$

## (Example 2)

In case of, V In $=12.0 \mathrm{~V}, \mathrm{~L}=10 \mu \mathrm{H}$, fsw $=1.2 \mathrm{MHz}$, VOUT $=32 \mathrm{~V}$, ILED $=60 \mathrm{~mA}$

$$
\operatorname{VOUT} \times \mathrm{D} \times(1-\mathrm{D})^{2} \times \mathrm{T} /(2 \times \mathrm{ILED})=32 \times(1-12 / 32) \times(12 / 32)^{2} \times 1 /\left(1.2 \times 10^{6}\right) /(2 \times 0.06)=19.5 \mu>\mathrm{L}(10 \mu \mathrm{H})
$$

$\rightarrow$ DCM

## - OUTPUT Capacitor selection

Output Capacitor smoothly keeps output voltage and supplies LED current. Output Voltage consists of Charge (FET ON) and Discharge (LED current). So Output voltage has Output ripple Voltage every FET switching.
Output ripple voltage is calculated as following.
Output ripple Voltage

| - Switching cycle = T | - Total LED current = ILED |
| :--- | :--- |
| - Switching ON duty = D | - Output ripple Voltage $=$ Vripple |
| - Output Capacitor = COUT | - Output Capacitor $($ real value $)=$ Creal |
| - Decreasing ratio of Capacitor $=$ Cerror |  |

Creal $=$ COUT $\times$ Cerror $\quad$ (Capacitor value is decreased by Bias, so)
Creal $=$ ILED $\times \mathrm{D} \times \mathrm{T} /$ Vripple
COUT $=$ ILED $\times \mathrm{D} \times \mathrm{T} /$ Vripple $/$ Cerror
(Example 1)
In case of, $\mathrm{VIN}=12.0 \mathrm{~V}$, fsw $=1.2 \mathrm{MHz}$, $\mathrm{VOUT}=32 \mathrm{~V}$, $\operatorname{ILED}=120 \mathrm{~mA}, \mathrm{COUT}=8.8 \mu \mathrm{~F}$, Cerror $=50 \%$
$\mathrm{T}=1 / 1.2 \mathrm{MHz}$
$\mathrm{D}=1-\mathrm{VIN} /$ VOUT $=1-12 / 32$

Vripple $=\operatorname{ILED} \times \mathrm{D} \times \mathrm{T} /($ COUT $\times$ Cerror $)=120 \mathrm{~mA} \times(1-12 / 32) / 1.2 \mathrm{MHz} /(8.8 \mu \mathrm{~F} \times 0.5)$ $=14.2 \mathrm{mV}$


Figure 33. Bias Characteristics of Capacitor

## -The separations of the IC Power supply and coil Power supply

This IC can work in separating the power source in both IC power supply and coil power supply. With this application, it can obtain that decrease of IC power consumption, and the applied voltage exceeds IC rating 27 V .

That application is shown in below Figure 34. The higher voltage source is applied to the power source of coil that is connected from an adapter etc. Next, the IC power supply is connected with a different coil power supply. Under the conditions for inputting from 4.2 V to 5.5 V into IC VIN, please follow the recommend design in Figure 34. It connects VIN terminal and VDC terminal together at ICOUTside.

When the coil power supply is applied, it is no any problem even though IC power supply is the state of OV. Although IC power supply is set to 0 V , pull-down resistance is arranged for the power off which cuts off the leak route from coil power supply in IC inside, the leak route is cut off. And, there is no power on-off sequence of coil power supply and IC power supply.

Separate VIN and Coil power supply


Connect VIN and VDC terminals


Figure 34. Application at the time of power supply isolation

## -Layout

In order to make the most of the performance of this IC, its PCB layout is very important. Characteristics such as efficiency and ripple and the likes change greatly with layout patterns, which please note carefully.


Figure 35. Schematic
<Input bypath capacitor CIN ( $10 \mu \mathrm{~F}$ )>
Put input bypath capacitor CIN (10 $\mu \mathrm{F}$ ) as close as possible between coilL1 and PGND pin.
<Smoothing capacitor CVDC1 $(2.2 \mu \mathrm{~F})$ of the regulator>
Connect smoothing capacitor CVDC1 $(2.2 \mu \mathrm{~F})$ as close as possible between VDC pin and GND.
<Schottky barrier diode SBD>
Connect schottky barrier diode SBD as close as possible between coil1and LX pin.
<Output capacitor COUT1>
Connect output capacitor COUT1 between cathode of SBD and PGND.
Make both PGND sides of CVIN and COUT1 as close as possible.
<LED current setting resistor RISET(36k $)$ )>>
Connect LED current setting resistor RISET(36k $\Omega$ ) as close as possible between ISET pin and GND.
There is possibility to oscillate when capacity is added to ISET terminal, so pay attention that capacity isn't added.
<Analog dimming pin smoothing capacitor CABC (1nF)>
Put analog dimming pin smoothing capacitor CABC (1nF) close to $A B C$ pin and do not extend the wiring to prevent noise increasing and also LED current waving.
<Frequency setting resistor( $56 \mathrm{~K} \Omega$ )>
Put frequency setting resistor( $56 \mathrm{~K} \Omega$ ) as close as possible between FSET pin and GND.
<Over voltage limit setting resistor ROVP1(2.2M $\Omega$ ) and ROVP2(68K $\Omega$ )
Put over voltage limit setting resistor ROVP1 $(2.2 \mathrm{M} \Omega)$ and ROVP2 $(68 \mathrm{~K} \Omega)$ as close as possible to OVP pin and do not extend the wiring to prevent noise increasing and also detecting over voltage protection in error.
<GMAMP setting resistor RCMP $(1 \mathrm{k} \Omega)$ and CCMP $(1 \mathrm{nF})$ for phase compensation > Put GMAMP setting resistor $\operatorname{RCMP}(1 \mathrm{~K} \Omega)$ and $\operatorname{CCMP}(22 \mathrm{nF})$ as close as possible to COMP pin and do not extend the wiring to prevent noise increasing and also oscillating.
<Connect to GND and PGND>
GND is analog ground, and PGND is power ground. PGND might cause a lot of noise due to the coil current of PGND.
Try to connect with analog ground, after smoothing with input bypath capacitor CVIN and output capacitor COUT1.
<Heat radiation of back side PAD>
PAD is used for improving the efficiency of IC heat radiation. Solder PAD to GND pin (analog ground).
Moreover, connect ground plane of board using via as shown in the patterns of next page.
The efficiency of heat radiation improves according to the area of ground plane.
<Others>
When those pins are not connected directly near the chip, influence is give to the performance of BD6142AMUV, and may limit the current drive performance. As for the wire to the inductor, make its resistance component small so as to reduce electric power consumption and increase the entire efficiency.

## -Recommended PCB layout



Figure 36. Top Copper trace layer


Figure 37. Middle1 Copper trace layer


Figure 38. Middle2 Copper trace layer


Figure 39. Bottom Copper trace layer

## -Selection of external parts

Recommended external parts are as shown below.
When to use other parts than these, select the following equivalent parts.

- Coil

| Value | Manufacturer | Product number | Size (mm) |  |  | DC current <br> $(\mathrm{mA})$ | DCR <br> $(\Omega)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | L | W | $\mathrm{H}_{(\mathrm{MAX})}$ |  |  |
| $4.7 \mu \mathrm{H}$ | TDK | LTF5022T-4R7N2R0-LC | 5.0 | 5.2 | 2.2 | 2000 | 0.073 |
| $4.7 \mu \mathrm{H}$ | TOKO | A915AY-4R7M | 5.2 | 5.2 | 3.0 | 1870 | 0.045 |
| $10 \mu \mathrm{H}$ | TOKO | A915AY-100M | 5.2 | 5.2 | 3.0 | 1400 | 0.140 |
| $10 \mu \mathrm{H}$ | TDK | LTF5022T-100M1R4-LC | 5.0 | 5.2 | 2.2 | 1400 | 0.140 |
| $10 \mu \mathrm{H}$ | TOKO | B1047AS-100M | 7.6 | 7.6 | 5.0 | 2700 | 0.053 |

- Capacitor

| Value | Pressure | Manufacturer | Product number | Size |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | L | W | H |
| $10 \mu \mathrm{~F}$ | 25 V | MURATA | GRM31CB31E106KA75 | 3.2 | 1.6 | 1.6 |
| $4.7 \mu \mathrm{~F}$ | 25 V | MURATA | GRM319R61E475K | 3.2 | 1.6 | $0.85 \pm 0.1$ |
| $2.2 \mu \mathrm{~F}$ | 50 V | TDK | C3225JB1H225K | 3.2 | 2.5 | $2.0 \pm 0.2$ |
| $2.2 \mu \mathrm{~F}$ | 50 V | MURATA | GRM31CB31H225K | 3.2 | 1.6 | 1.6 |
| $2.2 \mu \mathrm{~F}$ | 50 V | Panasonic | ECJHVB1H225K | 3.2 | 1.6 | 0.85 |
| $2.2 \mu \mathrm{~F}$ | 10 V | MURATA | GRM188B31A225K | 1.6 | 0.8 | 0.8 |
| $0.1 \mu \mathrm{~F}$ | 50 V | MURATA | GRM188B31H104K | 1.6 | 0.8 | 0.8 |
| $0.1 \mu \mathrm{~F}$ | 10 V | MURATA | GRM188B31A104K | 1.6 | 0.8 | 0.8 |
| 0.022 F | 10 V | MURATA | GRM155B31H223K | 1.0 | 0.5 | 0.5 |
| 470 FF | 50 V | MURATA | GRM155B11H471K | 1.0 | 0.5 | 0.5 |

- Resistor

| Value | Tolerance | Manufacturer | Product number | Size $(\mathrm{mm})$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | L | W | H |
| $2.2 \mathrm{M} \Omega$ | $\pm 1.0 \%$ | ROHM | MCR03PZPZFX2204 | 1.6 | 0.8 | 0.45 |
| $91 \mathrm{k} \Omega$ | $\pm 0.5 \%$ | ROHM | MCR03PZPZD9102 | 1.6 | 0.8 | 0.45 |
| $75 \mathrm{k} \Omega$ | $\pm 0.5 \%$ | ROHM | MCR03PZPZD7502 | 1.6 | 0.8 | 0.45 |
| $68 \mathrm{k} \Omega$ | $\pm 0.5 \%$ | ROHM | MCR03PZPZD6802 | 1.6 | 0.8 | 0.45 |
| $56 \mathrm{k} \Omega$ | $\pm 0.5 \%$ | ROHM | MCR03PZPZD5602 | 1.6 | 0.8 | 0.45 |
| $36 \mathrm{k} \Omega$ | $\pm 0.5 \%$ | ROHM | MCR03PZPZD3602 | 1.6 | 0.8 | 0.45 |
| $10 \mathrm{k} \Omega$ | $\pm 1.0 \%$ | ROHM | MCR03PZPZF103 | 1.6 | 0.8 | 0.45 |
| $1 \mathrm{k} \Omega$ | $\pm 0.5 \%$ | ROHM | MCR03PZPZD1002 | 1.6 | 0.8 | 0.45 |
| $330 \Omega$ | $\pm 0.5 \%$ | ROHM | MCR03PZPZD3300 | 1.6 | 0.8 | 0.45 |

- SBD

| Pressure | Manufacturer | Product number | Size (mm) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | L | W | H |
| 60 V | ROHM | RB160M-60 | 3.5 | 1.6 | 0.8 |

The coil is the part that is most influential to efficiency. Select the coil whose direct current resistor (DCR) and current inductance characteristic is excellent. BD6142AMUV is designed for the inductance value of $10 \mu \mathrm{H}$. Don't use the inductance value less than $3.3 \mu \mathrm{H}$. Select a capacitor of ceramic type with excellent frequency and temperature characteristics.
Further, select Capacitor to be used with small direct current resistance.

## - About heat loss

In heat design, operate the DC/DC converter in the following condition.
(The following temperature is a guarantee temperature, so consider the margin.)

1. Ambient temperature Ta must be less than $85^{\circ} \mathrm{C}$.
2. The loss of IC must be less than dissipation Pd.

## - Application example

1. ESD \& Flicker (wakeup (duty 5\%@200Hz))

LED current: 20 mA (ISET $=36 \mathrm{k} \Omega$ )
LED: 10 LEDs in series, 3 strings in parallel


Figure 40. Application example of 10 inch panel


Figure 41. Layout example for ESD protection
2. Analog Dimming and monitoring FAULT terminal

LED current: 20 mA (ISET $=36 \mathrm{k} \Omega$ )
LED: 10 LEDs in series, 8 strings in parallel


Figure 42. Application example of Analog dimming
3. Application example of CH terminal connected

LED current: 20 mA (ISET = 36k $\Omega$ )
LED: 3LEDs $\times 12$ strings


Figure 43. Application example of CH terminal connected

## -Operational Notes

(1) Absolute Maximum Ratings

An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.
(2) Operating conditions

These conditions represent a range within which characteristics can be provided approximately as expected. The electrical characteristics are guaranteed under the conditions of each parameter.
(3) Reverse connection of power supply connector

The reverse connection of power supply connector can break down ICs. Take protective measures against the breakdown due to the reverse connection, such as mounting an external diode between the power supply and the IC's power supply terminal.
(4) Power supply line

Design PCB pattern to provide low impedance for the wiring between the power supply and the GND lines. In this regard, for the digital block power supply and the analog block power supply, even though these power supplies has the same level of potential, separate the power supply pattern for the digital block from that for the analog block, thus suppressing the diffraction of digital noises to the analog block power supply resulting from impedance common to the wiring patterns. For the GND line, give consideration to design the patterns in a similar manner.
Furthermore, for all power supply terminals to ICs, mount a capacitor between the power supply and the GND terminal. At the same time, in order to use an electrolytic capacitor, thoroughly check to be sure the characteristics of the capacitor to be used present no problem including the occurrence of capacity dropout at a low temperature, thus determining the constant.
(5) GND voltage

Make setting of the potential of the GND terminal so that it will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.
(6) Short circuit between terminals and erroneous mounting

In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.
(7) Operation in strong electromagnetic field

Be noted that using ICs in the strong electromagnetic field can malfunction them.
(8) Inspection with set PCB

On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.
(9) Input terminals

In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals, such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. In addition, even if the power supply voltage is applied, apply to the input terminals a voltage lower than the power supply voltage or within the guaranteed value of electrical characteristics.
(10) Ground wiring pattern

If small-signal GND and large-current GND are provided, It will be recommended to separate the large-current GND pattern from the small-signal GND pattern and establish a single ground at the reference point of the set PCB so that resistance to the wiring pattern and voltage fluctuations due to a large current will cause no fluctuations in voltages of the small-signal GND. Pay attention not to cause fluctuations in the GND wiring pattern of external parts as well.
(11) External capacitor

In order to use a ceramic capacitor as the external capacitor, determine the constant with consideration given to a degradation in the nominal capacitance due to DC bias and changes in the capacitance due to temperature, etc.
(12) Thermal shutdown circuit (TSD)

When junction temperatures become $130^{\circ} \mathrm{C}$ (typ.) or higher, the thermal shutdown circuit operates and turns a switch OFF. The thermal shutdown circuit, which is aimed at isolating the LSI from thermal runaway as much as possible, is not aimed at the protection or guarantee of the LSI. Therefore, do not continuously use the LSI with this circuit operating or use the LSI assuming its operation.
(13) Thermal design

Perform thermal design in which there are adequate margins by taking into account the permissible dissipation (Pd) in actual states of use.
(14) Selection of coil

Select the low DCR inductors to decrease power loss for DC/DC converter.

Status of this document
The Japanese version of this document is formal specification. A customer may use this translation version only for a reference to help reading the formal version.
If there are any differences in translation version of this document formal version takes priority.

## -Ordering Information



## - Marking Diagram



## -Physical Dimension Tape and Reel Information

## VQFN024V4040



## - Revision History

| Date | Revision |  | Changes |
| :---: | :---: | :--- | :---: |
| 03.Dec.2012 | 001 | New Release |  |

## Notice

## Precaution on using ROHM Products

1. Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment ${ }^{(N o t e}{ }^{1}$ ), transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.
(Note1) Medical Equipment Classification of the Specific Applications

| JAPAN | USA | EU | CHINA |
| :---: | :---: | :---: | :---: |
| CLASSIII | CLASSIII | CLASS II b | CLASSIII |
|  |  | CLASSIII |  |

2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
[a] Installation of protection circuits or other protective devices to improve system safety
[b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure
3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
[a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
[b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
[c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl 2 , $\mathrm{H}_{2} \mathrm{~S}, \mathrm{NH}_{3}, \mathrm{SO}_{2}$, and $\mathrm{NO}_{2}$
[d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
[e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
[f] Sealing or coating our Products with resin or other coating materials
[g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
[h] Use of the Products in places subject to dew condensation
4. The Products are not subject to radiation-proof design.
5. Please verify and confirm characteristics of the final or mounted products in using the Products.
6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
8. Confirm that operation temperature is within the specified range described in the product specification.
9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

## Precaution for Mounting / Circuit board design

1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

## Precautions Regarding Application Examples and External Circuits

1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

## Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

## Precaution for Storage / Transportation

1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
[a] the Products are exposed to sea winds or corrosive gases, including $\mathrm{Cl} 2, \mathrm{H} 2 \mathrm{~S}, \mathrm{NH} 3, \mathrm{SO} 2$, and NO 2
[b] the temperature or humidity exceeds those recommended by ROHM
[c] the Products are exposed to direct sunshine or condensation
[d] the Products are exposed to high Electrostatic
2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

## Precaution for Product Label

QR code printed on ROHM Products label is for ROHM's internal use only.

## Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

## Precaution for Foreign Exchange and Foreign Trade act

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with ROHM representative in case of export.

## Precaution Regarding Intellectual Property Rights

1. All information and data including but not limited to application example contained in this document is for reference only. ROHM does not warrant that foregoing information or data will not infringe any intellectual property rights or any other rights of any third party regarding such information or data. ROHM shall not be in any way responsible or liable for infringement of any intellectual property rights or other damages arising from use of such information or data.:
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## General Precaution

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