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## LMV2011 High Precision, Rail-to-Rail Output Operational Amplifier

Check for Samples: [LMV2011](#)

### FEATURES

- (For  $V_s = 5V$ , Typical Unless Otherwise Noted)
- Low Ensured  $V_{os}$  Over Temperature  $35\mu V$
- Low Noise with no  $1/f$   $35nV/\sqrt{Hz}$
- High CMRR 130dB
- High PSRR 120dB
- High  $A_{VOL}$  130dB
- Wide Gain-Bandwidth Product 3MHz
- High Slew Rate  $4V/\mu s$
- Low Supply Current  $930\mu A$
- Rail-to-Rail Output 30mV
- No External Capacitors Required

### APPLICATIONS

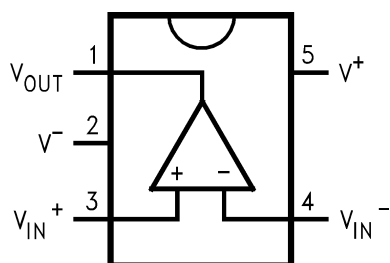
- Precision Instrumentation Amplifiers
- Thermocouple Amplifiers
- Strain Gauge Bridge Amplifier

### DESCRIPTION

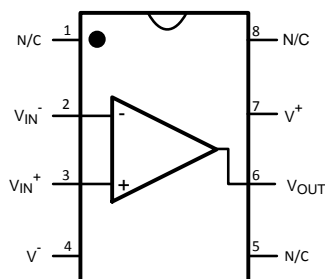
The LMV2011 is a new precision amplifier that offers unprecedented accuracy and stability at an affordable price and is offered in a miniature (5-pin SOT-23) package and in an 8-lead SOIC package. This device utilizes patented techniques to measure and continually correct the input offset error voltage. The result is an amplifier which is ultra stable over time and temperature. It has excellent CMRR and PSRR ratings, and does not exhibit the familiar  $1/f$  voltage and current noise increase that plagues traditional amplifiers. The combination of the LMV2011 characteristics makes it a good choice for transducer amplifiers, high gain configurations, ADC buffer amplifiers, DAC I-V conversion, and any other 2.7V-5V application requiring precision and long term stability.

Other useful benefits of the LMV2011 are rail-to-rail output, a low supply current of  $930\mu A$ , and wide gain-bandwidth product of 3MHz. These extremely versatile features found in the LMV2011 provide high performance and ease of use.

### Connection Diagrams



**Figure 1. 5-Pin SOT-23 (Top View)  
See DBV Package**



**Figure 2. 8-Pin SOIC (Top View)  
See D Package**



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.



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# LMV2011



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## Absolute Maximum Ratings<sup>(1)(2)</sup>

ESD Tolerance	Human Body Model	2000V
	Machine Model	200V
	Supply Voltage	5.5V
Common-Mode Input Voltage	$-0.3 \leq V_{CM} \leq V_{CC} + 0.3V$	
Differential Input Voltage	$\pm$ Supply Voltage	
Current At Input Pin	30mA	
Current At Output Pin	30mA	
Current At Power Supply Pin	50mA	
Junction Temperature (T <sub>J</sub> )	150°C	
Lead Temperature (soldering 10 sec.)	+300°C	

- (1) Absolute Maximum Ratings indicate limits beyond which damage may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and test conditions, see the Electrical Characteristics.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

## Operating Ratings<sup>(1)</sup>

Supply Voltage	2.7V to 5.25V
Storage Temperature Range	-65°C to 150°C
Operating Temperature Range	0°C to 70°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and test conditions, see the Electrical Characteristics.

## 2.7V DC Electrical Characteristics

Unless otherwise specified, all limits ensured for T<sub>J</sub> = 25°C, V<sup>+</sup> = 2.7V, V<sup>-</sup> = 0V, V<sub>CM</sub> = 1.35V, V<sub>O</sub> = 1.35V and R<sub>L</sub> > 1MΩ.

**Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
V <sub>OS</sub>	Input Offset Voltage			0.8	25 <b>35</b>	μV
	Offset Calibration Time			0.5	10 <b>12</b>	ms
TCV <sub>OS</sub>	Input Offset Voltage			0.015		μV/°C
	Long-Term Offset Drift			0.006		μV/month
	Lifetime V <sub>OS</sub> Drift			2.5	5	μV
I <sub>IN</sub>	Input Current			-3		pA
I <sub>OS</sub>	Input Offset Current			6		pA
R <sub>IND</sub>	Input Differential Resistance			9		MΩ
CMRR	Common Mode Rejection Ratio	$-0.3 \leq V_{CM} \leq 0.9V$ $0 \leq V_{CM} \leq 0.9V$		130	95 <b>90</b>	dB
PSRR	Power Supply Rejection Ratio	$2.7V \leq V^+ \leq 5V$		120	95 <b>90</b>	dB
A <sub>VOL</sub>	Open Loop Voltage Gain	R <sub>L</sub> = 10kΩ		130	95 <b>90</b>	dB
		R <sub>L</sub> = 2kΩ		124	90 <b>85</b>	
V <sub>O</sub>	Output Swing	R <sub>L</sub> = 10kΩ to 1.35V V <sub>IN(diff)</sub> = ±0.5V	2.665 <b>2.655</b>	2.68		V
				0.033	0.060 <b>0.075</b>	
		R <sub>L</sub> = 2kΩ to 1.35V V <sub>IN(diff)</sub> = ±0.5V	2.630 <b>2.615</b>	2.65		V
				0.061	0.085 <b>0.105</b>	

## 2.7V DC Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for  $T_J = 25^\circ\text{C}$ ,  $V^+ = 2.7\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{CM} = 1.35\text{V}$ ,  $V_O = 1.35\text{V}$  and  $R_L > 1\text{M}\Omega$ .

**Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$I_O$	Output Current	Sourcing, $V_O = 0\text{V}$ $V_{IN}(\text{diff}) = \pm 0.5\text{V}$		12	5 <b>3</b>	mA
		Sinking, $V_O = 5\text{V}$ $V_{IN}(\text{diff}) = \pm 0.5\text{V}$		18	5 <b>3</b>	
$R_{OUT}$	Output Impedance			0.05		$\Omega$
$I_S$	Supply Current			0.919	1.20 <b>1.50</b>	mA

## 2.7V AC Electrical Characteristics

$T_J = 25^\circ\text{C}$ ,  $V^+ = 2.7\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{CM} = 1.35\text{V}$ ,  $V_O = 1.35\text{V}$ , and  $R_L > 1\text{M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
GBW	Gain-Bandwidth Product			3		MHz
SR	Slew Rate			4		V/ $\mu\text{s}$
$\theta_m$	Phase Margin			60		Deg
$G_m$	Gain Margin			-14		dB
$e_n$	Input-Referred Voltage Noise			35		nV/ $\sqrt{\text{Hz}}$
$i_n$	Input-Referred Current Noise			150		fA/ $\sqrt{\text{Hz}}$
$e_{n,p-p}$	Input-Referred Voltage Noise	$R_S = 100\Omega$ , DC to 10Hz		850		nV <sub>pp</sub>
$t_{rec}$	Input Overload Recovery Time			50		ms
$t_s$	Output Settling Time	$A_V = -1$ , $R_L = 2\text{k}\Omega$ 1V Step	1%	0.9		$\mu\text{s}$
			0.1%	49		
			0.01%	100		

## 5V DC Electrical Characteristics

Unless otherwise specified, all limits ensured for  $T_J = 25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{CM} = 2.5\text{V}$ ,  $V_O = 2.5\text{V}$  and  $R_L > 1\text{M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$V_{OS}$	Input Offset Voltage			0.12	25 <b>35</b>	$\mu\text{V}$
	Offset Calibration Time			0.5	10 <b>12</b>	ms
$TCV_{OS}$	Input Offset Voltage			0.015		$\mu\text{V}/^\circ\text{C}$
	Long-Term Offset Drift			0.006		$\mu\text{V}/\text{month}$
	Lifetime $V_{OS}$ Drift			2.5	5	$\mu\text{V}$
$I_{IN}$	Input Current			-3		pA
$I_{OS}$	Input Offset Current			6		pA
$R_{IND}$	Input Differential Resistance			9		$\text{M}\Omega$
CMRR	Common Mode Rejection Ratio	$-0.3 \leq V_{CM} \leq 3.2$ $0 \leq V_{CM} \leq 3.2$		130	100 <b>90</b>	dB
PSRR	Power Supply Rejection Ratio	$2.7\text{V} \leq V^+ \leq 5\text{V}$		120	95 <b>90</b>	dB
$A_{VOL}$	Open Loop Voltage Gain	$R_L = 10\text{k}\Omega$		130	105 <b>100</b>	dB
		$R_L = 2\text{k}\Omega$		132	95 <b>90</b>	

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### 5V DC Electrical Characteristics (continued)

Unless otherwise specified, all limits ensured for  $T_J = 25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{CM} = 2.5\text{V}$ ,  $V_O = 2.5\text{V}$  and  $R_L > 1\text{M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$V_O$	Output Swing	$R_L = 10\text{k}\Omega$ to $2.5\text{V}$ $V_{IN}(\text{diff}) = \pm 0.5\text{V}$	4.96 <b>4.95</b>	4.978		V
				0.040	0.070 <b>0.085</b>	
		$R_L = 2\text{k}\Omega$ to $2.5\text{V}$ $V_{IN}(\text{diff}) = \pm 0.5\text{V}$	4.895 <b>4.875</b>	4.919		V
				0.091	0.115 <b>0.140</b>	
$I_O$	Output Current	Sourcing, $V_O = 0\text{V}$ $V_{IN}(\text{diff}) = \pm 0.5\text{V}$		15	8 <b>6</b>	mA
		Sinking, $V_O = 5\text{V}$ $V_{IN}(\text{diff}) = \pm 0.5\text{V}$		17	8 <b>6</b>	
$R_{OUT}$	Output Impedance			0.05		$\Omega$
$I_S$	Supply Current per Channel			0.930	1.20 <b>1.50</b>	mA

### 5V AC Electrical Characteristics

$T_J = 25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{CM} = 2.5\text{V}$ ,  $V_O = 2.5\text{V}$ , and  $R_L > 1\text{M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min	Typ	Max	Units
GBW	Gain-Bandwidth Product			3		MHz
SR	Slew Rate			4		V/ $\mu\text{s}$
$\theta_m$	Phase Margin			60		deg
$G_m$	Gain Margin			-15		dB
$e_n$	Input-Referred Voltage Noise			35		nV/ $\sqrt{\text{Hz}}$
$i_n$	Input-Referred Current Noise			150		fA/ $\sqrt{\text{Hz}}$
$e_{n\text{p-p}}$	Input-Referred Voltage Noise	$R_S = 100\Omega$ , DC to 10Hz		850		nV <sub>pp</sub>
$t_{\text{rec}}$	Input Overload Recovery Time			50		ms
$t_s$	Output Settling Time	$A_V = -1$ , $R_L = 2\text{k}\Omega$ 1V Step	1%	0.8		$\mu\text{s}$
			0.1%	36		
			0.01%	100		

## Typical Performance Characteristics

$T_A=25^\circ\text{C}$ ,  $V_S=5\text{V}$  unless otherwise specified.

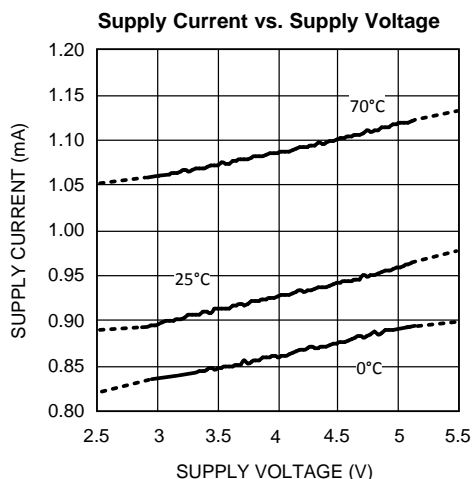


Figure 3.

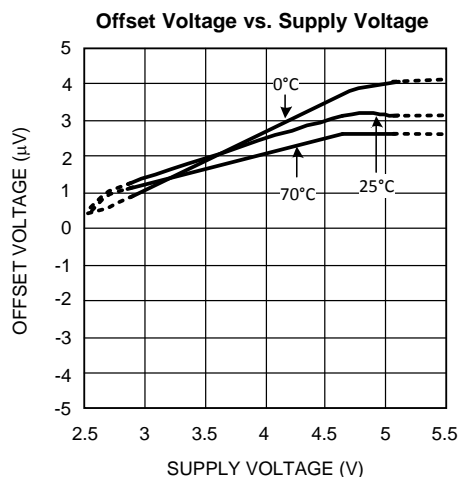


Figure 4.

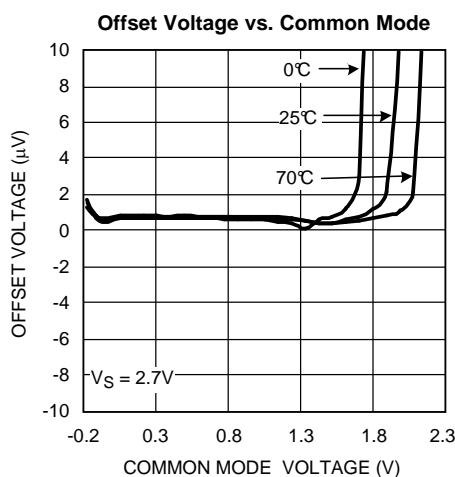


Figure 5.

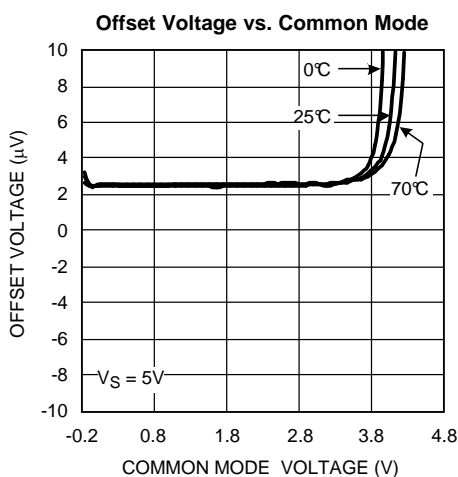


Figure 6.

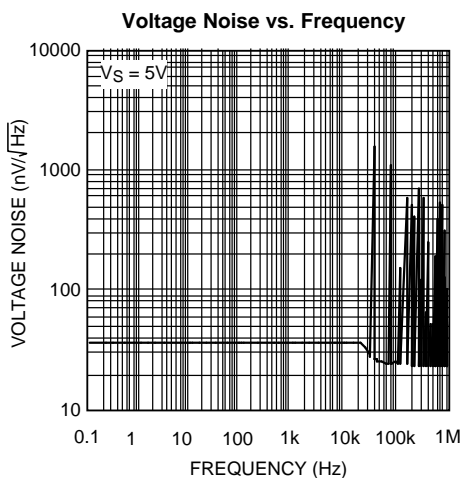


Figure 7.

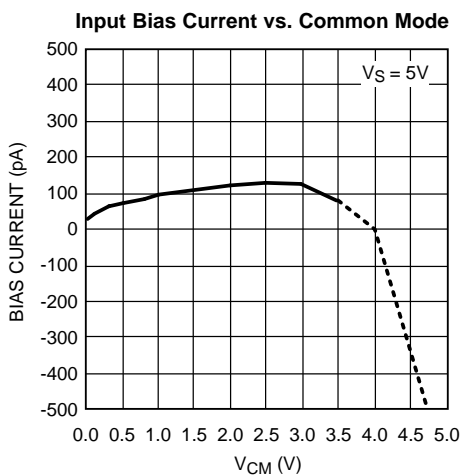


Figure 8.

## LMV2011



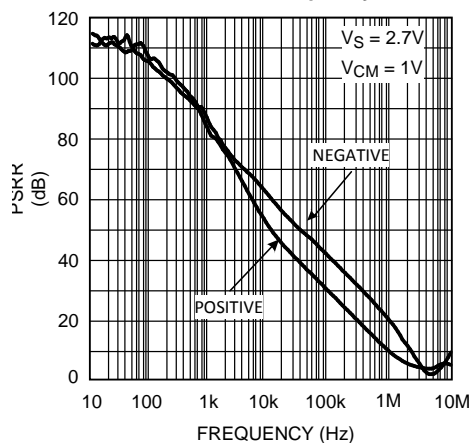
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### Typical Performance Characteristics (continued)

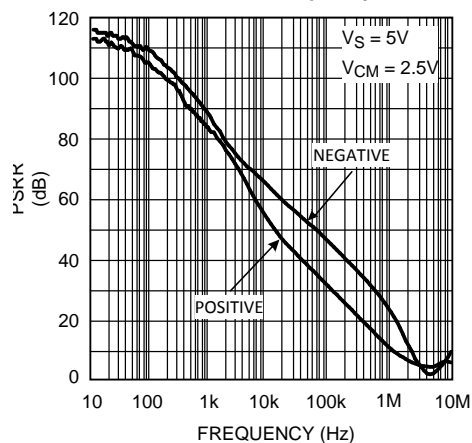
$T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{V}$  unless otherwise specified.

**PSRR vs. Frequency**



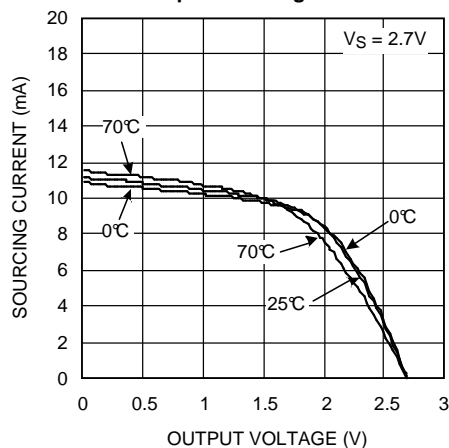
**Figure 9.**

**PSRR vs. Frequency**



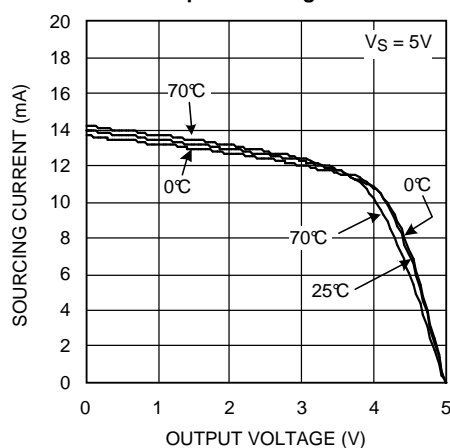
**Figure 10.**

**Output Sourcing @ 2.7V**



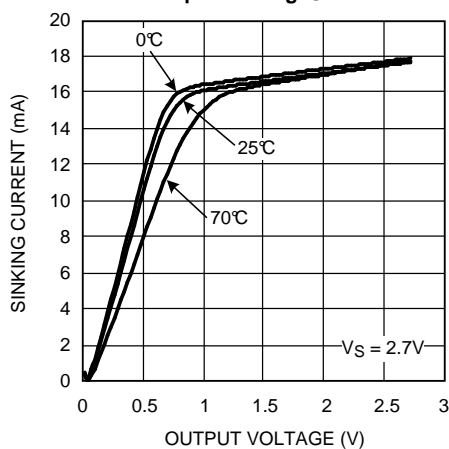
**Figure 11.**

**Output Sourcing @ 5V**



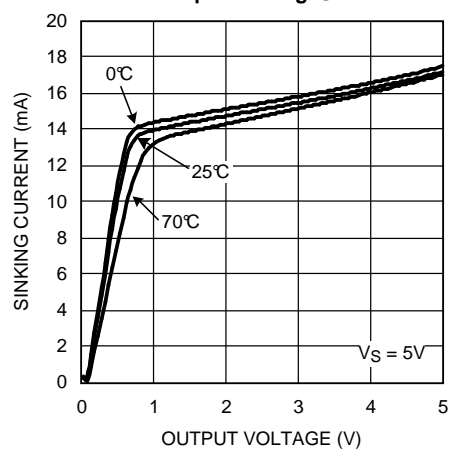
**Figure 12.**

**Output Sinking @ 2.7V**



**Figure 13.**

**Output Sinking @ 5V**

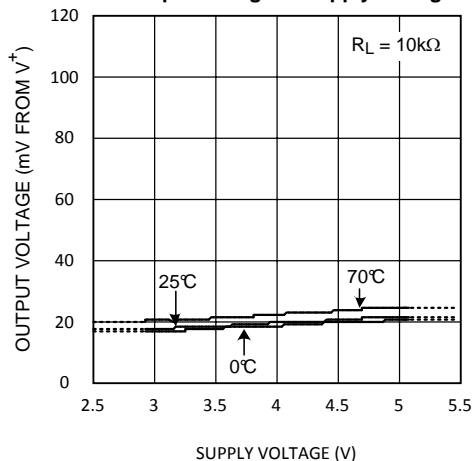


**Figure 14.**

## Typical Performance Characteristics (continued)

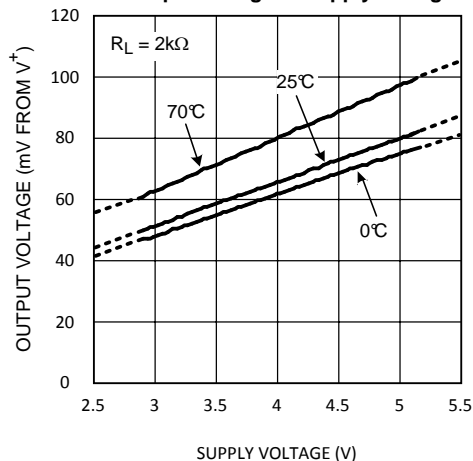
$T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{V}$  unless otherwise specified.

**Max Output Swing vs. Supply Voltage**



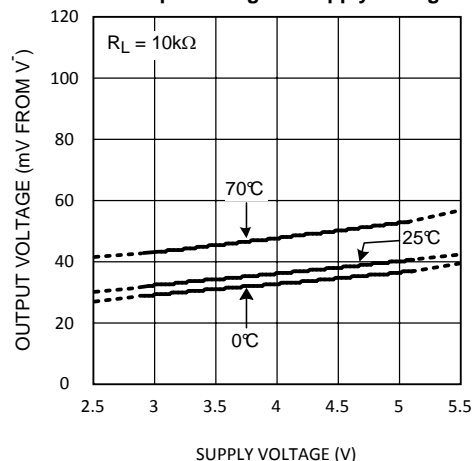
**Figure 15.**

**Max Output Swing vs. Supply Voltage**



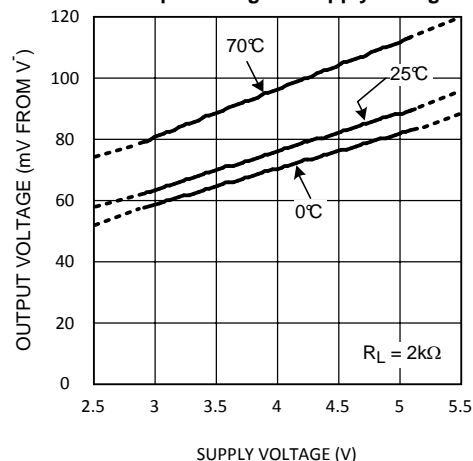
**Figure 16.**

**Min Output Swing vs. Supply Voltage**



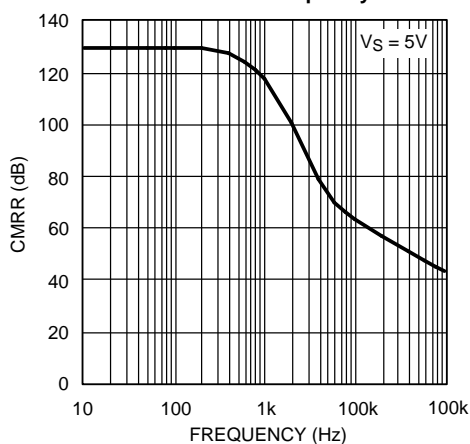
**Figure 17.**

**Min Output Swing vs. Supply Voltage**



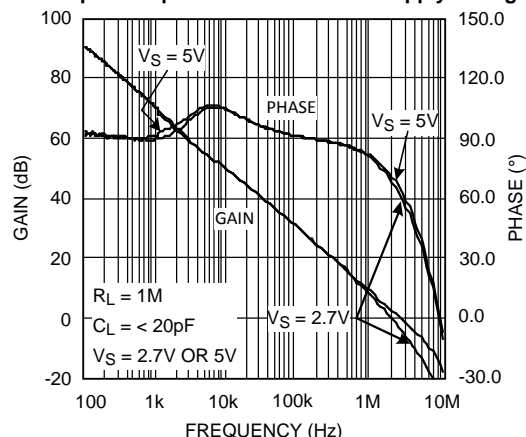
**Figure 18.**

**CMRR vs. Frequency**



**Figure 19.**

**Open Loop Gain and Phase vs. Supply Voltage**



**Figure 20.**



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### Typical Performance Characteristics (continued)

$T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{V}$  unless otherwise specified.

**Open Loop Gain and Phase vs.  $R_L$  @ 2.7V**

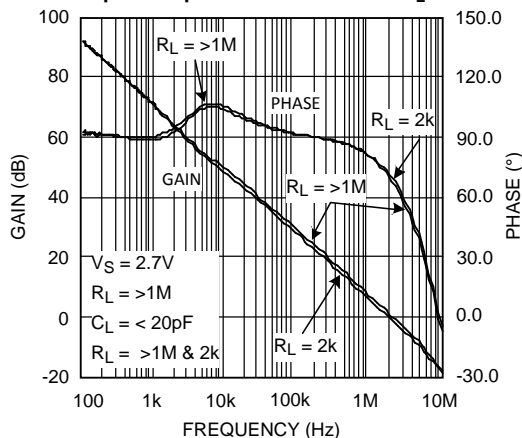


Figure 21.

**Open Loop Gain and Phase vs.  $R_L$  @ 5V**

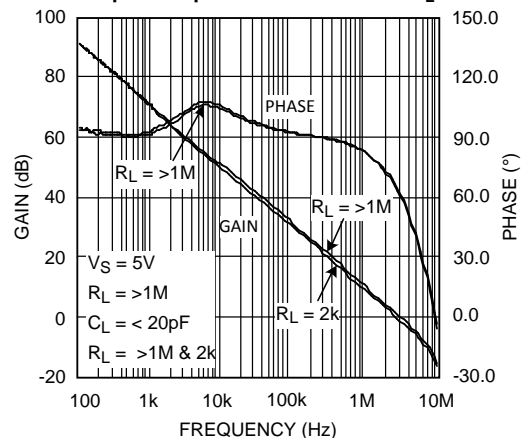


Figure 22.

**Open Loop Gain and Phase vs.  $C_L$  @ 2.7V**

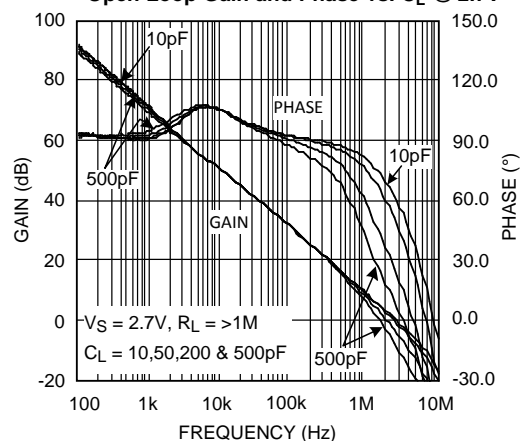


Figure 23.

**Open Loop Gain and Phase vs.  $C_L$  @ 5V**

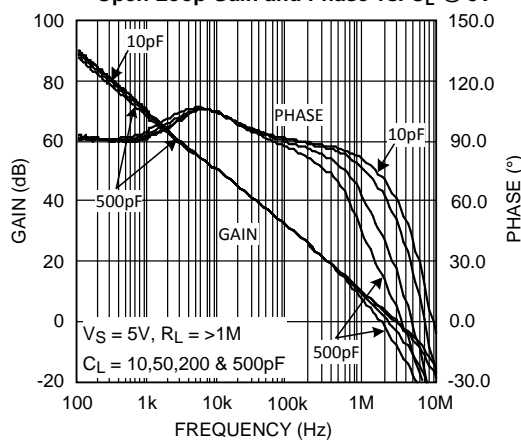


Figure 24.

**Open Loop Gain and Phase vs. Temperature @ 2.7V**

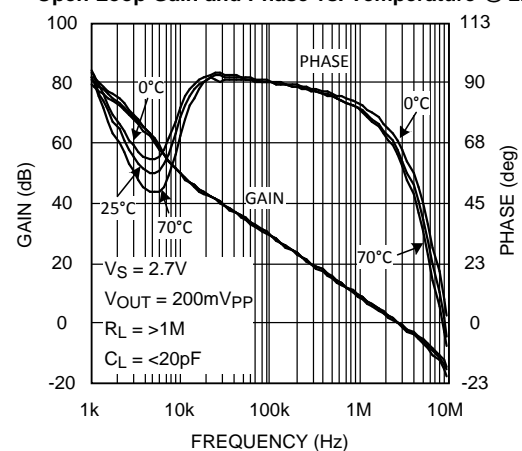


Figure 25.

**Open Loop Gain and Phase vs. Temperature @ 5V**

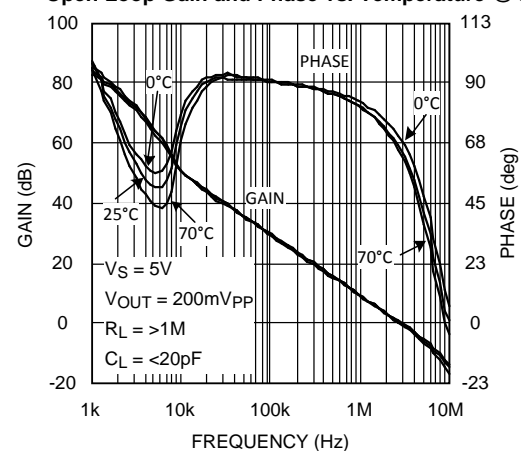
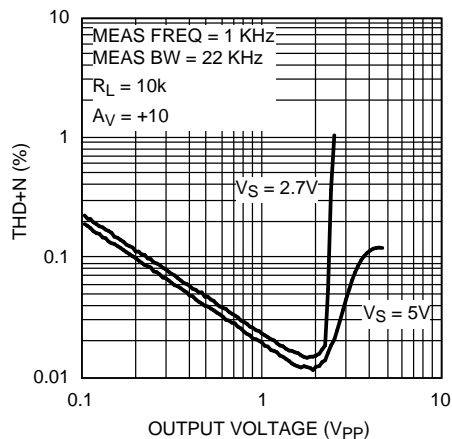


Figure 26.

## Typical Performance Characteristics (continued)

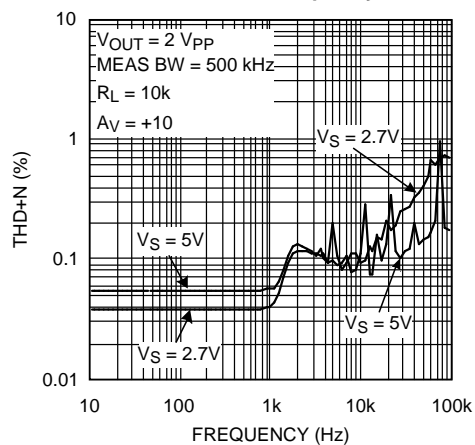
$T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{V}$  unless otherwise specified.

**THD+N vs. AMPL**



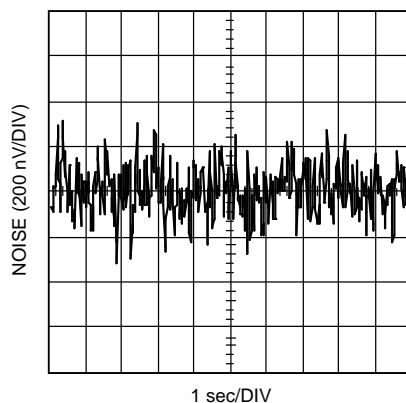
**Figure 27.**

**THD+N vs. Frequency**



**Figure 28.**

**0.1Hz – 10Hz Noise vs. Time**



**Figure 29.**

## LMV2011

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### APPLICATION INFORMATION

#### THE BENEFITS OF LMV2011 NO 1/f NOISE

Using patented methods, the LMV2011 eliminates the 1/f noise present in other amplifiers. That noise, which increases as frequency decreases, is a major source of measurement error in all DC-coupled measurements. Low-frequency noise appears as a constantly-changing signal in series with any measurement being made. As a result, even when the measurement is made rapidly, this constantly-changing noise signal will corrupt the result. The value of this noise signal can be surprisingly large. For example: If a conventional amplifier has a flat-band noise level of  $10\text{nV}/\sqrt{\text{Hz}}$  and a noise corner of 10Hz, the RMS noise at 0.001Hz is  $1\mu\text{V}/\sqrt{\text{Hz}}$ . This is equivalent to a 0.50 $\mu\text{V}$  peak-to-peak error, in the frequency range 0.001 Hz to 1.0 Hz. In a circuit with a gain of 1000, this produces a 0.50mV peak-to-peak output error. This number of 0.001 Hz might appear unreasonably low, but when a data acquisition system is operating for 17 minutes, it has been on long enough to include this error. In this same time, the LMV2011 will only have a 0.21mV output error. This is smaller by 2.4 x. Keep in mind that this 1/f error gets even larger at lower frequencies. At the extreme, many people try to reduce this error by integrating or taking several samples of the same signal. This is also doomed to failure because the 1/f nature of this noise means that taking longer samples just moves the measurement into lower frequencies where the noise level is even higher.

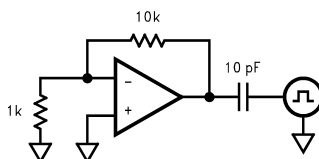
The LMV2011 eliminates this source of error. The noise level is constant with frequency so that reducing the bandwidth reduces the errors caused by noise.

Another source of error that is rarely mentioned is the error voltage caused by the inadvertent thermocouples created when the common "Kovar type" IC package lead materials are soldered to a copper printed circuit board. These steel-based leadframe materials can produce over  $35\mu\text{V}/^\circ\text{C}$  when soldered onto a copper trace. This can result in thermocouple noise that is equal to the LMV2011 noise when there is a temperature difference of only 0.0014 $^\circ\text{C}$  between the lead and the board!

For this reason, the lead-frame of the LMV2011 is made of copper. This results in equal and opposite junctions which cancel this effect. The extremely small size of the SOT-23 package results in the leads being very close together. This further reduces the probability of temperature differences and hence decreases thermal noise.

#### OVERLOAD RECOVERY

The LMV2011 recovers from input overload much faster than most chopper-stabilized opamps. Recovery from driving the amplifier to 2X the full scale output, only requires about 40ms. Many chopper-stabilized amplifiers will take from 250ms to several seconds to recover from this same overload. This is because large capacitors are used to store the unadjusted offset voltage.



**Figure 30. Overload Recovery Test**

The wide bandwidth of the LMV2011 enhances performance when it is used as an amplifier to drive loads that inject transients back into the output. ADCs (Analog-to-Digital Converters) and multiplexers are examples of this type of load. To simulate this type of load, a pulse generator producing a 1V peak square wave was connected to the output through a 10pF capacitor (Figure 30). The typical time for the output to recover to 1% of the applied pulse is 80ns. To recover to 0.1% requires 860ns. This rapid recovery is due to the wide bandwidth of the output stage and large total GBW.

#### NO EXTERNAL CAPACITORS REQUIRED

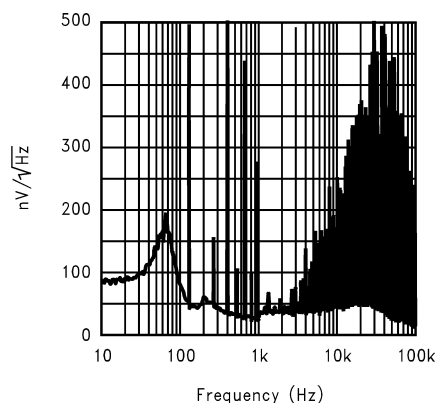
The LMV2011 does not need external capacitors. This eliminates the problems caused by capacitor leakage and dielectric absorption, which can cause delays of several seconds from turn-on until the amplifier's error has settled.

## MORE BENEFITS

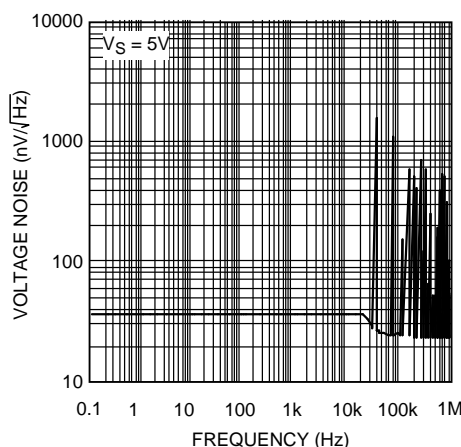
The LMV2011 offers the benefits mentioned above and more. It has a rail-to-rail output and consumes only 950µA of supply current while providing excellent DC and AC electrical performance. In DC performance, the LMC2001 achieves 130dB of CMRR, 120dB of PSRR and 130dB of open loop gain. In AC performance, the LMV2011 provides 3MHz of gain-bandwidth product and 4V/µs of slew rate.

## HOW THE LMV2011 WORKS

The LMV2011 uses new, patented techniques to achieve the high DC accuracy traditionally associated with chopper-stabilized amplifiers without the major drawbacks produced by chopping. The LMV2011 continuously monitors the input offset and corrects this error. The conventional chopping process produces many mixing products, both sums and differences, between the chopping frequency and the incoming signal frequency. This mixing causes large amounts of distortion, particularly when the signal frequency approaches the chopping frequency. Even without an incoming signal, the chopper harmonics mix with each other to produce even more trash. If this sounds unlikely or difficult to understand, look at the plot (Figure 31), of the output of a typical (MAX432) chopper-stabilized opamp. This is the output when there is no incoming signal, just the amplifier in a gain of -10 with the input grounded. The chopper is operating at about 150Hz; the rest is mixing products. Add an input signal and the noise gets much worse. Compare this plot with Figure 32 of the LMV2011. This data was taken under the exact same conditions. The auto-zero action is visible at about 30kHz but note the absence of mixing products at other frequencies. As a result, the LMV2011 has very low distortion of 0.02% and very low mixing products.



**Figure 31. The Output of a Chopper Stabilized Op Amp (MAX432)**



**Figure 32. The Output of the LMV2011**

## LMV2011

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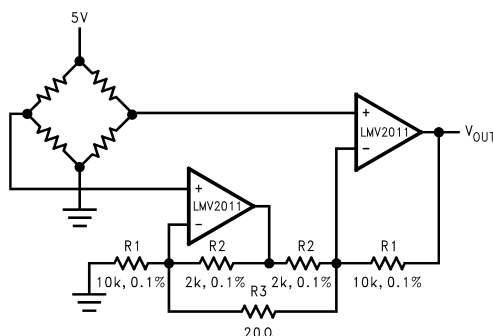
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### INPUT CURRENTS

The LMV2011's input currents are different than standard bipolar or CMOS input currents in that it appears as a current flowing in one input and out the other. Under most operating conditions, these currents are in the picoamp level and will have little or no effect in most circuits. These currents tend to increase slightly when the common-mode voltage is near the minus supply (See the [Typical Performance Characteristics](#)). At high temperatures such as 85°C, the input currents become larger, 0.5nA typical, and are both positive except when the  $V_{CM}$  is near  $V^-$ . If operation is expected at low common-mode voltages and high temperature, do not add resistance in series with the inputs to balance the impedances. Doing this can cause an increase in offset voltage. A small resistance such as 1k $\Omega$  can provide some protection against very large transients or overloads, and will not increase the offset significantly.

### PRECISION STRAIN-GAUGE AMPLIFIER

This Strain-Gauge amplifier ([Figure 32](#)) provides high gain (1006 or ~60 dB) with very low offset and drift. Using the resistors' tolerances as shown, the worst case CMRR will be greater than 108 dB. The CMRR is directly related to the resistor mismatch. The rejection of common-mode error, at the output, is independent of the differential gain, which is set by R3. The CMRR is further improved, if the resistor ratio matching is improved, by specifying tighter-tolerance resistors, or by trimming.



**Figure 33. Precision Strain Gauge Amplifier**

### Extending Supply Voltages and Output Swing by Using a Composite Amplifier Configuration:

In cases where substantially higher output swing is required with higher supply voltages, arrangements like the ones shown in [Figure 34](#) and [Figure 35](#) could be used. These configurations utilize the excellent DC performance of the LMV2011 while at the same time allow the superior voltage and frequency capabilities of the LM6171 to set the dynamic performance of the overall amplifier. For example, it is possible to achieve  $\pm 12V$  output swing with 300MHz of overall GBW ( $A_V = 100$ ) while keeping the worst case output shift due to  $V_{OS}$  less than 4mV. The LMV2011 output voltage is kept at about mid-point of its overall supply voltage, and its input common mode voltage range allows the  $V^-$  terminal to be grounded in one case ([Figure 34](#), inverting operation) and tied to a small non-critical negative bias in another ([Figure 35](#), non-inverting operation). Higher closed-loop gains are also possible with a corresponding reduction in realizable bandwidth. [Table 1](#) shows some other closed loop gain possibilities along with the measured performance in each case.



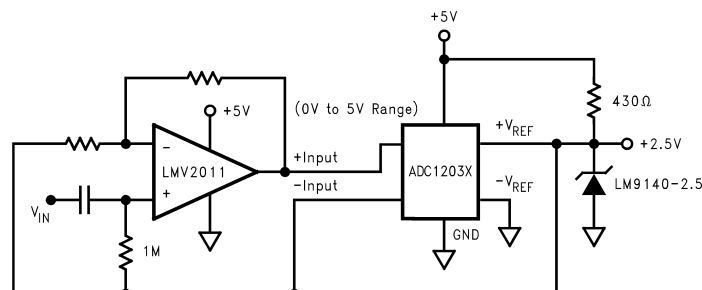
## LMV2011



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In the case of the inverting configuration, it is also possible to increase the input impedance of the overall amplifier, by raising the value of R1, without having to increase the feed-back resistor, R2, to impractical values, by utilizing a "Tee" network as feedback. See the LMC6442 data sheet (Application Notes section) for more details on this.

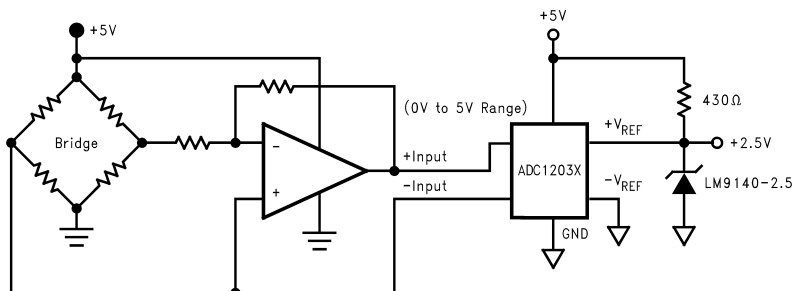


**Figure 36. AC Coupled ADC Driver**

### LMV2011 AS ADC INPUT AMPLIFIER

The LMV2011 is a great choice for an amplifier stage immediately before the input of an ADC (Analog-to-Digital Converter), whether AC or DC coupled. See [Figure 36](#) and [Figure 37](#). This is because of the following important characteristics:

- A)** Very low offset voltage and offset voltage drift over time and temperature allow a high closed-loop gain setting without introducing any short-term or long-term errors. For example, when set to a closed-loop gain of 100 as the analog input amplifier for a 12-bit A/D converter, the overall conversion error over full operation temperature and 30 years life of the part (operating at 50°C) would be less than 5 LSBs.
- B)** Fast large-signal settling time to 0.01% of final value (1.4μs) allows 12 bit accuracy at 100KHz or more sampling rate.
- C)** No flicker (1/f) noise means unsurpassed data accuracy over any measurement period of time, no matter how long. Consider the following opamp performance, based on a typical low-noise, high-performance commercially-available device, for comparison:  
 Opamp flatband noise = 8nV/√Hz  
 1/f corner frequency = 100Hz  
 A<sub>V</sub> = 2000  
 Measurement time = 100 sec  
 Bandwidth = 2Hz  
 This example will result in about 2.2 mV<sub>PP</sub> (1.9 LSB) of output noise contribution due to the opamp alone, compared to about 594μV<sub>PP</sub> (less than 0.5 LSB) when that opamp is replaced with the LMV2011 which has no 1/f contribution. If the measurement time is increased from 100 seconds to 1 hour, the improvement realized by using the LMV2011 would be a factor of about 4.8 times (2.86mV<sub>PP</sub> compared to 596μV when LMV2011 is used) mainly because the LMV2011 accuracy is not compromised by increasing the observation time.
- D)** Copper leadframe construction minimizes any thermocouple effects which would degrade low level/high gain data conversion application accuracy (see [THE BENEFITS OF LMV2011 NO 1/f NOISE](#)).
- E)** Rail-to-Rail output swing maximizes the ADC dynamic range in 5-Volt single-supply converter applications. Below are some typical block diagrams showing the LMV2011 used as an ADC amplifier ([Figure 36](#) and [Figure 37](#)).



**Figure 37. DC Coupled ADC Driver**



## LMV2011



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### REVISION HISTORY

Changes from Revision B (March 2013) to Revision C	Page
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- |  |                    |
|--|--------------------|
| • Changed layout of National Data Sheet to TI format ..... | <a href="#">15</a> |
|--|--------------------|

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LMV2011MA/NOPB	ACTIVE	SOIC	D	8	95	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	0 to 70	LMV20 11MA	<a href="#">Samples</a>
LMV2011MAX	NRND	SOIC	D	8	2500	TBD	Call TI	Call TI	0 to 70	LMV20 11MA	
LMV2011MAX/NOPB	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	0 to 70	LMV20 11MA	<a href="#">Samples</a>
LMV2011MF	NRND	SOT-23	DBV	5		TBD	Call TI	Call TI	0 to 70	A84A	
LMV2011MF/NOPB	ACTIVE	SOT-23	DBV	5	1000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	0 to 70	A84A	<a href="#">Samples</a>
LMV2011MFX/NOPB	ACTIVE	SOT-23	DBV	5	3000	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	0 to 70	A84A	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSELETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



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Datasheet of LMV2011MA/NOPB - IC OPAMP GP 3MHZ RRO 8SOIC

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**PACKAGE OPTION ADDENDUM**

1-Nov-2015

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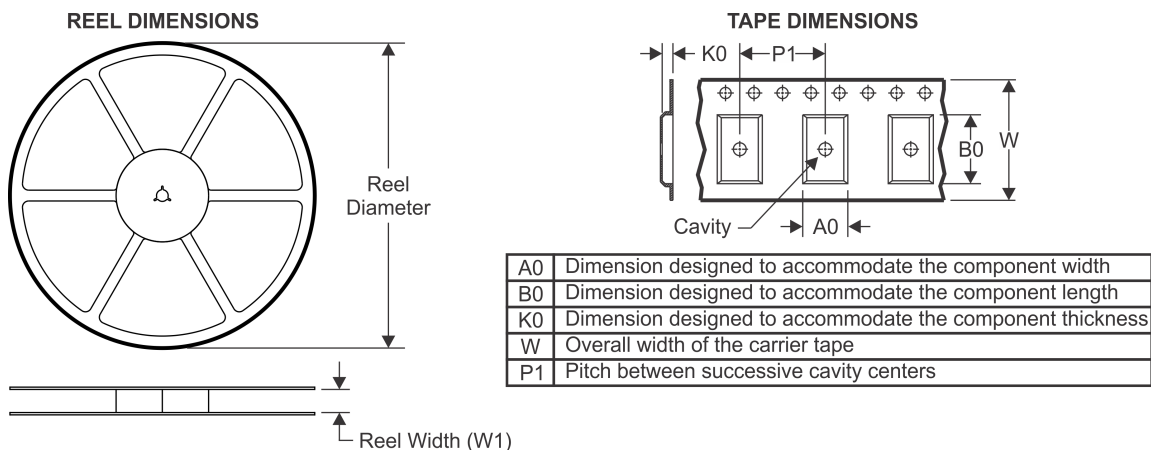
<sup>(6)</sup> Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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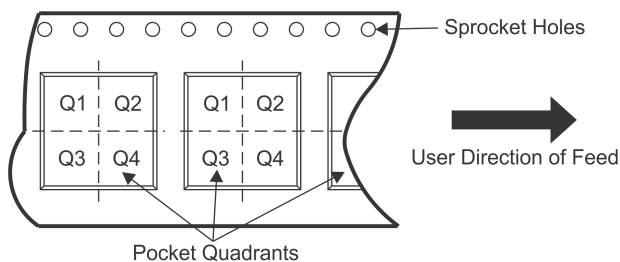
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### TAPE AND REEL INFORMATION



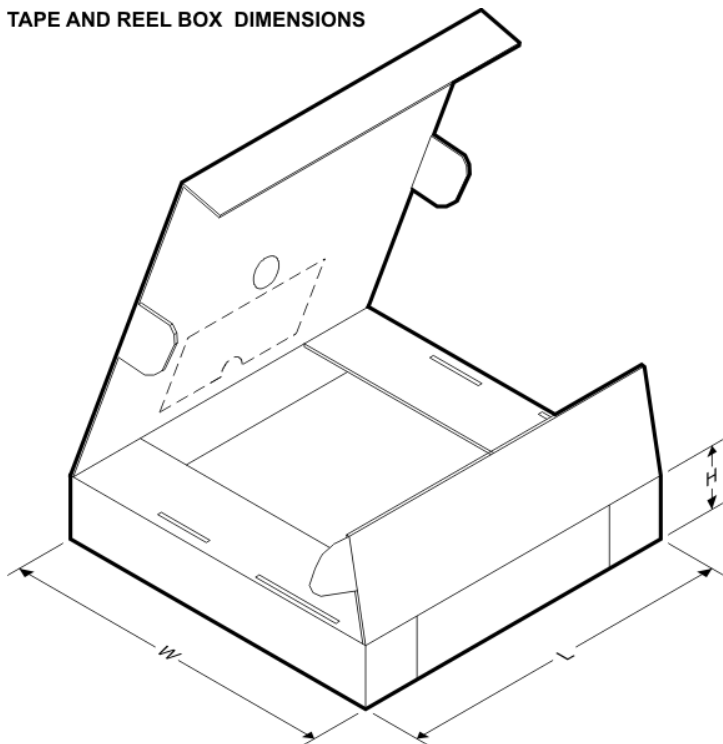
#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMV2011MAX	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMV2011MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1
LMV2011MF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMV2011MFX/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

**TAPE AND REEL BOX DIMENSIONS**



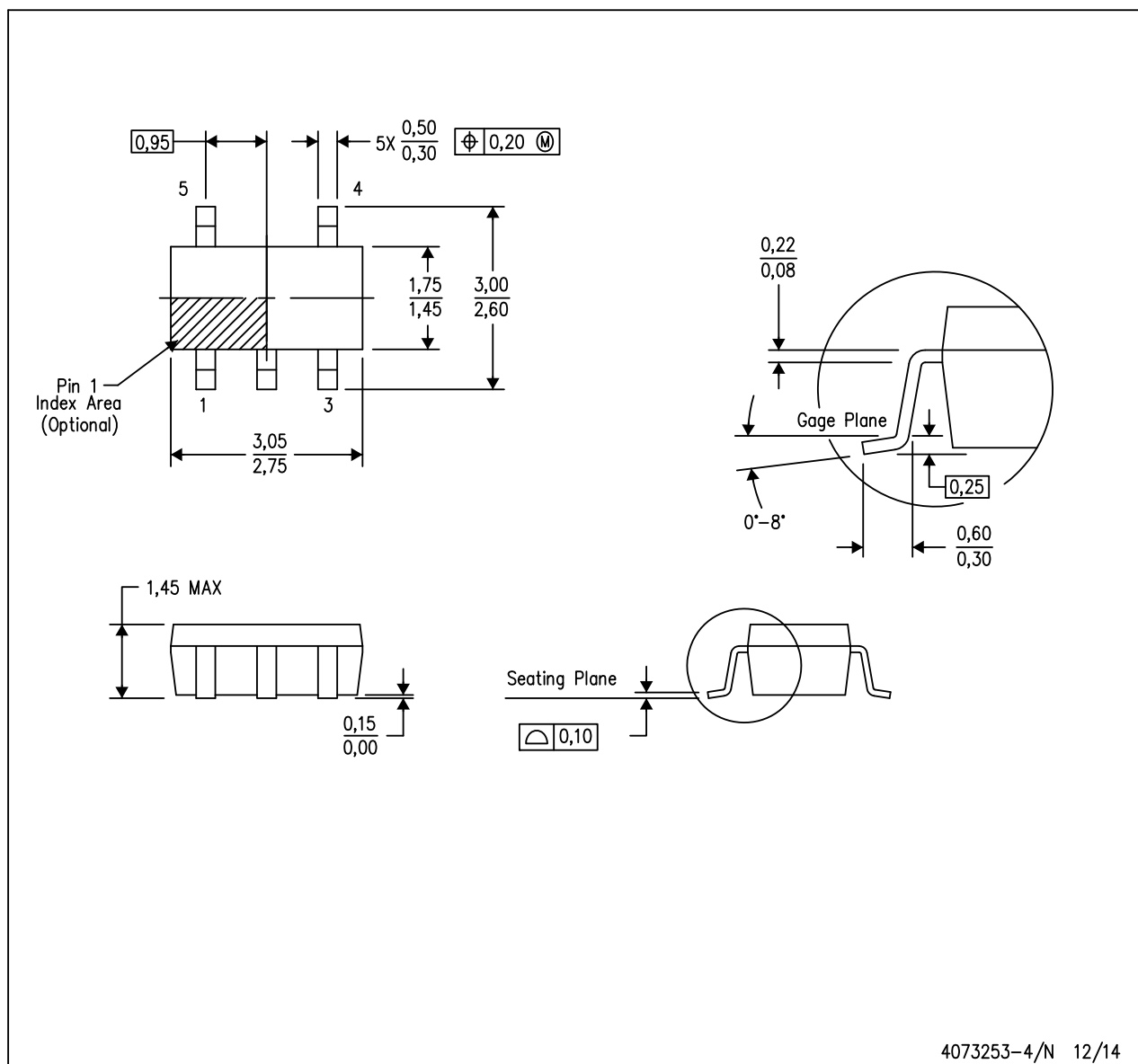
\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMV2011MAX	SOIC	D	8	2500	367.0	367.0	35.0
LMV2011MAX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0
LMV2011MF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
LMV2011MFX/NOPB	SOT-23	DBV	5	3000	210.0	185.0	35.0

## MECHANICAL DATA

DBV (R-PDSO-G5)

PLASTIC SMALL-OUTLINE PACKAGE



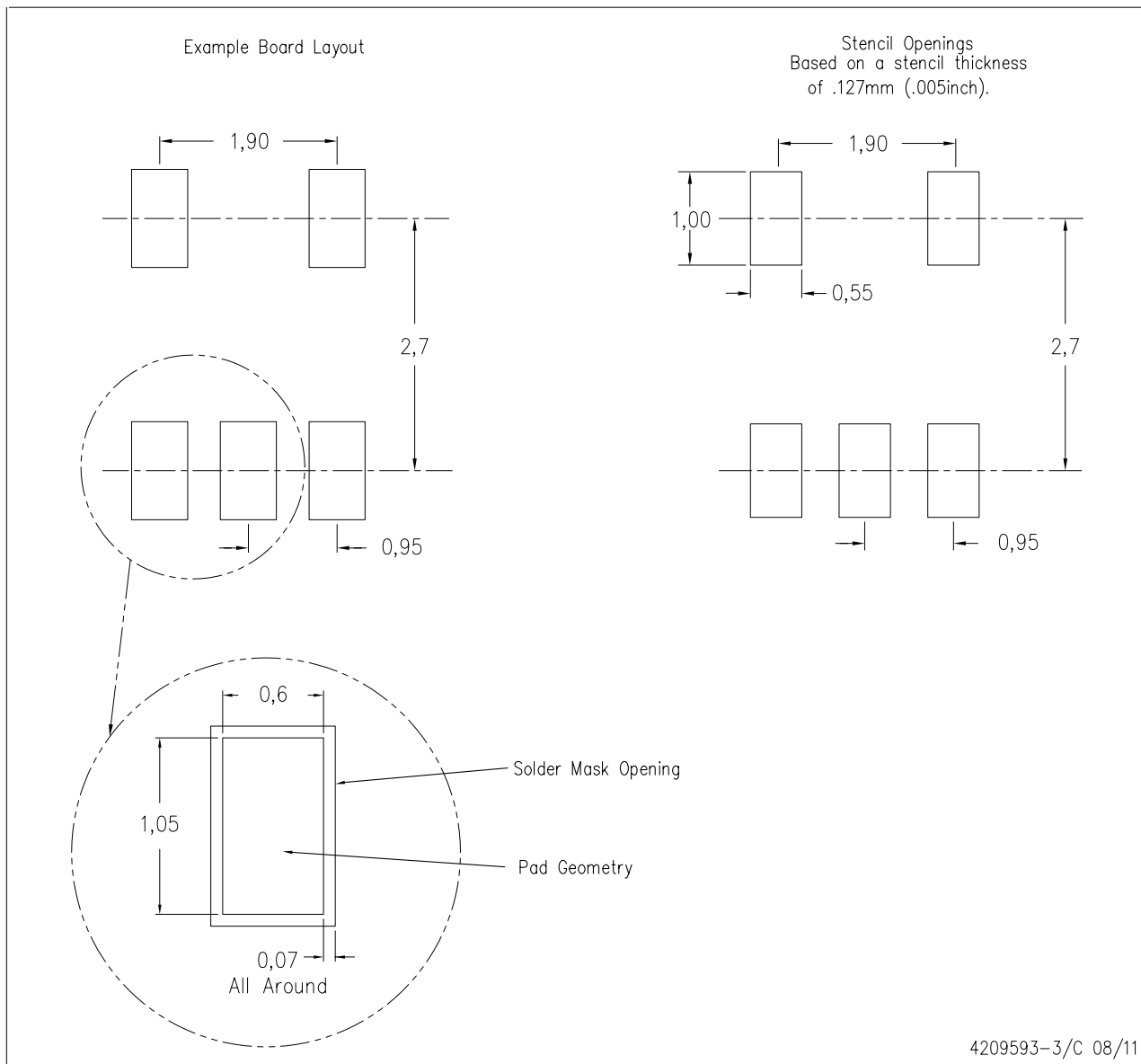
4073253-4/N 12/14

- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
  - Falls within JEDEC MO-178 Variation AA.

## LAND PATTERN DATA

DBV (R-PDSO-G5)

PLASTIC SMALL OUTLINE

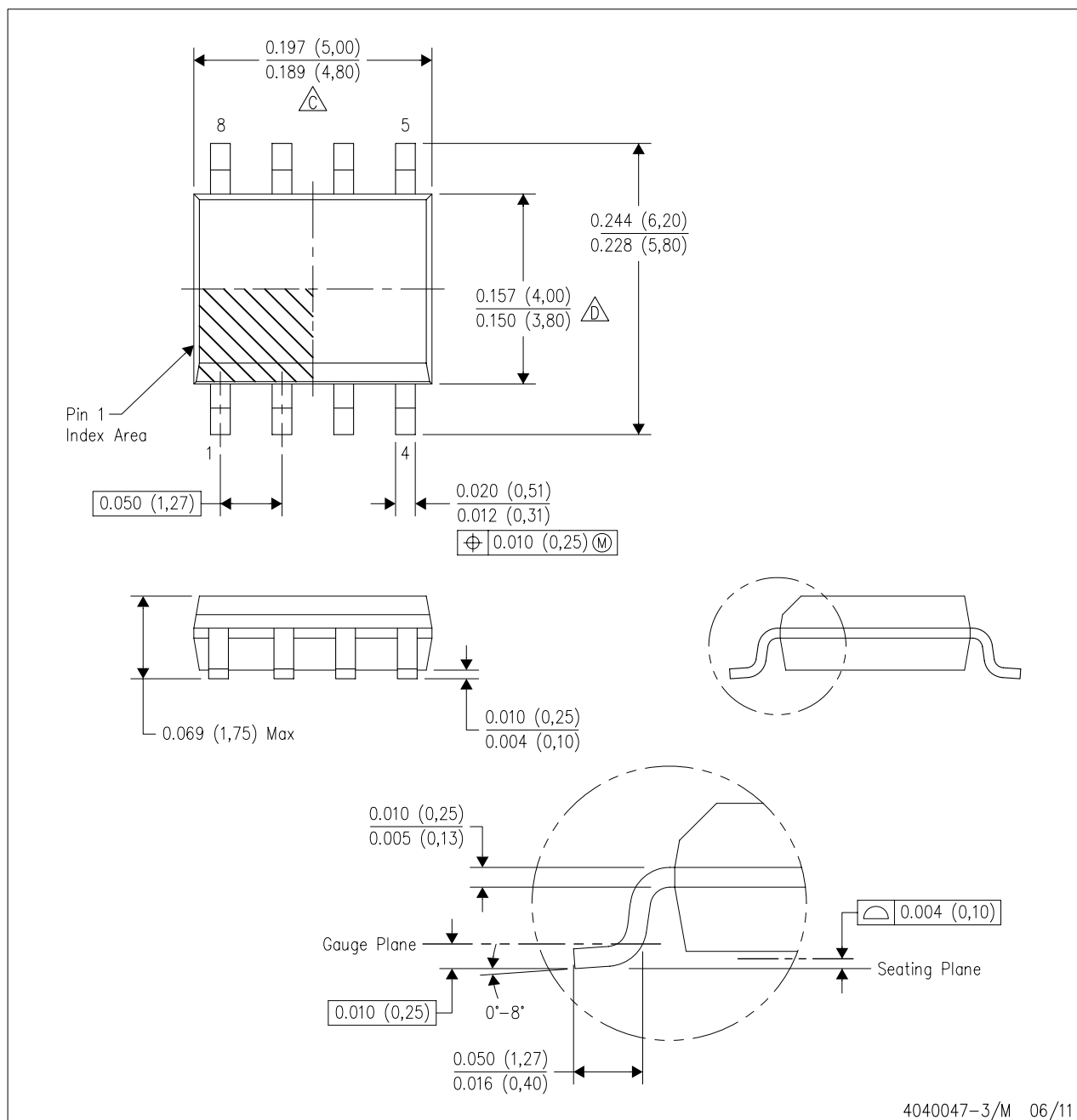


- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
  - D. Publication IPC-7351 is recommended for alternate designs.
  - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

## MECHANICAL DATA

D (R-PDSO-G8)

PLASTIC SMALL OUTLINE



**NOTES:**

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- D. Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.



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